Order number: MC100ES6056

Rev 3, 5/2004

# 2.5V / 3.3V ECL/PECL/LVDS Dual Differential 2:1 Multiplexer

The MC100ES6056 is a dual, fully differential 2:1 multiplexer. The differential data path makes the device ideal for multiplexing low skew clock or other skew sensitive signals. Multiple  $V_{BB}$  pins are provided.

The  $V_{BB}$  pin, an internally generated voltage supply, is available to this device only. For single-ended input conditions, the unused differential input is connected to  $V_{BB}$  as a switching reference voltage.  $V_{BB}$  may also rebias AC coupled inputs. When used, decouple  $V_{BB}$  and  $V_{CC}$  via a 0.01  $\mu$ F capacitor and limit current sourcing or sinking to 0.5 mA. When not used,  $V_{BB}$  should be left open.

The device features both individual and common select inputs to address both data path and random logic applications.

The 100ES Series contains temperature compensation.

#### **Features**

- · 360 ps Typical Propagation Delays
- Maximum Frequency > 3 GHz Typical
- PECL Mode Operating Range: V<sub>CC</sub> = 2.375 V to 3.8 V with V<sub>EE</sub> = 0 V
- ECL Mode Operating Range: V<sub>CC</sub> = 0 V with V<sub>FF</sub> = -2.375 V to -3.8 V
- · Open Input Default State
- · Separate and Common Select
- Q Output Will Default LOW with Inputs Open or at V<sub>FF</sub>
- V<sub>BB</sub> Outputs
- · LVDS Input Compatible

## MC100ES6056



**DT SUFFIX** 20 LEAD TSSOP PACKAGE CASE 948E



**DW SUFFIX** 20 LEAD SOIC PACKAGE CASE 751D

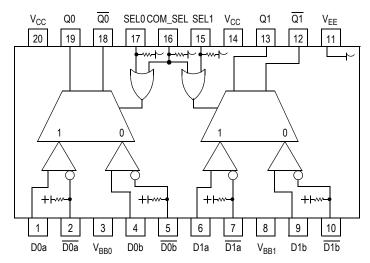
#### **ORDERING INFORMATION**

Device	Package
MC100ES6056DT	TSSOP-20
MC100ES6056DTR2	TSSOP-20
MC100ES6056DW	SO-20
MC100ES6056DWR2	SO-20





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Warning: All  $V_{CC}$  and  $V_{EE}$  pins must be externally connected to Power Supply to guarantee proper operation.

Figure 1. 20-Lead Pinout (Top View) and Logic Diagram

\* Input function will default LOW when left open.

Table 1. Pin Description

Pin	Function
D0a* – D1a*	ECL Input Data a
<u>D0a</u> * − <u>D1a</u> *	ECL Input Data a Invert
D0b* – D1b*	ECL Input Data b
<u>D0b</u> * − <u>D1b</u> *	ECL Input Data b Invert
SEL0* – SEL1*	ECL Indiv. Select Input
COM_SEL*	ECL Common Select Input
$V_{BB0}, V_{BB1}$	Output Reference Voltage
Q0 – Q1	ECL True Outputs
Q0 – Q1	ECL Inverted Outputs
V <sub>CC</sub>	Positive Supply
$V_{EE}$	Negative Supply

Table 2. Function Table

SEL0	SEL1	COM_SEL	Q0, Q0	Q1, Q1
Х	Х	Н	а	а
L	L	L	b	b
L	Н	L	b	а
Н	Н	L	а	а
Н	L	L	а	b

Table 3. General specifications

Charact	Value		
Internal Input Pulldown Resistor		75 kΩ	
Internal Input Pullup Resistor		75 kΩ	
ESD Protection	Human Body Model Machine Model Charged Device Model	> 4 kV > 400 V > 2 kV	
Thermal Resistance (Junction-to-Ambient)	0 LFPM, 20 TSSOP 500 LFPM, 20 TSSOP	140°C/W 100°C/W	
0 LFPM, 20 SOIC 500 LFPM, 20 SOIC		TBD TBD	
Meets or exceeds JEDEC Spec EIA/JESD78 IC Latchup Test			

