

## Functional Description

Data Input－Data is entered into the FIFO on $D_{0}-D_{3}$ inputs．To enter data the Input Ready（IR）should be HIGH， indicating that the first location is ready to accept data． Data then present at the four data inputs is entered into the first location when the Shift $\ln (\mathrm{SI})$ is brought HIGH．An SI HIGH signal causes the IR to go LOW．Data remains at the first location until SI is brought LOW．When SI is brought LOW and the FIFO is not full，IR will go HIGH，indicating that more room is available．Simultaneously，data will prop－ agate to the second location and continue shifting until it reaches the output stage or a full location．If the memory is full，IR will remain LOW．

Data Transfer－Once data is entered into the second cell， the transfer of any full cell to the adjacent（downstream） empty cell is automatic，activated by an on－chip control． Thus data will stack up at the end of the device while empty locations will＂bubble＂to the front．The tpT parameter
defines the time required for the first data to travel from input to the output of a previously empty device．
Data Output－Data is read from the $\mathrm{O}_{0}-\mathrm{O}_{3}$ outputs． When data is shifted to the output stage，Output Ready （OR）goes HIGH，indicating the presence of valid data． When the OR is HIGH，data may be shifted out by bringing the Shift Out（SO）HIGH．A HIGH signal at SO causes the OR to go LOW．Valid data is maintained while the SO is HIGH．When SO is brought LOW，the upstream data，pro－ vided that stage has valid data，is shifted to the output stage．When new valid data is shifted to the output stage， OR goes HIGH．If the FIFO is emptied，OR stays LOW，and $\mathrm{O}_{0}-\mathrm{O}_{3}$ remains as before，i．e．，data does not change if FIFO is empty．
Input Ready and Output Ready－may also be used as status signals indicating that the FIFO is completely full （Input Ready stays LOW for at least $\mathrm{t}_{\mathrm{PT}}$ ）or completely empty（Output Ready stays LOW for at least $t_{\text {PT }}$ ）．

## Block Diagram



Absolute Maximum Ratings（Note 1）

Storage Temperature
Ambient Temperature under Bias Junction Temperature under Bias $V_{C C}$ Pin Potential to Ground Pin Input Voltage（Note 2）
Input Current（Note 2）
Voltage Applied to Output

| in HIGH State（with $\mathrm{V}_{\mathrm{CC}}=0 \mathrm{~V}$ ） |  |
| :--- | ---: |
| Standard Output | -0.5 V to $\mathrm{V}_{\mathrm{CC}}$ |
| 3－STATE Output | -0.5 V to +5.5 V |

Current Applied to Output
$-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
$-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$
$-55^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$

$$
-0.5 \mathrm{~V} \text { to }+7.0 \mathrm{~V}
$$

$$
-0.5 \mathrm{~V} \text { to }+7.0 \mathrm{~V}
$$

-30 mA to +5.0 mA

$$
-0.5 \mathrm{~V} \text { to } \mathrm{V}_{\mathrm{CC}}
$$

$$
-0.5 \mathrm{~V} \text { to }+5.5 \mathrm{~V}
$$

## Recommended Operating Conditions

| Free Air Ambient Temperature | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ |
| :--- | ---: |
| Supply Voltage | +4.5 V to +5.5 V |

Note 1：Absolute maximum ratings are values beyond which the device may be damaged or have its useful life impaired．Functional operation under these conditions is not implied． Note 2：Either voltage limit or current limit is sufficient to protect inputs．

