Data Sheet, Rev. 1.51, Nov. 2005

AN985B/BX

CardBus-to-Ethernet LAN Controller

Communications



Never stop thinking.

Edition 2005-11-30

Published by Infineon Technologies AG, St.-Martin-Strasse 53, 81669 München, Germany © Infineon Technologies AG 2005. All Rights Reserved.

Attention please!

The information herein is given to describe certain components and shall not be considered as a guarantee of characteristics.

Terms of delivery and rights to technical change reserved.

We hereby disclaim any and all warranties, including but not limited to warranties of non-infringement, regarding circuits, descriptions and charts stated herein.

Information

For further information on technology, delivery terms and conditions and prices please contact your nearest Infineon Technologies Office (www.infineon.com).

Warnings

Due to technical requirements components may contain dangerous substances. For information on the types in question please contact your nearest Infineon Technologies Office.

Infineon Technologies Components may only be used in life-support devices or systems with the express written approval of Infineon Technologies, if a failure of such components can reasonably be expected to cause the failure of that life-support device or system, or to affect the safety or effectiveness of that device or system. Life support devices or systems are intended to be implanted in the human body, or to support and/or maintain and sustain and/or protect human life. If they fail, it is reasonable to assume that the health of the user or other persons may be endangered.

CardBus-to-Ethernet LAN Controller

Revision History: 2005-11-30, Rev. 1.51

Previous Version:					
Page/Date	Subjects (major changes since last revision)				
2005-09-13	Rev. 1.51: when changed to the new Infineon format				
2005-11-30	Minor change. Included Green package information				

Trademarks

ABM[®], ACE[®], AOP[®], ARCOFI[®], ASM[®], ASP[®], DigiTape[®], DuSLIC[®], EPIC[®], ELIC[®], FALC[®], GEMINAX[®], IDEC[®], INCA[®], IOM[®], IPAT[®]-2, ISAC[®], ITAC[®], IWE[®], IWORX[®], MUSAC[®], MuSLIC[®], OCTAT[®], OptiPort[®], POTSWIRE[®], QUAT[®], QuadFALC[®], SCOUT[®], SICAT[®], SICOFI[®], SIDEC[®], SLICOFI[®], SMINT[®], SOCRATES[®], VINETIC[®], 10BaseV[®], 10BaseVX[®] are registered trademarks of Infineon Technologies AG. 10BaseS[™], EasyPort[™], VDSLite[™] are trademarks of Infineon Technologies AG. Microsoft[®] is a registered trademark of Microsoft Corporation, Linux[®] of Linus Torvalds, Visio[®] of Visio Corporation, and FrameMaker[®] of Adobe Systems Incorporated.



Table of Contents

Table of Contents

	Table of Contents	4
	List of Figures	6
	List of Tables	7
1	General Description	8
2	System Block Diagram	8
3	Features	8
4	Block Diagram	10
5 5.1	Pin Assignment Diagram	
6	Pin Description	13
7	Functional Descriptions	18
7.1	Network Packet Buffer Management	
7.1.1	Descriptor Structure Types	18
7.1.2	The Point of Descriptor Management	19
7.2	Transmit Scheme and Transmit Early Interrupt	
7.2.1	Transmit Flow	
7.2.2	Transmit Pre-fetch Data Flow	
7.2.3	Transmit Early interrupt Scheme	
7.3	Receive Scheme and Receive Early Interrupt Scheme	
7.4	Network Operation	
7.4.1	MAC Operation	
7.4.2		
7.4.2.1	100BASE-TX Transmit Operation	
7.4.2.2	100BASE-TX Receiving Operation	
7.4.2.3	10BASE-T Transmission Operation	
7.4.2.4	10BASE-T Receive Operation	
7.4.2.5 7.4.2.6	Loop-back Operation of Transceiver	
7.4.2.0		
7.4.2.7	Power Down Operation	
7.4.3	Flow Control in Full Duplex Application	
7.5	LED Display Operation	
7.6	Reset Operation	
7.6.1	Reset Whole Chip	
7.6.2	Reset Transceiver Only	
7.7	Wake on LAN Function	
7.7.1	The Magic Packet Format	31
7.7.2	The Wake on LAN Operation	31
7.8	ACPI Power Management Function	31
7.8.1	Power States	32
8	Registers and Descriptors Description	33
8.1	AN985B/BX Configuration Registers	34
8.1.1	AN985B/BX Configuration Registers Descriptions	
8.2	PCI /CARDBUS Control/Status Registers	
8.2.1	PCI/CARDBUS Control/Status Registers Description	49



Table of Contents

8.3 8.3.1 8.4 8.4.1 8.4.2	PHY Registers PHY Transceiver Registers Descriptions Descriptors and Buffer Management Receive Descriptor Descriptions Transmit Descriptor Descriptions	83 93 94
9 9.1 9.2 9.3 9.4	Electrical Specifications and Timings Absolute Maximum Ratings DC Specifications AC Specifications Timing Specifications	101 101 102
10	Package Outlines	108
11 11.1 11.2 11.3	Appendix MII Management Access Procedure Debugging Purpose Registers: Offset FCH EEPROM DATA TABLE	109 109
	References	111



List of Figures

List of Figures

- Figure 1 System Diagram of the AN985B/BX 8
- Figure 2 Block Diagram of the AN985B/BX 10
- Figure 3 Pin Assignment (top view) 11
- Figure 4 Ring Structure of Frame Buffer 18
- Figure 5 Chain Structure of Frame Buffer 19
- Figure 6 Transmit Pointers for Descriptor Management 20
- Figure 7 Receive Pointers for Descriptor Management 21
- Figure 8 Transmit Flow 22
- Figure 9 Transmit Data Flow of Pre-fetch Data 23
- Figure 10 Transmit Normal Interrupt and Early Interrupt Comparison 23
- Figure 11 Receive Data Flow (without early interrupt and with early interrupt) 24
- Figure 12 Detailed Receive Early Interrupt Flow 24
- Figure 13 MAC Control Frame Format 29
- Figure 14 PAUSE Operation Receive State Diagram 30
- Figure 15 NIC, PHY, and I/O interconnection 91
- Figure 16 Timing 92
- Figure 17 PCI Clock Waveform 103
- Figure 18 PCI Timings 104
- Figure 19 Flash Write Timings 105
- Figure 20 Flash Read Timings 106
- Figure 21 Serial EEPROM Timing 107
- Figure 22 Package Outline for the AN985B/BX 108



List of Tables

List of Tables

- Table 1Abbreviations for Pin Type 12
- Table 2Abbreviations for Buffer Type12
- Table 3Pin Definitions and Functions 13
- Table 4 Format 25
- Table 5Power State 32
- Table 6
 Registers Address Space 34
- Table 7 Registers Overview 34
- Table 8
 Registers Access Conditions Registers Access Conditions 34
- Table 9Registers Access Types 34
- Table 10Registers Clock Domains 35
- Table 11 Registers Address Space 47
- Table 12 Registers Overview 47
- Table 13Registers Access Types48
- Table 14 Registers Address Space 82
- Table 15 Registers Overview 82
- Table 16 Registers Access Types 82
- Table 17 Registers Overview 93
- Table 18Registers Access Types93
- Table 19
 Receive Descriptor Table 94
- Table 20 Transmit Descriptor Table 98
- Table 21 Min-Max Ratings 101
- Table 22 General DC Specifications 101
- Table 23 PCI Interface DC Specifications 101
- Table 24 Flash/EEPROM Interface DC Specifications 101
- Table 25 PCI Signaling AC Specifications for 3.3 V 102
- Table 26PCI Clock Specifications102
- Table 27 PCI Timings 103
- Table 28 Flash Interface Timings 104
- Table 29 EEPROM Interface Timings (AC/AD) 106
- Table 30 Dimensions for 128 -pin LQFP Package (AN985B/BX) 108
- Table 31 EEPROM DATA TABLE 110



2

General Description

1 General Description

System Block Diagram

The AN985B/BX is a high performance CARDBUS Fast Ethernet controller with a integrated physical layer interface for 10BASE-T and 100BASE-TX applications. The AN983B/BX is the environmentally friendly "green" package version.

The AN985B/BX was designed with 0.25um CMOS technology to provide glueless 32-bit bus master interface for CARDBUS, boot ROM interface and CSMA/CD protocol for Fast Ethernet, as well as the physical media interface for 100BASE-TX of IEEE802.3u and 10BASE-T of IEEE802.3. The auto-negotiation function is also supported for speed and duplex detections.

The AN985B/BX provides both half-duplex and full-duplex operations, as well as support for full-duplex flow control.

It provides long FIFO buffers for transmission and reception, and an early interrupt mechanism to enhance performance.

The AN985B/BX also supports ACPI and CARDBUS compliant power management functions and Magic Packet wake-up event.