Table 4. Absolute Maximum Ratings<sup>1</sup>

Symbol	Characteristic	Conditions	Rating	Units
V <sub>SUPPLY</sub>	Power Supply Voltage	Difference between V <sub>CC</sub> & V <sub>EE</sub>	3.9	V
V <sub>IN</sub>	Input Voltage	$V_{CC} - V_{EE} \le 3.6 \text{ V}$	V <sub>CC</sub> + 0.3 V <sub>EE</sub> - 0.3	V
I <sub>OUT</sub>	Output Current	Continuous Surge	50 100	mA mA
I <sub>BB</sub>	V <sub>BB</sub> Sink/Source Current		±0.5	°C
T <sub>A</sub>	Operating Temperature Range		-40 to +85	°C
T <sub>STG</sub>	Storage Temperature Range		-65 to +150	°C

Absolute maximum continuous ratings are those maximum values beyond which damage to the device may occur. Exposure to these conditions
or conditions beyond those indicated may adversely affect device reliability. Functional operation at absolute-maximum-rated conditions is not
implied.

**Table 5. DC Characteristics** ( $V_{CC} = 0 \text{ V}, V_{EE} = -2.5 \text{ V} \pm 5\% \text{ or } 3.8 \text{ V to } -3.135 \text{ V}; V_{CC} = 2.5 \text{ V} \pm 5\% \text{ or } 3.135 \text{ V to } 3.8 \text{ V}, V_{EE} = 0 \text{ V})$ 

		-40°C		0°C to 85°C				
Symbol	Characteristics	Min	Тур	Max	Min	Тур	Max	Unit
I <sub>EE</sub>	Power Supply Current		30	60		30	60	mA
V <sub>OH</sub>	Output HIGH Voltage <sup>1</sup>	V <sub>CC</sub> -1085	V <sub>CC</sub> -960	V <sub>CC</sub> -880	V <sub>CC</sub> -1025	V <sub>CC</sub> -930	V <sub>CC</sub> -860	mV
V <sub>OL</sub>	Output LOW Voltage <sup>1</sup>	V <sub>CC</sub> -1950	V <sub>CC</sub> -1695	V <sub>CC</sub> -1500	V <sub>CC</sub> -1950	V <sub>CC</sub> -1705	V <sub>CC</sub> -1500	mV
V <sub>IH</sub>	Input HIGH Voltage	V <sub>CC</sub> -1165		V <sub>CC</sub> -880	V <sub>CC</sub> -1165		V <sub>CC</sub> -880	mV
V <sub>IL</sub>	Input LOW Voltage	V <sub>CC</sub> -1810		V <sub>CC</sub> -1475	V <sub>CC</sub> -1810		V <sub>CC</sub> -1475	mV
$V_{BB}$	Output Reference Voltage	V <sub>CC</sub> -1380	V <sub>CC</sub> -1290	V <sub>CC</sub> -1220	V <sub>CC</sub> -1380	V <sub>CC</sub> -1290	V <sub>CC</sub> -1200	mV
V <sub>PP</sub>	Differential Input Voltage <sup>2</sup>	0.15		1.3	0.15		1.3	V
V <sub>CMR</sub>	Differential Cross Point Voltage <sup>3</sup>	V <sub>CC</sub> -2.3		V <sub>CC</sub> -0.8	V <sub>CC</sub> –2.3		V <sub>CC</sub> -0.8	V
I <sub>IH</sub>	Input HIGH Current			150			150	μА
I <sub>IL</sub>	Input LOW Current	0.5			0.5			μΑ

- 1. Output termination voltage  $V_{TT}$  = 0V for  $V_{CC}$  = 2.5V operation is supported but the power consumption of the device will increase.
- 2. V<sub>PP</sub> (DC) is the minimum differential input voltage swing required to maintain device functionality.
- 3.  $V_{CMR}$  (DC) is the crosspoint of the differential input signal. Functional operation is obtained when the crosspoint is within the  $V_{CMR}$  (DC) range and the input swing lies within the  $V_{PP}$  (DC) specification.

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#### MC100ES6056

**Table 6. AC Characteristics** ( $V_{CC} = 0 \text{ V}$ ;  $V_{EE} = -2.5 \text{ V} \pm 5\% \text{ or } -3.8 \text{ V}$  to -3.135 V;  $V_{CC} = 2.5 \text{ V} \pm 5\% \text{ or } 3.135 \text{ V}$  to 3.8 V;  $V_{EE} = 0 \text{ V}$ )<sup>1</sup>

