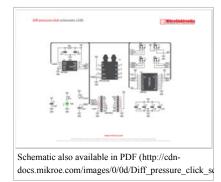
## **Diff pressure click**

From MikroElektonika Documentation

**Diff pressure** is a mikroBUS<sup>™</sup> add-on board carrying an NXP MPXV5010DP signal conditioned, temperature compensated and calibrated pressure sensor with two axial ports to accommodate industrial grade tubing. It is designed for comparing two pressure measurements.

## Features and usage notes



The two ports on Diff pressure click are designated as Pressure side (P1) and Vacuum side (P2). The sensor is designed to operate with a positive differential pressure where P1 > P2.

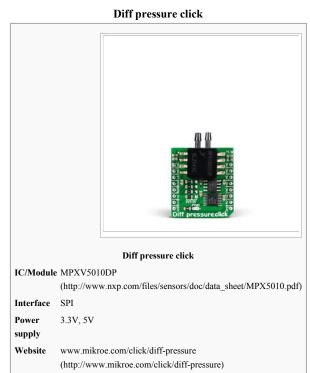
The P1 and P2 ports are not marked on the sensor itself, but according to the vendor's data sheet, P1 is on the side of part markings. In the case of Diff pressure click, that's the top half of the sensor.

The measurement range is from 0 to 10 kPa. In the temperature range between  $0^{\circ}$  and 85°C, the sensor has a maximum error rate of 5.0%.

MPXV5010DP IC has an analog output. The signal passes through the onboard 22-bit ADC before being outputted through the mikroBUS™ SPI interface (CS, SCK, MISO).

Diff pressure click is designed to use either a 3.3V or a 5V power supply. It's 3.3V by default. To change it to 5V, resolder the onboard jumpers (zero Ohm resistors)

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## Programming

The following code snippet initializes SPI, UART and the Diff Pressure click and reads the difference between the two pressures to the UART terminal.

```
void main()
 2 {
         //Local Declarations
int32_t buffer = 0;
char uart_text[20] = { 0 };
float difference = 0;
         status t status;
9
10
         GPIO_Digital_Input( &GPIO_PORT_24_31, _GPIO_PINMASK_6 );
GPIO_Digital_Output( &GPIO_PORT_24_31, _GPIO_PINMASK_4 );
11
12
         UART1_Init( 9600 );
Delay_ms(200);
         UART1_Write_Text( "UART Initialized\r\n" );
Delay_ms(200);
UART1_Write_Text( "SPI Initialized\r\n" );
          //Diff Pressure Click
         UART1_Write_Text( "Diff Pressure Click Initialized\r\n" );
         while (1)
                tatus
                       = diff_pressure_read_adc( &buffer );
                                                                         //Read ADC
              if ( status == OK )
                   //Get Pressure Difference
difference = diff_pressure_get_kpa_difference( buffer );
                   //Write it out
UARI1 Write Text( "KPA Difference: ");
FloatToStr( difference, uart_text);
UARI1_Write_Text( uart_text);
UARI1_Write_Text( "\r\n");
buffer = 0;
             else //Data wash
UART1_Write_Text( "Not Ready\r\n");
```

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Code examples that demonstrate the usage of Diff press click with MikroElektronika hardware, written for mikroC for ARM, AVR, dsPIC, PIC and PIC32 are available on Libstock (http://libstock.mikroe.com/projects/view/1901/diff-pressure-click).

## Resources

- Diff pressure click example on Libstock (http://libstock.mikroe.com/projects/view/1901/diff-pressure-click)
- Vendor's data sheet (http://www.nxp.com/files/sensors/doc/data\_sheet/MPX5010.pdf)
- MCP3551 ADC data sheet (http://ww1.microchip.com/downloads/en/devicedoc/21950b.pdf)

 $-\ mikroBUS^{TM}\ standard\ specifications\ (http://download.mikroe.com/documents/standards/mikrobus/mikrobus-standard-specification-v200.pdf)$