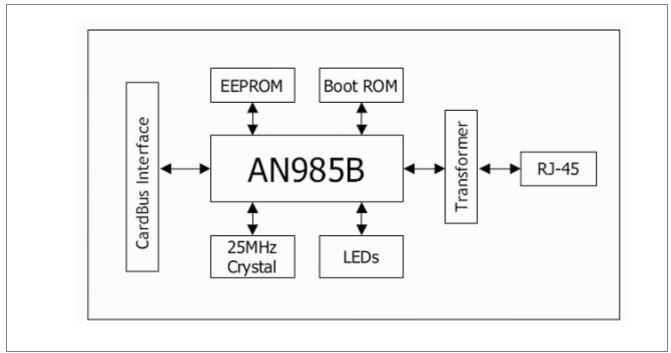


Figure 1 System Diagram of the AN985B/BX

3 Features

Industry standard

- IEEE802.3u 100BASE-TX and IEEE802.3 10BASE-T compliant
- Supports for IEEE802.3x flow control
- IEEE802.3u Auto-Negotiation support for 10BASE-T and 100BASE-TX
- CARDBUS Interface
- ACPI and PCI power management Ver.1.1 compliant



Features

Supports PC98 wake on LAN

FIFO

- · Provides two independent long FIFOs with 2k bytes each for transmission and reception
- Pre-fetch up to two transmit packets to minimize inter frame gap (IFG) to 0.96 μ s
- Retransmit collided packet without reload from host memory within 64 bytes
- Automatically retransmit FIFO under-run packet with maximum drain threshold until 3 times retry failure and that will not influence the registers and transmit threshold of next packet

CARDBUS I/F

- · Provides 32-bit PCI bus master data transfer
- Supports CARDBUS clock with frequency from 0 Hz to 33 MHz
- · Supports network operation with CARDBUS system clock from 20 MHz to 33 MHz
- Performance meter, CARDBUS bus master latency timer, for tuning the threshold to enhance performance
- Burst transmit packet interrupt and transmit/receive early interrupt to reduce host CPU utilization
- Memory-read, memory-read-line, memory-read-multiple, memory-write, memory-write-and-invalidate command while being bus master
- Supports big or little endian byte ordering

EEPROM/Boot ROM I/F

- Write-able Flash ROM and EPROM as boot ROM with size up to 128 KB
- · CARDBUS to access boot ROM by byte, word, or double word
- · Re-write Flash boot ROM through I/O port by programming register
- Serial interface for read/write 93C46/66 EEPROM
- Automatically loads device ID, vendor ID, subsystem ID, subsystem vendor ID, Maximum-Latency, and Minimum-Grand from the 64 byte contents of 93C46/66 after PCI reset de-asserted in PCI environment
- CIS data is recalled from 93C66 to AN985B/BX PC internal SRAM to speed up CIS access in CARDBUS environment

MAC/Physical

- Integrates the whole Physical layer functions of 100BASE-TX and 10BASE-T
- Full -duplex operation on both 100 Mbit/s and 10 Mbit/s modes
- Auto-negotiation (NWAY) function of full/half duplex operation for both 10 and 100 Mbit/s
- Transmits wave-shaper, receive filters, and adaptive equalizer
- MLT-3 transceivers with DC restoration for Base-line wander compensation
- MAC and Transceiver (TXCVR) loop-back modes for diagnostic
- Built in Stream Cipher Scrambler/ De-scrambler and 4B/5B encoder/decoder
- External transmitting transformer with turn ratio 1:1
- External receiving transformer with turn ratio 1:1

LED Display

- 3 LEDs display scheme provided:
 - 100 Mbit/s (on) or Speed 10 (off)
 - Link (keeps on when link ok) or Activity (will be blinking with 10 Hz when receiving or transmitting but not collision)
 - FD (keeps on when in Full duplex mode) or Collision (will be blinking with 20 Hz when colliding)
- 4 LEDs displayed scheme provided:
 - 100 Mbit/s and Link (keep on when link and 100 Mbit/s)
 - 10 Mbit/s and Link (keep on when link and 10 Mbit/s)
 - Activity (will be blinking with 10 Hz when receiving or transmitting but not collision)
 - FD (keeps on when in Full duplex mode) or Collision (will be blinking with 20 Hz when colliding)

Miscellaneous

• 128-pin QFP package for CARDBUS interface.



Block Diagram

4 Block Diagram

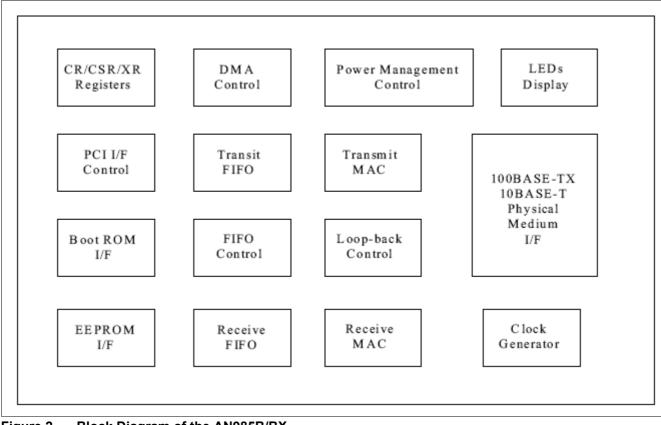


Figure 2 Block Diagram of the AN985B/BX



Pin Assignment Diagram



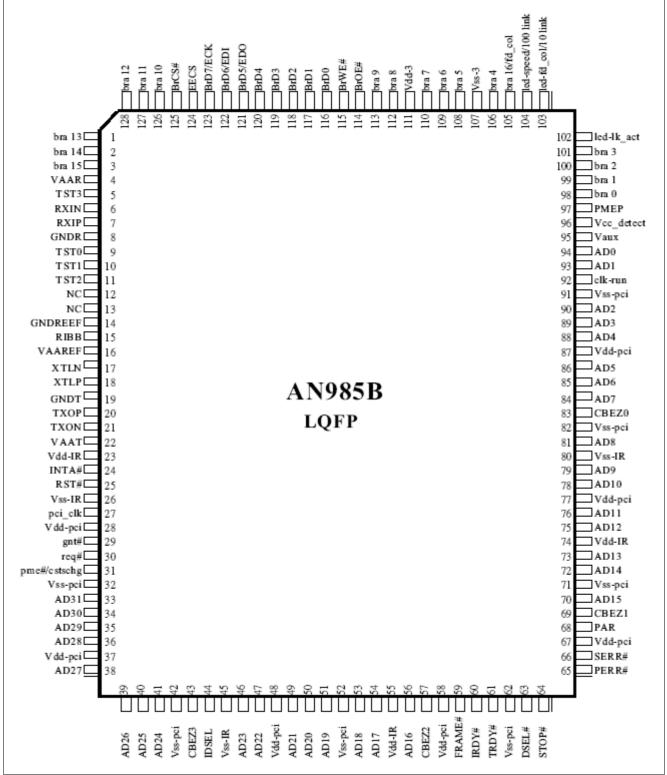


Figure 3 Pin Assignment (top view)



Pin Assignment Diagram

5.1 Pin Type and Buffer Type Abbreviations

Standardized abbreviations:

Table 1Abbreviations for Pin Type

Abbreviations	Description
Ι	Standard input-only pin. Digital levels.
0	Output. Digital levels.
I/O	I/O is a bidirectional input/output signal.
AI	Input. Analog levels.
AO	Output. Analog levels.
AI/O	Input or Output. Analog levels.
PWR	Power
GND	Ground
MCL	Must be connected to Low (JEDEC Standard)
МСН	Must be connected to High (JEDEC Standard)
NU	Not Usable (JEDEC Standard)
NC	Not Connected (JEDEC Standard)

Table 2 Abbreviations for Buffer Type

Abbreviations	Description
Z	High impedance
PU1	Pull up, 10 kΩ
PD1	Pull down, 10 kΩ
PD2	Pull down, 20 kΩ
TS	Tristate capability: The corresponding pin has 3 operational states: Low, high and high- impedance.
OD	Open Drain. The corresponding pin has 2 operational states, active low and tristate, and allows multiple devices to share as a wire-OR. An external pull-up is required to sustain the inactive state until another agent drives it, and must be provided by the central resource.
OC	Open Collector
PP	Push-Pull. The corresponding pin has 2 operational states: Active-low and active-high (identical to output with no type attribute).
OD/PP	Open-Drain or Push-Pull. The corresponding pin can be configured either as an output with the OD attribute or as an output with the PP attribute.
ST	Schmitt-Trigger characteristics
TTL	TTL characteristics



Pin Description

6 Pin Description

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
PCI Interfac	e			
24	INTA#	O/D		CARDBUS Interrupt Request AN985B/BX asserts this signal when one of the interrupt events occurs.
25	RST#	I		CARDBUS Signal to Initialize the AN985B/BX The active reset signal should be sustained for at least 100μ s to guarantee that the AN985B/BX has completed the initializing activity. During the reset period, all the output pins of AN985B/BX will be set to tri-state and all the O/D pins are floated.
27	CLK	1		This CARDBUS Clock Inputs to AN985B/BX for CARDBUS Relative Circuits as the Synchronized Timing Base with CARDBUS The Bus signals are recognized on the rising edge of CARDBUS-CLK. In order to let the network operate properly, the frequency range of the CARDBUS-CLK is limited to between 20 MHz and 33 MHz when the network is operating.
29	GNT#	I		CARDBUS Bus Granted This signal indicates that the bus request of AN985B/BX has been accepted.
30	REQ#	0		CARDBUS Bus Request Bus master device wants to get bus access right
31	PME#/CSTSCH G	I/O		Power Management Event The Power Management Event signal is an open drain, active low signal for CARDBUS(PME#). When WOL-bit 18 of CSR is set into "1", this means that the AN985B/BX is set into Wake On LAN mode. In this mode, when the AN985B/BX receives a Magic Packet frame from network then the AN985B/BX will active this signal too. In the Wake On LAN mode, when LWS-bit (bit 17) of CSR18 is set to "1" this means the LAN-WAKE signal is a HP-style signal, otherwise it is an IBM-style signal.