			_	40°C to 85°0	3	
Symbol	Characteristics		Min	Тур	Max	Unit
f <sub>max</sub>	Maximum Frequency			> 3		GHz
t <sub>PLH</sub> , t <sub>PHL</sub>	Propagation Delay to Output Differential	D to Q, $\overline{\underline{Q}}$ SEL to Q, $\overline{\underline{Q}}$ COM_SEL to Q, Q	300 300 300	400 430 490	500 600 650	ps ps ps
t <sub>SKEW</sub>	Skew	Output-to-Output <sup>2</sup> Part-to-Part		10	50 200	ps ps
t <sub>JITTER</sub>	Cycle-to-Cycle Jitter	RMS (1σ)			1	ps
V <sub>PP</sub>	Minimum Input Swing		200	800	1200	mV
V <sub>CMR</sub>	Differential Cross Point Voltage		V <sub>CC</sub> -2.1		V <sub>CC</sub> -1.1	V
t <sub>r</sub> / t <sub>f</sub>	Output Rise/Fall Time (20%–80%)		70	120	230	ps

- 1. Measured using a 750 mV source, 50% duty cycle clock source. All loading with 50  $\!\Omega$  to V  $_{CC}\!-\!2.0$  V.
- 2. Skew is measured between outputs under identical transitions. Duty cycle skew is defined only for differential operation when the delays are measured from the cross point of the inputs to the cross point of the outputs.

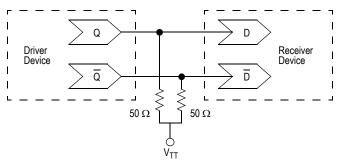


Figure 2. Typical Termination for Output Driver and Device Evaluation

#### **Marking Notes:**

Device Nomenclature	20-Lead TSSOP Marking	20-Lead SOIC W/B Marking
MC100ES6056DT	6056	
MC100ES6056DW		MC100ES6056

#### Trace Code Identification for 20 SOIC: AWLYYWW

- "A" The First character indicates the Assembly location.
- "WL" The Second & Third characters indicate the Source Wafer Lot Tracking Code.
- "YY" The Fourth & Fifth characters indicate the Year device was assembled.
- "WW" The Sixth & Seventh characters indicate the Work Week device was assembled.

#### Trace Code Identification for 20 TSSOP: ALYW

- "A" The First character indicates the Assembly location.
- "L" The Second character indicates the Source Wafer Lot Tracking Code.
- "Y" The Third character indicates the "ALPHA CODE" of the year device was assembled.
- "W" The Fourth character indicates the "ALPHA CODE" of the Work Week device was assembled.

The "Y" Year ALPHA CODES

#### The "W" Work Week ALPHA CODES

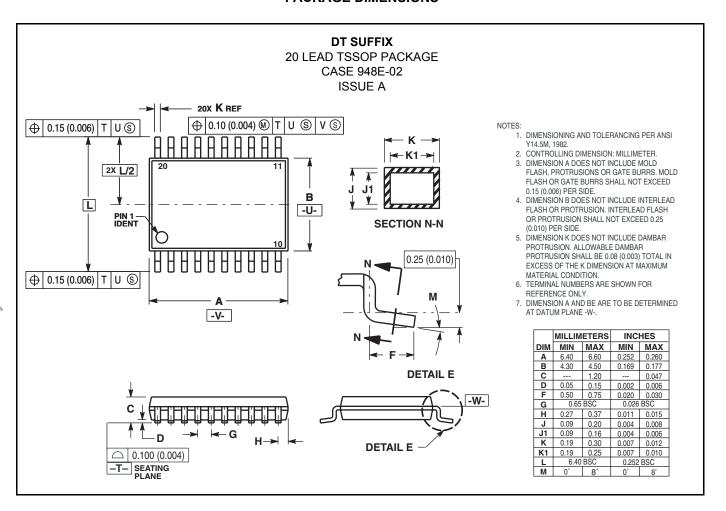
Year	Month	Work Week Code	1st 6 Months
A = 2003	FIRST 6 MONTHS	WW01 – WW26	A =
B = 2003	SECOND 6 MONTHS	WW27 – WW52	B =
C = 2004	FIRST 6 MONTHS	WW01 – WW26	C =
D = 2004	SECOND 6 MONTHS	WW27 – WW52	D =
E = 2005	FIRST 6 MONTHS	WW01 – WW26	E=
F = 2005	SECOND 6 MONTHS	WW27 – WW52	F =
G = 2006	FIRST 6 MONTHS	WW01 – WW26	G =
H = 2006	SECOND 6 MONTHS	WW27 – WW52	H =
I = 2007	FIRST 6 MONTHS	WW01 – WW26	I =
J = 2007	SECOND 6 MONTHS	WW27 – WW52	J =
K = 2008	FIRST 6 MONTHS	WW01 – WW26	K =
L = 2008	SECOND 6 MONTHS	WW27 – WW52	L =
M = 2009	FIRST 6 MONTHS	WW01 – WW26	M =
N = 2009	SECOND 6 MONTHS	WW27 – WW52	N =
O = 2010	FIRST 6 MONTHS	WW01 – WW26	0 =
P = 2010	SECOND 6 MONTHS	WW27 – WW52	P =
Q = 2011	FIRST 6 MONTHS	WW01 – WW26	Q =
R = 2011	SECOND 6 MONTHS	WW27 – WW52	R=
S = 2012	FIRST 6 MONTHS	WW01 – WW26	S =
T = 2012	SECOND 6 MONTHS	WW27 – WW52	T =
U = 2013	FIRST 6 MONTHS	WW01 – WW26	U =
V = 2013	SECOND 6 MONTHS	WW27 – WW52	V =
W = 2014	FIRST 6 MONTHS	WW01 – WW26	W :
X = 2014	SECOND 6 MONTHS	WW27 – WW52	X =
Y = 2015	FIRST 6 MONTHS	WW01 – WW26	Y =
Z = 2015	SECOND 6 MONTHS	WW27 – WW52	Z =