## DC Electrical Characteristics

| Symbol | Parameter | Min | Typ | Max | Units | $\mathrm{V}_{\mathrm{cc}}$ | Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{IH}}$ | Input HIGH Voltage | 2.0 |  |  | V |  | Recognized as a HIGH Signal |
| $\mathrm{V}_{\mathrm{IL}}$ | Input LOW Voltage |  |  | 0.8 | V |  | Recognized as a LOW Signal |
| $\mathrm{V}_{\mathrm{CD}}$ | Input Clamp Diode Voltage |  |  | －1．5 | V | Min | $\mathrm{I}_{\mathrm{I}}=-18 \mathrm{~mA}$ |
| $\mathrm{V}_{\mathrm{OH}}$ | Output HIGH $10 \% \mathrm{~V}_{\mathrm{CC}}$ <br> Voltage $5 \% \mathrm{~V}_{\mathrm{CC}}$ | $\begin{aligned} & \hline 2.4 \\ & 2.7 \end{aligned}$ |  |  | V | Min | $\begin{aligned} & \mathrm{l}_{\mathrm{OH}}=-1 \mathrm{~mA} \\ & \mathrm{l}_{\mathrm{OH}}=-1 \mathrm{~mA} \end{aligned}$ |
| $\mathrm{V}_{\text {OL }}$ | Output LOW Voltage $10 \% \mathrm{~V}_{\text {CC }}$ |  |  | 0.5 | V | Min | $\mathrm{l}_{\mathrm{OL}}=8 \mathrm{~mA}$ |
| ${ }_{1}{ }_{\text {H }}$ | Input HIGH Current |  |  | 5.0 | $\mu \mathrm{A}$ | Max | $\mathrm{V}_{\text {IN }}=2.7 \mathrm{~V}$ |
| $\mathrm{I}_{\text {BVI }}$ | Input HIGH Current <br> Breakdown Test |  |  | 7.0 | $\mu \mathrm{A}$ | Max | $\mathrm{V}_{\mathrm{IN}}=7.0 \mathrm{~V}$ |
| ${ }_{\text {CEX }}$ | Output HIGH Leakage Current |  |  | 50 | $\mu \mathrm{A}$ | Max | $\mathrm{V}_{\text {OUT }}=\mathrm{V}_{\text {CC }}$ |
| $\mathrm{V}_{\text {ID }}$ | Input Leakage <br> Test | 4.75 |  |  | V | 0.0 | $\mathrm{I}_{\mathrm{ID}}=1.9 \mu \mathrm{~A}$ <br> All Other Pins Grounded |
| $\overline{\mathrm{IOD}}$ | Output Leakage Circuit Current |  |  | 3.75 | $\mu \mathrm{A}$ | 0.0 | $V_{I O D}=150 \mathrm{mV}$ <br> All Other Pins Grounded |
| ILL | Input LOW Current |  |  | －0．4 | mA | Max | $\mathrm{V}_{\text {IN }}=0.5 \mathrm{~V}$ |
| Ios | Output Short－Circuit Current | －20 |  | －130 | mA | Max | $\mathrm{V}_{\text {OUT }}=0 \mathrm{~V}$ |
| ${ }^{\text {CCH }}$ | Power Supply Current |  | 115 | 160 | mA | Max | $\mathrm{V}_{\mathrm{O}}=\mathrm{HIGH}$ |


| Symbol | Parameter | $\begin{gathered} \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C} \\ \mathrm{~V}_{\mathrm{CC}}=+5.0 \mathrm{~V} \\ \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF} \end{gathered}$ |  |  | $\begin{gathered} \mathrm{T}_{\mathrm{A}}=-55^{\circ} \mathrm{C} \text { to }+125^{\circ} \mathrm{C} \\ \mathrm{~V}_{\mathrm{CC}}=+5.0 \mathrm{~V} \\ \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF} \end{gathered}$ |  | $\begin{gathered} \mathrm{T}_{\mathrm{A}}=0^{\circ} \text { to }+70^{\circ} \mathrm{C} \\ \mathrm{~V}_{\mathrm{CC}}=+5.0 \mathrm{~V} \\ \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF} \end{gathered}$ |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min | Typ | Max | Min | Max | Min | Max |  |
| $f_{\text {max }}$ | Shift In Rate | 10 |  |  | 8.0 |  | 10 |  | MHz |
| $f_{\text {max }}$ | Shift Out Rate | 10 |  |  | 8.0 |  | 10 |  | MHz |
| $\mathrm{t}_{\text {PLH }}$ | Propagation Delay | 1.5 |  | 44.0 | 1.5 | 50.0 | 1.5 | 48.0 |  |
| $\mathrm{t}_{\mathrm{PHL}}$ | Shift In to IR | 1.5 |  | 31.0 | 1.5 | 37.0 | 1.5 | 35.0 | ns |
| $\mathrm{t}_{\text {PLH }}$ | Propagation Delay | 1.5 |  | 52.0 | 1.5 | 57.0 | 1.5 | 55.0 |  |
| $\mathrm{t}_{\mathrm{PHL}}$ | Shift Out to OR | 1.5 |  | 31.0 | 1.5 | 37.0 | 1.5 | 35.0 | ns |
| $\mathrm{t}_{\text {PLH }}$ | Propagation Delay | 1.5 |  | 46.0 | 1.5 | 52.0 | 1.5 | 50.0 | ns |
| $\mathrm{t}_{\text {PHL }}$ | Output Data Delay | 1.5 |  | 34.0 | 1.5 | 39.0 | 1.5 | 37.0 | ns |
| ${ }_{\text {tpLH }}$ | Propagation Delay Master Reset to IR | 1.5 |  | 27.0 | 1.5 | 33.0 | 1.5 | 31.0 | ns |
| ${ }_{\text {tpLH }}$ | Propagation Delay Master Reset to OR | 1.5 |  | 30.0 | 1.5 | 34.0 | 1.5 | 32.0 | ns |