 Table 3
 Pin Definitions and Functions



Pin Description

Pin or Ball No.	Name	Pin	Buffer	Function
NO. 33	AD-31	Type I/O	Туре	Multiplexed Address Data Pin of CARDBUS Bus
33 34	AD-31 AD-30			
35	AD-30			
36	AD-28			
38	AD-20 AD-27			
<u>39</u>	AD-27 AD-26			
40	AD-20			
41	AD-23			
46	AD-24 AD-23			
47	AD-23			
49	AD-22 AD-21			
-9 50	AD-21 AD-20			
50 51	AD-20 AD-19			
53	AD-19 AD-18			
54	AD-10 AD-17			
56	AD-16			
70	AD-15			
72	AD-14			
73	AD-13			
75 75	AD-12			
76	AD-12			
78	AD-10			
70 79	AD-10 AD-9			
81	AD-9 AD-8			
84	AD-0 AD-7			
85	AD-6			
86	AD-5			
88	AD-3 AD-4			
89	AD-4 AD-3			
90	AD-3 AD-2			
93	AD-2 AD-1			
94	AD-1 AD-0			
43	C-BEB3	I/O		Bus Command and Byte Enable
43 57	C-BEB3			
69	C-BEB2 C-BEB1			
83	C-BEB1			
44	IDSEL			Initialization Device Select
				This signal is asserted when the host issues the configuration cycles to the AN985B/BX.
59	FRAME#	I/O		Begin and Duration of Bus Access Driven by master device

Table 3 Pin Definitions and Functions (cont'd)



Pin Description

Table 3 Pin Definitions and Functions (cont'd)						
Pin or Ball	Name	Pin	Buffer	Function		
No.		Туре	Туре			
60	IRDY#	I/O		Master Device is Ready to Data Transaction		
61	TRDY#	I/O		Slave Device is Ready to Data Transaction		
63	DEVSEL#	I/O		Device Select		
				Device select, target is driving to indicate the address is		
				decoded		
64	STOP#	I/O		Stop the Current Transaction Target device requests the master device to stop the		
				current transaction		
65	PERR#	I/O		Data Parity Error		
00		"0		Data parity error is detected, driven by the agent receiving		
				data		
66	SERR#	O/D		Address Parity Error		
68	PAR	I/O		Parity		
				Parity, even parity (AD [31:0] + C/BE [3:0]); master drives		
				par for address and write data phas; target drives par for		
	0.11			read data phase		
92	Clk-run	I/O, O/D		Clock Run for CARDBUS System In the normal operation situation, Host should assert this		
		0/0		signal to indicate to AN985B/BX about the normal situation.		
				On the other hand, when Host deasserts this signal the		
				clock is going down to a non-operating frequency. When		
				AN985B/BX recognizes the deasserted status of clk-run,		
				then it will assert clk-run to request Host to maintain the		
				normal clock operation. When the clk-run function is disabled then the AN985B/BX will set clk-run in tri-state.		
BOOTBOM	EEPROM Interf					
98	BrA0	1/O		ROM Data Bus		
99 99	BrA1			Provides up to 128kB EPROM or Flash-ROM application		
<u>99</u> 100	BrA2			space.		
100	BrA3					
101	BrA4					
108	BrA5					
100	BrA6					
109	BrA7					
110	BrA8					
112	BrA9					
126	BrA10					
120	BrA10 BrA11					
127	BrA12					
-	BrA12 BrA13					
1	BrA13 BrA14					
2 3	BrA14 BrA15					
105	BrA16					



Pin Description

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
116	BrD0	0	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	BootROM Data Bus Bit (0~7)
117	BrD1			Inputs/Output data for AN985B/BX
118	BrD2			EDO: Data Output of serial EEPROM
119	BrD3			EDI: Data Input of serial EEPROM
120	BrD4			ECK: Clock input of serial EEPROM The AN985B/BX outputs clock signal to EEPROM.
121	BrD5/EDO	O/I	_	
122	BrD6/EDI	0/0		
123	BrD7/ECK	0/0		
124	EECS	0		Chip Select of Serial EEPROM
125	BrCS#	0		BootROM Chip Select
114	BrOE#	0		BootROM Read Enable for Flash ROM Application
115	BrWE#	0		BootROM Write Enable for Flash ROM Application
Physical Int	erface			•••
18	XTLP	I		Crystal Inputs
17	XTLN			To be connected to a 25 MHz crystal.
6	RXIN	1		Differentials Receive Inputs
7	RXIP			The differentials receive inputs of 100BASE-TX or
				10BASE-T, these pins are directly inputted from Magnetic
20	TXOP	0		Differential Transmit Outputs
21	TXON			The differential Transmit outputs of 100BASE-TX or
15	RIBB			10BASE-T, these pins are directly outputted to Magnetic. Reference Bias Resistor
15		1		To be tied to an external 10.0K (1%) resistor which should
				be connected to the analog ground at the other end.
9	TST0	1		Test Pin
10	TST1			
11	TST2			
5	TST3			
12	NC	0		Not Connected
13	NC			
LED Display	and Miscellane	ous	I	
102	Led-Act	0		4 LED Mode: LED Display for Activity Status
				This pin will be driven on with 10 Hz blinking frequency
				when either effective receiving or transmitting is detected.
	(Led-Ink/act)	0		(3 LED Mode): LED Display for Link and Activity Status Link and Activity
103	Led-10Lnk	0		4 LED Mode: LED Display for 10 Mbit/s Speed
				This pin will be driven on continually when the 10 Mbit/s network operating speed is detected.
	(Led-fd/col)	0		(3 LED Mode): LED Display for Full Duplex or Collision
				Status
				full duplex/collision

Table 3 Pin Definitions and Functions (cont'd)



Pin Description

Pin or Ball No.	Name	Pin Type	Buffer Type	Function
104	Led-100Lnk	0		4 LED Mode: LED Display for 100 Mbit/s Speed This pin will be driven on continually when the 100 Mbit/s network operating speed is detected.
	(Led-speed)	0		(3 LED Mode): LED Display for 100 Mbit/s or 10 Mbit/s speed speed 100(on)/10(off)
105	Led-Fd/Col	0		4 LED Mode: LED Display for Full Duplex or Collision Status This pin will be driven on continually when a full duplex configuration is detected. This pin will be driven on with 20 Hz blinking frequency when a collision status is detected in the half duplex configuration.
	bra(16)	0		(3 LED Mode):bra 16
95	Vaux	1		 When this pin is asserted, it indicates an auxiliary power source is supported. ACPI purpose, for detecting the auxiliary power source. This pin should be or-wired connected to: 1) 3.3 V when 3.3 Vaux support, or 2) 5 V when 5 Vaux support from 3-way switch.
96	Vcc-detect	1		 When this pin is asserted, it indicates PCI power source is supported. ACPI purpose, for detecting the main power is remained or not. This pin should be connected to PCI bus power source +5 V.
97	PMEP	0		High pulse/low pulse 50ms
Digital Powe	er Pins			
26, 32, 42, 45, 52, 62, 71, 80, 82, 91, 107	$V_{ m ss-pci}, V_{ m ss-IR}, V_{ m ss-3}$			
23, 28, 37, 48, 55, 58, 67, 74, 77, 87, 111	$V_{\rm dd-pci}, V_{\rm dd-IR}, V_{\rm dd-3}, { m Connect to}$ 3.3 V			
Analog Pow	ver Pins			
4,16,22	$V_{AAR}, V_{AAREF}, V_{AAT}, 3.3 V$			
8,14,19	GNDR, GNDREF, GNDT			

Table 3 Pin Definitions and Functions (cont'd)



7 Functional Descriptions

7.1 Network Packet Buffer Management

7.1.1 Descriptor Structure Types

For networking operations, the AN985B/BX transmits the data packet from transmitting buffers in host memory to AN985B/BX's transmitting FIFO and receives the data packet from AN985B/BX's receiving FIFO to receive buffers in host memory. The descriptors that the AN985B/BX supports to build in host memory are used as the pointers of these transmitting and receiving buffers.

There are two structure types for the descriptor, **Ring and Chain**, supported by the AN985B/BX and are shown as below. The type selections are controlled by bit 24 of RDES1 and the bit 24 of TDES1.

The transmitting and receiving buffers are physically built in host memory. Any buffer can contain either a whole packet or just part of a packet. But it can't contain more than one packet.

Ring structure

There are two buffers per descriptor in the ring structure. Support receives early interrupt.