1st 6 Months (WW01 – WW26)	2nd 6 Months (WW27 – WW52)
A = WW01	A = WW27
B = WW02	B = WW28
C = WW03	C = WW29
D = WW04	D = WW30
E = WW05	E = WW31
F = WW06	F = WW32
G = WW07	G = WW33
H = WW08	H = WW34
I = WW09	I = WW35
J = WW10	J = WW36
K = WW11	K = WW37
L = WW12	L = WW38
M = WW13	M = WW39
N = WW14	N = WW40
O = WW15	O = WW41
P = WW16	P = WW42
Q = WW17	Q = WW43
R = WW18	R = WW44
S = WW19	S = WW45
T = WW20	T = WW46
U = WW21	U = WW47
V = WW22	V = WW48
W = WW23	W = WW49
X = WW24	X = WW50
Y = WW25	Y = WW51
Z = WW26	Z = WW52

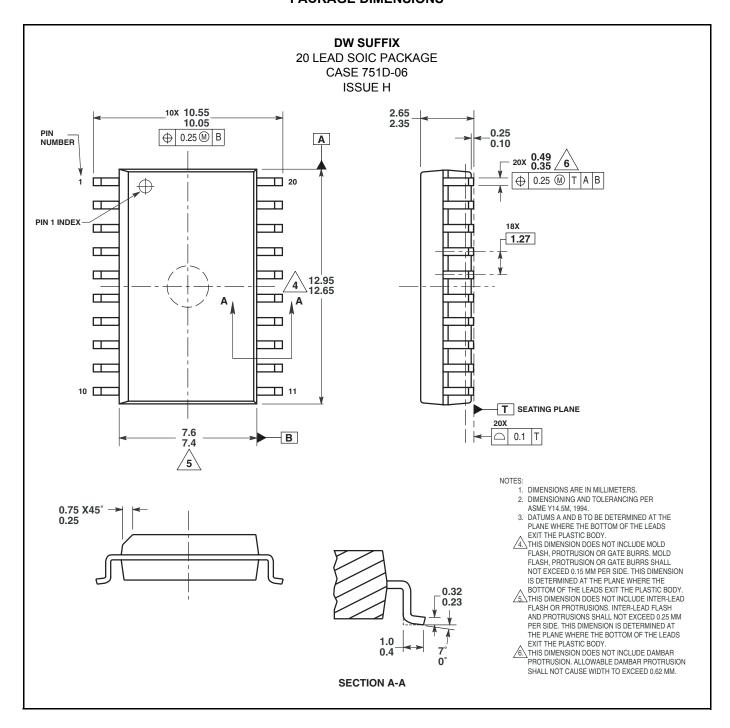
#### 20 TSSOP Tracecode Marking Example:

# 5ABR | | | | | 5 | | | = Assembly Location | | | A | | = First Lot Assembled of this device in the designated Work Week | | B | = 2003 Second 6 Months, WW27 – WW52 | | R = WW44 of 2003

#### PACKAGE DIMENSIONS



#### PACKAGE DIMENSIONS



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