## AC Operating Requirements

| Symbol | Parameter | $\begin{aligned} & \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C} \\ & \mathrm{~V}_{\mathrm{CC}}=+5.0 \mathrm{~V} \end{aligned}$ |  | $\begin{gathered} \mathrm{T}_{\mathrm{A}}=-55^{\circ} \mathrm{C} \text { to }+125^{\circ} \mathrm{C} \\ \mathrm{~V}_{\mathrm{CC}}=+5.0 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{T}_{\mathrm{A}}=0^{\circ} \text { to }+70^{\circ} \mathrm{C} \\ \mathrm{~V}_{\mathrm{CC}}=+5.0 \mathrm{~V} \end{gathered}$ |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min | Max | Min | Max | Min | Max |  |
| $\mathrm{t}_{\text {S }}(\mathrm{H})$ | Setup Time, HIGH or LOW | 1.0 |  | 1.0 |  | 1.0 |  | ns |
| $\mathrm{t}_{\text {s }}(\mathrm{L})$ | $\mathrm{D}_{\mathrm{n}}$ to SI | 1.0 |  | 1.0 |  | 1.0 |  |  |
| $\mathrm{t}_{\mathrm{H}}(\mathrm{H})$ | Hold Time, HIGH or LOW | 10.0 |  | 10.0 |  | 10.0 |  |  |
| $\mathrm{t}_{\mathrm{H}}(\mathrm{L})$ | $\mathrm{D}_{\mathrm{n}}$ to SI | 10.0 |  | 10.0 |  | 10.0 |  |  |
| $\mathrm{t}_{W}(\mathrm{H})$ | Shift In Pulse Width | 5.0 |  | 5.0 |  | 5.0 |  | ns |
| $\mathrm{t}_{\text {w }}(\mathrm{L})$ | HIGH or LOW | 10.0 |  | 10.0 |  | 10.0 |  |  |
| ${ }^{\text {tw }}$ (H) | Shift Out Pulse Width | 7.5 |  | 8.5 |  | 7.5 |  |  |
| $\mathrm{t}_{\mathrm{w}}(\mathrm{L})$ | HIGH or LOW | 10.0 |  | 10.0 |  | 10.0 |  |  |
| ${ }_{t_{w}(\mathrm{H})}$ | Input Ready Pulse Width, HIGH | 7.5 |  | 8.5 |  | 7.5 |  | ns |
| ${ }_{\text {t }}(\mathrm{L})$ | Output Ready Pulse Width, LOW | 5.0 |  | 5.0 |  | 5.0 |  | ns |
| ${ }_{t_{W}(\mathrm{~L})}$ | Master Reset Pulse Width, LOW | 10.0 |  | 10.0 |  | 10.0 |  | ns |
| $\overline{t_{\text {REC }}}$ | Recovery Time, MR to SI | 32.0 |  | 35.0 |  | 35.0 |  | ns |
| $\mathrm{t}_{\text {PT }}$ | Data Throughput Time |  | 0.9 |  | 1.0 |  | 1.0 | $\mu \mathrm{s}$ |

Physical Dimensions inches (millimeters) unless otherwise noted


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