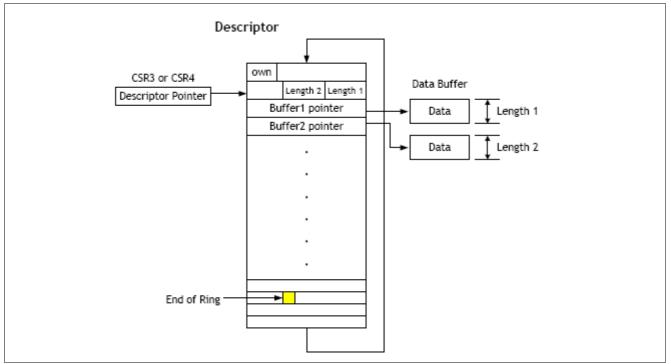


Figure 4 Ring Structure of Frame Buffer

Chain structure

There is only one buffer per descriptor in the chain structure.



Functional Descriptions

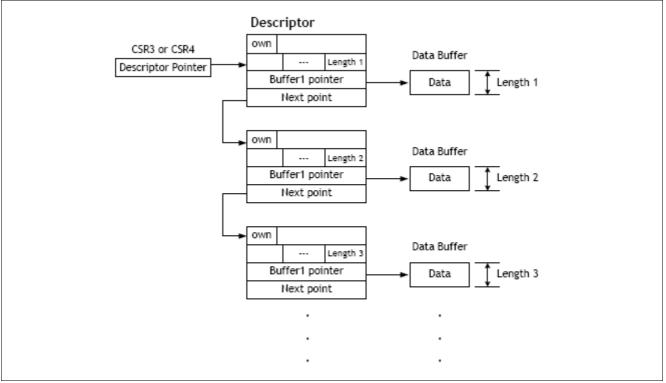


Figure 5 Chain Structure of Frame Buffer

7.1.2 The Point of Descriptor Management

OWN bit = 1, ready for network side access

OWN bit = 0, ready for host side access

• Transmit Descriptor Pointers



Functional Descriptions

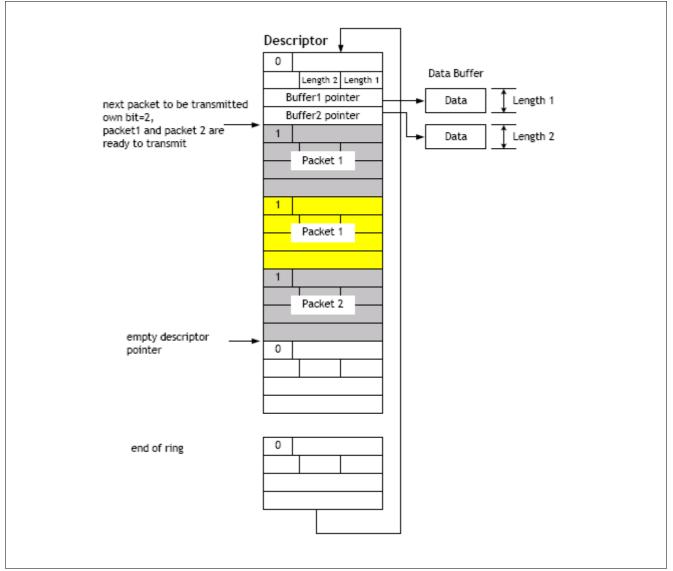


Figure 6 Transmit Pointers for Descriptor Management

Receive Descriptor Pointers



Functional Descriptions

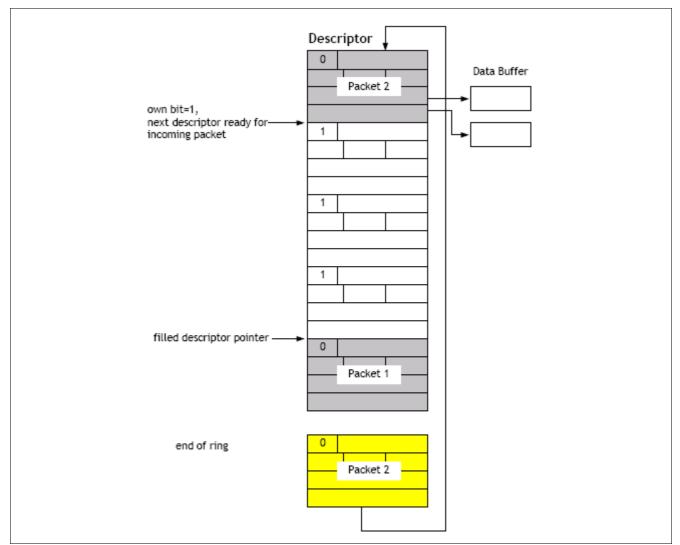


Figure 7 Receive Pointers for Descriptor Management



7.2 Transmit Scheme and Transmit Early Interrupt

7.2.1 Transmit Flow

The flow of packet transmit is shown below.

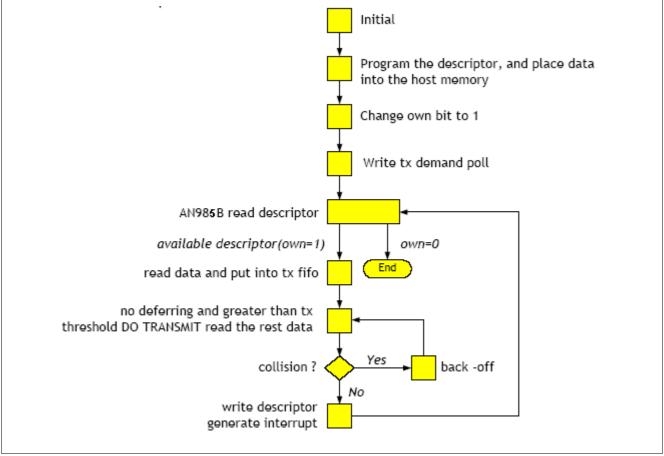


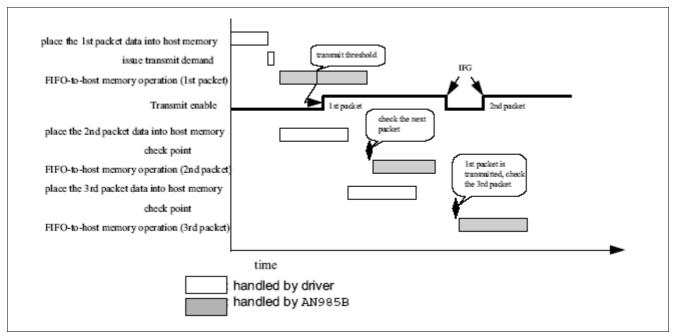
Figure 8 Transmit Flow

7.2.2 Transmit Pre-fetch Data Flow

- Transmit FIFO size = 2K-byte
- Two packets in the FIFO at the same time
- Meet the transmit min. back-to-back



Functional Descriptions





7.2.3 Transmit Early interrupt Scheme

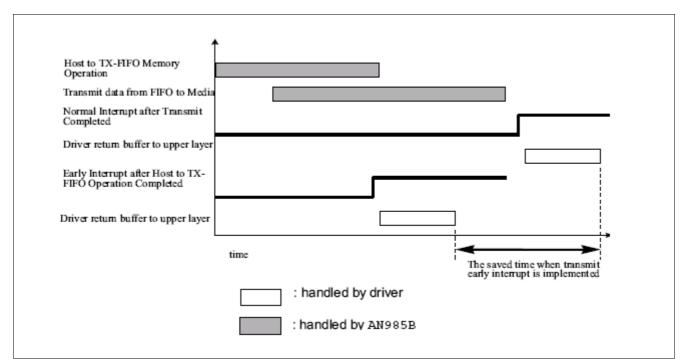


Figure 10 Transmit Normal Interrupt and Early Interrupt Comparison

7.3 Receive Scheme and Receive Early Interrupt Scheme

The following figure shows the difference of timing without early interrupt and with early interrupt.



Functional Descriptions

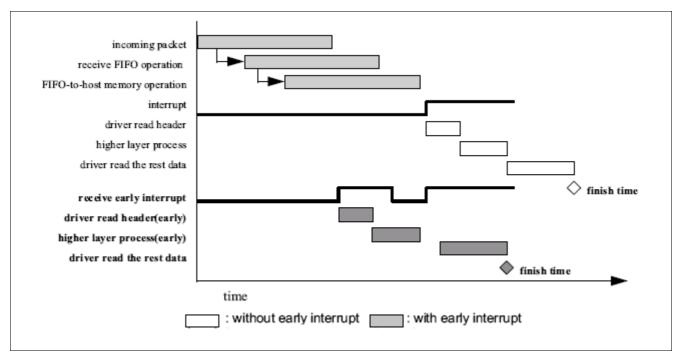
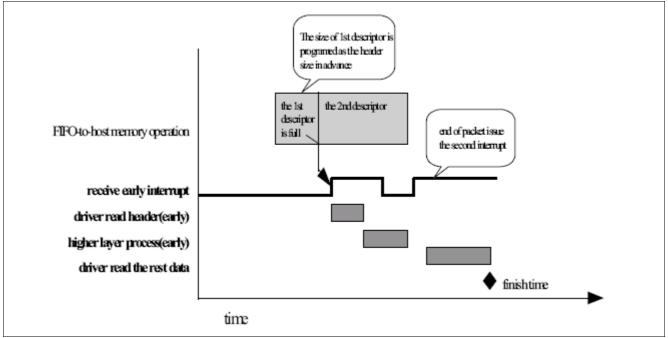
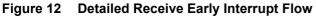


Figure 11 Receive Data Flow (without early interrupt and with early interrupt)





7.4 Network Operation

7.4.1 MAC Operation

The MAC (Media Access Control) portion of AN985B/BX, incorporates the essential protocol requirements for operating as an IEEE802.3 and Ethernet compliant node.



