

AC Controller Modules

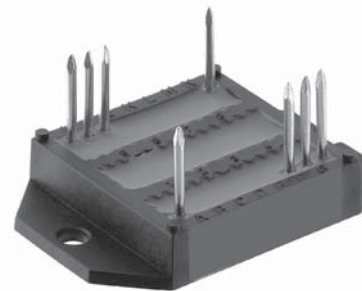
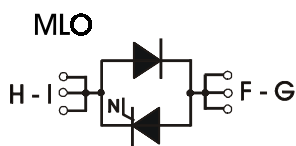
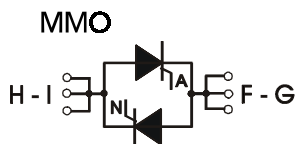
ECO-PAC 2

$$I_{RMS} = 230A$$

$$V_{RRM} = 800 - 1800 V$$

Preliminary Data

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type
900	800	MMO230 -08io7 MLO230 -08io7
1300	1200	MMO230 -12io7 MLO230 -12io7
1500	1400	MMO230 -14io7 MLO230 -14io7
1700	1600	MMO230 -16io7 MLO230 -16io7
1900	1800	MMO230 -18io7 MLO230 -18io7



Symbol	Conditions	Maximum Ratings	
I_{RMS}	$T_C = 85^{\circ}C$; 50-400 Hz (per single controller)	230	A
I_{TRMS}		180	A
I_{TAVM}	$T_C = 85^{\circ}C$; 180° sine	105	A
I_{TSM}	$T_{VJ} = 45^{\circ}C$; $V_R = 0 V$; $t = 10 ms$ (50 Hz), sine	2250	A
	$t = 8.3 ms$ (60 Hz), sine	2400	A
	$T_{VJ} = 125^{\circ}C$; $V_R = 0 V$; $t = 10 ms$ (50 Hz), sine	2000	A
	$t = 8.3 ms$ (60 Hz), sine	2150	A
I^2dt	$T_{VJ} = 45^{\circ}C$; $V_R = 0 V$; $t = 10 ms$ (50 Hz), sine	25300	A ² s
	$t = 8.3 ms$ (60 Hz), sine	23900	A ² s
	$T_{VJ} = 125^{\circ}C$; $V_R = 0 V$; $t = 10 ms$ (50 Hz), sine	20000	A ² s
	$t = 8.3 ms$ (60 Hz), sine	19100	A ² s
$(di/dt)_{cr}$	$T_{VJ} = 125^{\circ}C$; $f = 50 Hz$; $t_p = 200 \mu s$; $V_D = \frac{2}{3} V_{DRM}$; $I_G = 0.45 A$; $di_G/dt = 0.45 A/\mu s$; repetitive, $I_T = 250 A$	150	A/ μs
	non repetitive, $I_T = I_{TAVM}$	500	A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = 125^{\circ}C$; $V_{DR} = \frac{2}{3} V_{DRM}$; $R_{GK} = \infty$, method 1 (linear voltage rise)	1000	V/ μs
P_{GM}	$T_{VJ} = 125^{\circ}C$; $t_p = 30 ms$	≤ 10	W
	$I_T = I_{TAVM}$; $t_p = 300 ms$	≤ 5	W
P_{GAVM}		0.5	W
V_{RGM}		10	V
T_{VJ}		-40 ... + 125	$^{\circ}C$
T_{VJM}		125	$^{\circ}C$
T_{stg}		-40 ... + 125	$^{\circ}C$
V_{ISOL}	50/60 Hz, RMS	$t = 1 min$	3000 V ~
	$I_{ISOL} \leq 1 mA$	$t = 1 s$	3600 V ~
M_d	Mounting torque (M4)	1.5 - 2.0	Nm
		14 - 18	lb.in.
Weight	typ.	26	g

Features

- Thyristor controller for AC (circuit W1C acc. to IEC) for mains frequency
- Isolation voltage 3000 V~
- Planar glass passivated chips
- Low forward voltage drop
- Leads suitable for PC board soldering

Applications

- Switching and control of single and three phase AC circuits
- Light and temperature control
- Softstart AC motor controller
- Solid state switches

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density
- Small and light weight

Data according to IEC 60747 refer to a single thyristor unless otherwise stated
 IXYS reserves the right to change limits, test conditions and dimensions.

Component					
Symbol	Conditions	Characteristic Values			
		min.	typ.	max.	
I_D, I_R	$T_{VJ} = 125^{\circ}\text{C}; V_R = V_{RRM}; V_D = V_{DRM}$			5	mA
V_T	$I_T = 300 \text{ A}; T_{VJ} = 25^{\circ}\text{C}$			1.5	V
V_{TO}	For power-loss calculations only			0.8	V
r_T				2.4	mΩ
V_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = -40^{\circ}\text{C}$			1.5 1.6	V V
I_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = -40^{\circ}\text{C}$			150 200	mA mA
V_{GD}	$T_{VJ} = 125^{\circ}\text{C}; V_D = \frac{2}{3}V_{DRM}$			0.2	V
I_{GD}	$T_{VJ} = 125^{\circ}\text{C}; V_D = \frac{2}{3}V_{DRM}$			10	mA
I_L	$T_{VJ} = 25^{\circ}\text{C}; t_p = 10 \text{ ms}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$			450	mA
I_H	$T_{VJ} = 25^{\circ}\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$			200	mA
t_{gd}	$T_{VJ} = 25^{\circ}\text{C}; V_D = \frac{1}{2}V_{DRM}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$			2	μs
R_{thJC}	per Thyristor; DC per module			0.26 0.13	K/W K/W
R_{thCH}	per Thyristor; DC per module		0,2 0,1		K/W K/W
d_s	Creeping distance on surface			11.2	mm
d_A	Creeping distance in air			5.0	mm
a	Max. allowable acceleration			50	m/s ²