Table 4 Format	
Field	Description
Preamble	A 7-byte field of (10101010b)
Start Frame Delimiter	A 1-byte field of (10101011b)
Destination Address	A 6-byte field
Source Address	A 6-byte field
Length/Type	A 2-byte field indicated the frame is in IEEE802.3 format or Ethernet format.IEEE802.3 format: 0000H ~ 05DCH for Length field Ethernet format: 05DD ~ FFFFH for Type field
Data	46^{1} ~ 1500 bytes of data information
CRC	A 32-bit cyclic redundant code for error detection

1) If padding is disabled (TDES1 bit23), the data field may be shorter than 46 bytes.

Transmit Data Encapsulation

The differences between the encapsulation and a MAC frame while operating in the 100BASE-TX mode are listed as follow:

- 1. The first byte of the preamble is replaced by the JK code according to the IEE802.3u, clause 24.
- After the CRC field of the MAC frame, the AN985B/BX inserts the TR code according to the IEE802.3u, clause 24.

Receive Data Decapsulation

When operating in 100BASE-TX mode the AN985B/BX detects a JK code for a preamble as well as a TR code for the packet end. If a JK code is not detected, the AN985B/BX will abort this frame receiving and wait for a new JK code detection. If a TR code is not detected, the AN985B/BX will report a CRC error.

Deferring

The Inter-Frame Gap (IFG) time is divided into two parts:

- 1. IFG1 time (64-bit time): If a carrier is detected on the medium during this time, the AN985B/BX will reset the IFG1 time counter and restart to monitor the channel for an idle again.
- 2. IFG2 time (32-bit time): After counting the IFG2 time the AN985B/BX will access the channel even though a carrier has been sensed on the network.

Collision Handling

The scheduling of re-transmissions is determined by a controlled randomization process called "truncated binary exponential back-off". At the end of enforcing a collision (jamming), the AN985B/BX delays before attempting to re-transmit the packet. The delay is an integer multiple of slot time. The number of slot times to delay before the nth re-transmission attempt is chosen as a uniform distributed integer r in the range:

 $0 \le r < 2^k$, where k = min (n, 10)



7.4.2 Transceiver Operation

The transceiver portion of the AN985B/BX, integrates the IEEE802.3u compliant functions of PCS (physical coding sub-layer), PMA (physical medium attachment) sub-layer, PMD (physical medium dependent) sub-layer for 100BASE-TX, the IEEE802.3 compliant functions of Manchester encoding/decoding and a transceiver for 10BASE-T. All the functions and operation schemes are described in the following sections:

7.4.2.1 100BASE-TX Transmit Operation

Regarding the 100BASE-TX transmission, the transceiver provides transmission functions PCS, PMA, and PMD for encoding of MII data nibbles to five-bit code-groups (4B/5B), scrambling, serialization of scrambled code-groups, converting the serial NRZ code into NRZI code, converting the NRZI code into MLT3 code, and then driving the MLT3 code into the category 5 Unshielded Twisted Pair cable through an isolation transformer with the turns ratio of 1:1.

Data Code-Groups Encoder

In normal MII mode application, the transceiver receives nibble type 4B data via the TxD0~3 inputs of the MII. These inputs are sampled by the transceiver on the rising edge of Tx-clk and passed to the 4B/5B encoder to generate the 5B code-group used by 100BASE-TX.

Idle Code-Groups

In order to establish and maintain the clock synchronization, the transceiver needs to keep transmitting signals to medium. The transceiver will generate Idle code-groups for transmission when there is no real data MAC wants to send.

Start-of-Stream Delimiter-SSD (/J/K/)

In a transmission stream, the first 16 nibbles are MAC preamble. In order to let a partner delineate the boundary of a data transmission sequence and to authenticate carrier events, the transceiver will replace the first 2 nibbles of the MAC preamble with /J/K/ code-groups.

End-of-Stream Delimiter-ESD (/T/R/)

In order to indicate the termination of the normal data transmissions, the transceiver will insert 2 nibbles of /T/R/ code-group after the last nibble of FCS.

Scrambling

All the encoded data (including the idle, SSD, and ESD code-groups) is passed to data scrambler to reduce the EMI and spread the power spectrum using a 10-bit scrambler seed loaded at the beginning.

Data Conversion of Parallel to Serial, NRZ to NRZI, NRZI to MLT3

After being scrambled, the transmission data with 5B type in 25 MHz will be converted to a serial bit stream in 125 MHz by the parallel to serial function. After serialization, the transmission serial bit stream will be further converted from NRZ to NRZI format. After NRZI is converted, the NRZI bit stream is passed through MLT3 encoder to generate the TP-PMD specified MLT3 code. With this MLT3 code, it lowers the frequency and reduces the energy of the transmission signal in the UTP cable and also makes the system easy to meet the FCC specification of EMI.

Wave-Shaper and Media Signal Driver

In order to reduce the energy of the harmonic frequency of transmission signals, the transceiver provides the wave-shaper prior to the line driver to smoothen but keep symmetric the rising/falling edge of transmission signals. The wave-shaped signals including the 100BASE-TX and 10BASE-T both are passed to the same media signal driver. This design can simplify the external magnetic connection with a single one.



7.4.2.2 100BASE-TX Receiving Operation

Regarding the 100BASE-TX receiving operation, the transceiver provides the receiving functions of PMD, PMA, and PCS for receiving incoming data signals through category 5 UTP cable and an isolation transformer with turn's ratio of 1:1. It includes the adaptive equalizer, baseline wander, data conversions of MLT3 to NRZI, NRZI to NRZ, and serial to parallel, the PLL for clock and data recovery, the de-scrambler, and the decoder of 5B/4B.

Adaptive Equalizer and Baseline Wander

The high-speed signals over the unshielded (or shielded) twisted Pair cable will induce the amplitude attenuation and phase shifting. Furthermore, these effects are dependent on the signal frequency, cable type, cable length and the connectors of the cabling. So a reliable adaptive equalizer and baseline wander to compensate all the amplitude attenuation and phase shifting are necessary. In the transceiver, it provides the robust circuits to perform these functions.

MLT3 to NRZI Decoder and PLL for Data Recovery

After receiving the proper MLT3 signals, the transceiver converts the MLT3 to NRZI code for further processing. After adaptive equalizer, baseline wander, and MLT3 to NRZI decoder, the compensated signals with NRZI type in 125 MHz are passed to the Phase Lock Loop circuits to extract out the original data and the synchronous clock.

Data Conversions of NRZI to NRZ and Serial to Parallel

After data recovery, the signals will be passed to the NRZI to NRZ converter to generate the 125 MHz serial bit stream. This serial bit stream will be packed to parallel 5B type for further processing.

De-scrambling and Decoding of 5B/4B

The parallel 5B type data is passed to the de-scrambler and 5B/4B decoder to return their original MII nibble type data.

Carrier Sensing

Carrier Sense (CRS) signal is asserted when the transceiver detects any 2 non-contiguous zeros within any 10bit boundary of the receiving bit stream. CRS is de-asserted when ESD code-group or Idle code-group is detected. In half duplex mode, CRS is asserted during packet transmission or reception. But in full duplex mode, CRS is asserted only during packet reception.

7.4.2.3 10BASE-T Transmission Operation

It includes the parallel to serial converter, Manchester Encoder, Link test function, Jabber function, the transmit wave-shaper, and line driver described in the section of "Wave-Shaper and Media Signal Driver" of "100BASE-T Transmission Operation". It also provides Collision detection and SQE test for half duplex application.

7.4.2.4 10BASE-T Receive Operation

It includes the carrier sense function, receiving filter, PLL for clock and data recovering, Manchester decoder, and serial to parallel converter.

7.4.2.5 Loop-back Operation of Transceiver

The transceiver provides internal loop-back (also called transceiver loop-back) operation for both the 100BASE-TX and 10BASE-T operations. Setting bit 14 of PHY register 0 to 1 can enable the loop-back operation. In this loop-back operation, PHY will not transmit packets (but PHY will still send MLT3 for Idle).

In the 100BASE-TX internal loop-back operation, the data comes from the transmit output of NRZ to NRZI converter then loops-back to the receiving path into the input of NRZI to NRZ converter.



In the 10BASE-T loop-back operation, the data is through transmitting path and loop-back from the output of the Manchester encoder into the input of Phase Lock Loop circuit of receiving path.

7.4.2.6 Full Duplex and Half Duplex Operation of Transceiver

The transceiver can operate for either full duplex or half duplex network application. In full duplex, both transmission and reception can be operated simultaneously. Under full duplex mode, collision (COL) signal is ignored and carrier sense (CRS) signal is asserted only when the transceiver is receiving.

In half duplex mode, either transmission or reception can be operated at one time. Under half duplex mode, collision signal is asserted when transmitted and received signals collided and carrier sense asserted during transmission and reception.

7.4.2.7 Auto-Negotiation Operation

The Auto-Negotiation function is designed to provide the means to exchange information between the transceiver and the network partner to automatically configure both to take maximum advantage of their abilities, and both are setup accordingly. The Auto-Negotiation function can be controlled through bit 12 of PHY register 0.

The Auto-Negotiation exchanges information with the network partner using the Fast Link Pulses (FLPs) - a burst of link pulses. There are 16 bits of signaling information contained in the burst pulses to advertise all remote partners' capabilities, which are determined by PHY, register 4. According to this information they find out their highest common capability by following the priority sequence as below:

- 1. 100BASE-TX full duplex
- 2. 100BASE-TX half duplex
- 3. 10BASE-T full duplex
- 4. 10BASE-T half duplex

During power-up or reset, if Auto-Negotiation is found enabled, FLPs will be transmitted and the Auto-Negotiation function will process. Otherwise, the Auto-Negotiation will not occur until the bit 12 of PHY register 0 is set to 1. When the Auto-Negotiation is disabled, the Network Speed and Duplex Mode are selected by programming PHY register 0.

7.4.2.8 Power Down Operation

To reduce the power consumption the transceiver is designed with power down feature, which can save the power consumption significantly. Since the power supply of the 100BASE-TX and 10BASE-T circuits are separated, the transceiver can turn off the circuit of either the 100BASE-TX or 10BASE-T when the other is operating.

7.4.3 Flow Control in Full Duplex Application

The PAUSE function operation is used to inhibit transmission of data frames for a specified period of time. The AN985B/BX supports full duplex protocol of IEEE802.3x. To support the PAUSE function, the AN985B/BX implements the MAC Control Sub-layer functions to decode the MAC Control frames received from MAC control clients and execute the relative requests accordingly. When the Full Duplex mode and PAUSE functions are selected after Auto-Negotiation is completed, the AN985B/BX enables the PAUSE function for flow control of full duplex applications. In this section we will describe how the AN985B/BX implements the PAUSE function.



MAC Control Frame and PAUSE Frame

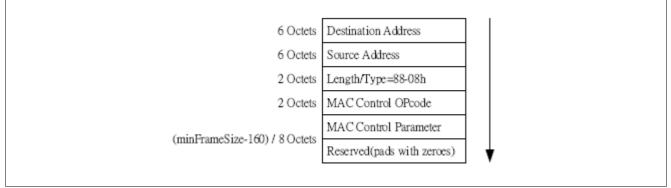


Figure 13 MAC Control Frame Format

The MAC Control frame is distinguished from other MAC frames only by their Length/Type field identifier. The MAC Control Opcode defined in MAC Control Frame format for PAUSE function is 0001_{H} . Also, the PAUSE time is specified in the MAC Control Parameters field with 2 Octets, unsigned integer, in the units of Slot-Times. The range of possible PAUSE time is 0 to 65535 Slot-Times.

So, a valid PAUSE frame issued by a MAC control client (could be a switch or a bridge) which will contain:

- 1. The destination address set equal to the globally assigned 48 bit mulitcast address 01-80-C2-00-00-01, or equal to the unicast address which the MAC control client wishes to inhibit its transmission of data frames
- 2. Filled MAC Control Opcode field with 0001_H
- 3. 2 Octets of PAUSE time specified in the MAC Control parameter field to indicate the length of time for which the destination is wished to inhibit data frame transmission

Receive Operation for PAUSE Function

Upon reception of a valid MAC Control frame, the AN985B/BX will start a timer for the length of time specified by the MAC Control Parameters field. When the timer value reaches zero then the AN985B/BX ends PAUSE state. However, a PAUSE frame should not affect the transmission of a frame that has been submitted to the MAC (started Transmit out of the MAC and can't be interrupted). On the other hand, the AN985B/BX shall not begin to transmit a frame more than one Slot-Times after receiving a valid PAUSE frame with a non-zero PAUSE time. If the AN985B/BX receives a PAUSE frame with a zero PAUSE time value, the AN985B/BX ends the PAUSE state immediately.



Functional Descriptions

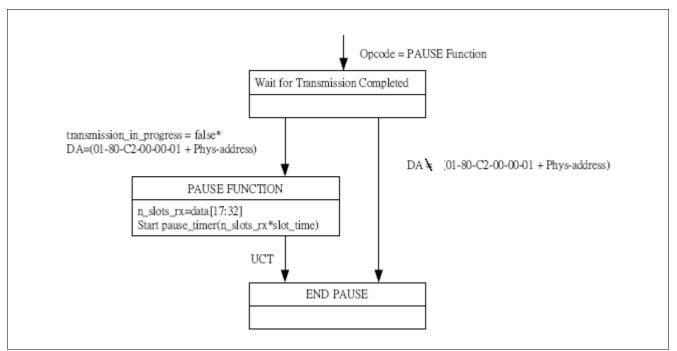


Figure 14 PAUSE Operation Receive State Diagram



7.5 LED Display Operation

The AN985B/BX provides two LED schemes one is three-LED which provides display pins for Link test status/Activity status, Speed mode, and Full duplex/Collision status. These pins can directly drive the LED device; the other is four-LED schemes which provide link100, link10, act, fd/col. The detail descriptions about the operation are described in the Pin Description section.

7.6 Reset Operation

7.6.1 Reset Whole Chip

There are two ways to reset the AN985B/BX. First, hardware reset, the AN985B/BX can be reset via RST# pin. For ensuring proper reset operation, at least 100us active Reset input signal is required. Second, software reset, when bit 0 of CSR0 register is set to 1, the AN985B/BX will reset entire circuits and registers to default values then clear the bit 0 of CSR0 to 0.

7.6.2 Reset Transceiver Only

When bit 15 of XR0 register is set to 1, the transceiver will reset entire circuits and register contents to default value then clear the bit 15 of XR0 to 0.

7.7 Wake on LAN Function

The AN985B/BX can assert a signal to wake up the system when it receives a Magic Packet from the network. The Wake on LAN operation is described as follows:

7.7.1 The Magic Packet Format

- Valid destination address that can pass the address filter of the AN985B/BX
- The payload of frame must include at least 6 contiguous 'FF' followed immediately by 16 repetitions of IEEE address
- The frame can contain multiple 'six FF + sixteen IEEE address' patterns
- CRC OK

7.7.2 The Wake on LAN Operation

The Wake on LAN enable function is controlled by bit 18 of CSR18; it is loaded from the EEPROM after reset or programmed by a driver to enable Wake on LAN function. If the bit 18 of CSR18 is set and the AN985B/BX receives a Magic Packet, it will assert the PME# signal (drive to low) to indicated is receiving a wake up frame as well as to set the PME status bit (the bit 15 of CSR20).

7.8 ACPI Power Management Function

The AN985B/BX has a built-in capability for Power Management (PM), which controlled by the host system The AN985B/BX will provide:

- Compatibility with Device Class Power Management Reference Specification, Rev1.09
- Compatibility with ACPI specification, Rev 1.0
- Compatibility with CARDBUS Bus Power Management Interface Specification, Rev 1.1
- Compatibility with AMD Magic Packet™ Technology.
- Compatibility with CARDBUS CLKRUN scheme.



7.8.1 Power States

DO (Fully On)

In this state the AN985B/BX operates at full functionality and consumes its normal power. While in the D0 state, if the CARDBUS clock is lower than 16 MHz, the AN985B/BX may not receive or transmit frames properly.

D1

In this state the AN985B/BX doesn't response to any accesses, except if configuration space and full function contexts are in place. The only network operation the AN985B/BX can initiate is a wake-up event.

D2

In this state the AN985B/BX only responds to access configuration space and full function context in place. The AN985B/BX can't transmit or receive, even the wake-up frame.

D3_{cold} (Power Removed)

In this state all function context is lost. When power is restored, the function will return to D0.

D3_{hot} (Software Visible D3)

When the AN985B/BX is brought back to D0 from D3_{hot} the software must perform a full initialization.

The AN985B/BX in the D3_{hot} state responds to configuration cycles as long as power and clocks are supplied. This requires the device to perform an internal reset and return to a power-up reset condition without the RST# pin asserted.

Device State	CARDBU S-Bus State	Function Context	Clock	Power	Supported Actions to Function	Supported Actions from Function
D0	B0	Full function context in place	Full speed	Full power	Any CARDBUS transaction	Any CARDBUS transaction or interrupt
D1	B0, B1	Configuration maintained. No Tx and Rx except wake-up events	Stopped to Full speed	-	CARDBUS configuration access	Only wake-up events
D2	B0, B1, B2	Configuration maintained. No Tx and Rx	Stopped to Full speed	-	CARDBUS configuration access (B0, B1)	-
D3hot	B0, B1, B2	Configuration lost, full initialization required upon return to D0	Stopped to Full speed	-	CARDBUS configuration access (B0, B1)	-
D3cold	B3	All configurations lost. Power-on defaults in place on return to D0	No clock	No power	Power-on reset	-

Table 5Power State



8 Registers and Descriptors Description

There are three kinds of registers designed for AN985B/BX. They are AN985B/BX configuration registers, CARDBUS control/status registers, and Transceiver control/status registers.

The AN985B/BX configuration registers are used to initialize and configure the AN985B/BX for identifying and querying the AN985B/BX.

The CARDBUS control/status registers are used to communicate between host and AN985B/BX. Host can initialize, control, and read the status of the AN985B/BX through the mapped I/O or memory address space.

Regarding the registers of transceiver portion of AN985B/BX, there are 11 basic registers with 16bits supporting for AN985B/BX. It includes 7 basic registers which are defined according to the clause 22 "Reconciliation Sublayer and Media Independent Interface" and clause 28 "Physical Layer link signaling for 10 Mbit/s and 100 Mbit/s Auto-Negotiation on twisted pair" of IEEE802.3u standard. The AN985B/BX also provides receiving and transmitting descriptors for packet buffering and management. These descriptors are described in the following section



8.1 AN985B/BX Configuration Registers

Table 6 Registers Address Space

Module	Base Address	End Address	Note
Configuration	0000 0000 _H	0000 00C4 _H	Ххххх

Register Short Name	Register Long Name	Offset Address	Page Number	
LID_CR0	Loaded Identification Number of Device and	00 _H	36	
	Vendor			
CSD_CR1	Configuration Command and Status	04 _H	36	
CC_CR2	Class Code and Revision Number	08 _H	38	
LT_CR3	Latency Timer	0C _H	38	
IOBA_CR4	I/O Base Address	10 _H	39	
MBA_CR5	Memory Base Address	14 _H	40	
CIS_CR10	Card Information Structure	28 _H	40	
SID_CR11	Subsystem ID and Vendor ID	2C _H	41	
BRBA_CR12	Boot ROM Base Address	30 _H	41	
CP_CR13	Capabilities Pointer	34 _H	41	
CI_CR15	Configuration Interrupt	3C _H	42	
DS_CR16	Driver Space for Special Purpose	40 _H	43	
SIG_CR32	Signature	80 _H	43	
PMR0_CR48	Power Management Register 0	C0 _H	44	
PMR1_CR49	Power Management Register 1	C4 _H	46	

Table 7Registers Overview

The register is addressed wordwise.

Table 8 Registers Access ConditionsRegisters Access Conditions

Access Condition Short Name	Dependency
	= _B .

Standard abbreviations:

Table 9 Registers Access Types

Mode	Symbol	Description Hardware (HW)	Description Software (SW)	
read/write	rw	Register is used as input for the HW	Register is read and writable by SW	
read	r	Register is written by HW (register between input and output -> one cycle delay)	alue written by software is ignored by ardware; that is, software may write any alue to this field without affecting hardware ehavior (= Target for development.)	
write	w		Register is writable by SW	
read/write hardware affected	rwh	Register can be modified by HW	Register can be modified by HW, but the priority SW versus HW has to be specified	



Mode	Symbol	Description Hardware (HW)	Description Software (SW)	
	rwv			
Read only ro		Register is set by HW (register between input and output -> one cycle delay)	SW can only read this register	
Read virtual rv		Physically, there is no new register, the input of the signal is connected directly to the address multiplexer.	SW can only read this register	
Latch high, self clearing	lhsc	Latch high signal at high level, clear on read	SW can read the register	
Latch low, self clearing	llsc	Latch high signal at low-level, clear on read	SW can read the register	
Latch high, mask clearing	lhmk	Latch high signal at high level, register cleared with written mask	SW can read the register, with write mask the register can be cleared (1 clears)	
Latch low, mask clearing	llmk	Latch high signal at low-level, register cleared on read	SW can read the register, with write mask the register can be cleared (1 clears)	
Interrupt high, self clearing	ihsc	Differentiate the input signal (low- >high) register cleared on read	SW can read the register	
Interrupt low, self clearing	ilsc	Differentiate the input signal (high- >low) register cleared on read	SW can read the register	
Interrupt high, mask clearing	ihmk	Differentiate the input signal (high- >low) register cleared with written mask	SW can read the register, with write mask the register can be cleared	
Interrupt low, mask clearing	ilmk	Differentiate the input signal (low- >high) register cleared with written mask	SW can read the register, with write mask the register can be cleared	
Interrupt enable register	ien	Enables the interrupt source for interrupt generation	SW can read and write this register	
latch_on_reset	lor	rw register, value is latched after first clock cycle after reset	Register is read and writable by SW	
Read/write self clearing	rwsc	Register is used as input for the hw, the register will be cleared due to a HW mechanism.	Writing to the register generates a strobe signal for the HW (1 pdi clock cycle) Register is read and writable by SW.	

Table 9Registers Access Types (cont'd)

Table 10Registers Clock Domains

Clock Short Name	Description

8.1.1 AN985B/BX Configuration Registers Descriptions

Offset	b31	31b16 b15b16 b15			b0
00h	Device ID*		Vendor ID*		
04h	Status		Command		
08h	Base Class Code Subclass			Revision#	Step#



Offset	b31b16		b15b0		
0ch			Latency timer	Cache line size	
10h	Base I/O address				
14h	Base memory add	Base memory address			
18h~24h	Reserved				
28h	ROM-im*	Address space offset*		Add-indi*	
2ch	Subsystem ID*		Subsystem vendor ID*		
30h	Boot ROM base address				
34h	Reserved				
38h	Reserved				
3ch	Max_Lat*	Min_Gnt*	Interrupt pin	Interrupt line	
40h	Reserved		Driver Space	Reserved	
80h	Signature of AN985B/BX				
c0h	PMC		Next_Item_Ptr	Cap_ID	
c4h	Reserved		PMCSR	+	

Note: Automatically recalled from EEPROM when CARDBUS reset is deserted.

1. $CIS(28_H)$ is a read-only register.

2. $DS(40_H)$, bit 15-8, is read/write able register.

3. $SIG(80_{H})$ is hard wired register, read only.

Loaded Identification Number of Device and Vendor

LID_CR0	Offset	Reset Value
Loaded Identification Number of Device and	00 _н	From EEPROM _H
Vendor		

<u>31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0</u>

LDID	LVID
ro	ro

Field	Bits	Туре	Description
LDID	31:16	ro	Loaded Device ID
			The device ID number loaded from serial EEPROM.
LVID	15:0	ro	Loaded Vendor ID
			The vendor ID number loaded from serial EEPROM.

Reset Value loaded from EEPROM

Configuration Command and Status



AN985B/BX

CSD_CR1			Offset Reset Value
Configuration Command and Status			04 _H 0290 0000 _H
24 20 20 20 2		00 00 04	
SPSESMSTRO	ICNCT	BB Res	NC Res CS Re CP CMCM CI E s E Res O SA O*
rw rw rw rw rc	o ro rw	ro ro	ro ro rw ro rw rw rw rw
Field	Bits	Туре	Description
SPE	31	rw	Status of Parity Error
			1 _B , means that AN985B/BX detected a parity error. This bit will be set in this condition even if the parity error response (bit 6 of CR1) is disabled.
SES	30	rw	Status of System Error 1_B , means that AN985B/BX asserted the system error pin
SMA	29	rw	Status of Master Abort
			1 _B , means that AN985B/BX received a master abort and terminated a master transaction
STA	28	rw	Status of Target Abort 1 _B , means that AN985B/BX received a target abort and terminated a
_	07		master transaction
	27	ro	Reserved
SDST	26:25	ro	Status of Device Select Timing The timing of the assertion of device select. 01_B , means a medium assertion of DEVSEL#
SDPR	24	rw	Status of Data Parity Report 1: when three conditions are met: AN985B/BX asserted parity error - PERR# or it detected parity error asserted by other device. AN985B/BX is operating as a bus master. 5AN985B/BX's parity error response bit (bit 6 of CR1) is enabled.
SFBB	23	ro	Status of Fast Back-to-Back Always 1, since AN985B/BX has the ability to accept fast back-to-back transactions.
Res	22:21	ro	Reserved
NC	20	ro	$\begin{array}{l} \textbf{New Capabilities} \\ This bit indicates that whether the AN985B/BX provides a list of extended capabilities, such as CARDBUS power management. \\ 0_{B} , the AN985B/BX doesn't provide New Capabilities \\ 1_{B} , the AN985B/BX provides the CARDBUS management function \end{array}$
Res	19:9	ro	Reserved
CSE	8	rw	Command of System Error Response 1 _B , enable system error response. AN985B/BX will assert SERR#
			when it find a parity error on the address phase.



Field	Bits	Туре	Description		
CPE	6	rw	Command of Parity Error Response0B, disable parity error response. AN985B/BX will ignore any detected parity error and keep on its operating. Default value is 0.1B, enable parity error response. AN985B/BX will assert system error (bit 13 of CSR5) when a parity error is detected.		
Res	5:3	ro	Reserved		
СМО	2	rw	Command of Master Operation Ability0B, disable the bus master ability1B, enable the CARDBUS bus master ability. Default value is 1 for normal operation.		
CMSA	1	rw	$\begin{array}{l} \textbf{Command of Memory Space Access}\\ \textbf{0}_{B} & , \mbox{disable the memory space access ability}\\ \textbf{1}_{B} & , \mbox{enable the memory space access ability} \end{array}$		
CIOSA	0	rw	$\begin{array}{l} \mbox{Command of I/O Space Access} \\ 0_{B} & , \mbox{disable the I/O space access ability} \\ 1_{B} & , \mbox{enable the I/O space access ability} \end{array}$		

Class Code and Revision Number

CC_CR2	Offset	Reset Value
Class Code and Revision Number	08 _H	0200 ???? _н

31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

BCC	SC	Res	RN	SN	
ro	ro	ro	ro	ro	

Field	Bits	Туре	Description
BCC	31:24	ro	Base Class Code It means AN985B/BX is network controller.
SC	23:16	ro	Subclass Code It means AN985B/BX is a Fast Ethernet Controller.
Res	15:8	ro	Reserved
RN	7:4	ro	Revision Number Identifies the revision number of AN985B/BX.
SN	3:0	ro	Step Number Identifies the AN985B/BX steps within the current revision.

Latency Timer

LT_CR3	Offset	Reset Value
Latency Timer	0C _H	0000 0000 _H



31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16	15 14 13 12 11 10 9 8	7 6 5 4 3 2 1 0
Res	LT	CLS
ro	rw	rw

Field	Bits	Туре	Description
Res	31:16	ro	Reserved
LT	15:8	rw	Latency Timer This value specifies the latency timer of the AN985B/BX in units of CARDBUS bus clock. Once the AN985B/BX asserts FRAME#, the latency timer starts to count. If the latency timer expires and the AN985B/BX still asserted FRAME#, then the AN985B/BX will terminate the data transaction as soon as its GNT# is removed.
CLS	7:0	rw	Cache Line Size This value specifies the system cache line size in units of 32-bit double words (DW). The AN985B/BX supports 8, 16, and 32 DW of cache line size. This value is used by the AN985B/BX driver to program the cache alignment bits (bit 14 and 15 of CSR0). The cache alignment bits are used for cache oriented CARDBUS commands; say memory-read-line, memory-read-multiple, and memory-write-and-invalidate.

I/O Base Address

IOBA_CR4 I/O Base Address	Offset 10 _H						Value 0001 _H
31 30 29 28 27 26 25 24 23 22 21 20 19 18	<u>17 16 15 14 1</u>	13 12 11 10	98	7 6	5 4	3 2	1 0
IOBA					Res	6	IO SI
rw					ro		ro

Field	Bits	Туре	Description
IOBA	31:8	rw	I/O Base Address This value indicate the base address of CARDBUS control and status register (CSR0~28).
Res	7:1	ro	Reserved
IOSI	0	ro	I/O Space Indicator 1_B , means that the configuration registers map into the I/O space



Memory Base Address

MBA_CR5 Memory Base Address	Offset 14 _H			Reset Value 0000 0000 _P	-
31 30 29 28 27 26 25 24 23 22 2	21 20 19 18 17 16 15 14 13 12 11 10	9 8 7	6 5 4	3 2 1 0)
	MBA		Res)
	rw		ro	ro	2

Field	Bits	Туре	Description
MBA	31:10	rw	Memory Base Address
			This value indicates the base address of CARDBUS control and status register (CSR0~28).
Res	9:1	ro	Reserved
IOSI	0	ro	Memory Space Indicator
			1_{B} $\ \ $, means that the configuration registers map into the I/O space

Card Information Structure

This register is used to point one of the possible address spaces where the CIS begins. This register is designed for CARDBUS environment. It's data is auto-loaded from the serial EEPROM after power on or hardware reset.

CIS_CR10	Offset	Reset Value
Card Information Structure	28 _H	From EEPROM _H

31 30	29 28 27	26 25 2	24 23 22	21 20 1	19 18 17 1	6 15 14 13 1	12 11 10 9 8 7 6 5	4	32	1 0
									1	
ROM					ASC	C				AI
	I		1 1 1					1	1	
ro					ro					ro

Field	Bits	Туре	Description
ROM	31:30	ro	ROM Image This ROM image value is applied when the CIS is stored in a boot ROM. This value is loaded from serial EEPROM.
ASO	29:4	ro	Address Space Offset This value indicates the offset within the address space. The address space is specified by address space indicator(bit 2~0 of CR10).
AI	3:0	ro	$\begin{array}{c} \mbox{Address Space Indicator} \\ \mbox{This value indicates the location where the CIS address space begins.} \\ \mbox{111}_{B} \ , \mbox{means that the CIS begins in the boot ROM space.} \\ \mbox{others}_{B}, \mbox{ makes all the bits of CIS reset to 0} \end{array}$



Subsystem ID and Vendor ID

SID_CR11 Subsystem ID and Vendor ID		รset ว _{ิн}		Reset Value From EEPROM _H
31 30 29 28 27 26 25 24 23 2 SID	22 21 20 19 18 17 16	15 14 13 12 11 10 9	9 8 7 6 5 SVID	<u>4</u> 3210

Field	Bits	Туре	Description
SID	31:16	ro	Subsystem ID
			This value is loaded from EEPROM after power on or hardware reset.
SVID	15:0	ro	Subsystem Vendor ID
			This value is loaded from EEPROM after power on or hardware reset.

Boot ROM Base Address

This register should be initialized before accessing the boot ROM space. (Write ffffffff_H return fffe0001_H)

BRBA_CR12 Boot ROM Base Address	Offset 30 _H	Reset Value XXXX 0000 _H
31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 BRBA	16 15 14 13 12 11 10 9 8 7 6 5 4 Res	3 2 1 0 BR E
rw	ro	rw

Field	Bits	Туре	Description
BRBA	31:17	rw	Boot ROM Base Address This value indicates the address mapping of boot ROM field. Besides, it also defines the boot ROM size. The value of bit 17~10 is set to 0 for AN985B/BX to support up to 256 KB of boot ROM.
Res	16:1	ro	Reserved
BRE	0	rw	$\begin{array}{l} \textbf{Boot ROM Enable} \\ The AN985B/BX really enables its boot ROM access only if both the memory space access bit (bit 1 of CR1) and this bit are set to 1. \\ 1_B , enable Boot ROM (Combines with bit 1 of CR1) \end{array}$

Capabilities Pointer

CP_CR13	Offset	Reset Value
Capabilities Pointer	34 _H	0000 00C0 _H



AN985B/BX

Registers and Descriptors Description

31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8	7 6 5 4 3 2 1 0
Res	СР
ro	ro

Field	Bits	Туре	Description
Res	31:8	ro	Reserved
СР	7:0	ro	Capabilities Pointer

Configuration Interrupt

CI_CR15 Configuration Interrupt		fset C _H	Reset Value XXXX 01XX _H
31 30 29 28 27 26 25 24		15 14 13 12 11 10 9 8	7 6 5 4 3 2 1 0
ML	MG	IP	
ro	ro	ro	rw

Field	Bits	Туре	Description
ML	31:24	ro	Max. Lat Register This value indicates "how often" the AN985B/BX needs to access to the CARDBUS bus in the units of 250 ns. This value is loaded from serial EEPROM after power on or hardware reset.
			Note: Automatically recalled from EEPROM.
MG	23:16	ro	Min. Gnt Register This value indicates how long the AN985B/BX needs to retain the CARDBUS bus ownership whenever it initiates a transaction, in the units of 250 ns. This value is loaded from serial EEPROM after power on or hardware reset.
			Note: Automatically recalled from EEPROM.
IP	15:8	ro	Interrupt Pin This value indicates which of the four interrupt request pins that AN985B/BX is connected.Always 01 _H : means the AN985B/BX connects to INTA#
IL	7:0	rw	Interrupt Line This value indicates which of the system interrupt request lines the INTA# of AN985B/BX is routed to. The BIOS will fill this field when it initializes and configures the system. The AN985B/BX driver can use this value to determine priority and vector information.



Driver Space for Special Purpose

DS_CR16 Driver Space for Special Purpose	Offset 40 _H	Reset Value 0000 XX00 _H
31 30 29 28 27 26 25 24 23 22 21 20 19 1	3 17 16 15 14 13 12 11 10 9 8	7 6 5 4 3 2 1 0
Res	DS	Res
ro	rw	ro

Field	Bits	Туре	Description
Res	31:16	ro	Reserved
DS	15:8	rw	Driver Space for special purpose Since this area won't be cleared in the software reset. The AN985B/BX driver can use this rw area for special purpose.
Res	7:0	ro	Reserved

Signature of AN985B/BX

Hard wired register, read only

SIG_CR32 Signature				iset D _H	Reset Value 0985 1317 _H
31 30 29 28	27_26_25_24	23 22 21	20 19 18 17 16	15 14 13 12 11 10 9 8 7 6 5	5 4 3 2 1 0
	D	ID		VID	
	r	0		ro	
Field	Bits	Туре	Description		
DID	31:16	ro	Device ID		

DID	31:16	ro	Device ID	
			The device ID number of AN985B/BX.	
VID	15:0	ro	/endor ID	
			The vendor ID number of ADM Technology Corp.	



Power Management Register 0

PMR0_CR48 Power Manag	-		Offset C0 _H	Reset Value FE82 0001 _H
31 30 29 28 PMES	D2 D1		20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 Re PM s EC VER NIP	5 4 3 2 1 0 CAPID
ro	ro ro	ro ro	rororororo	ro
Field	Bits	Туре	Description	
PMES	31:27	ro	PME Support The AN985B/BX will assert PME#/CSTSCHG signal D2, D3 power state. The AN985B/BX supports Wake states.	
D2S	26	ro	D2 Support The AN985B/BX supports D2 Power Management Si	tate.
D1S	25	ro	D1 Support The AN985B/BX supports D1 Power Management St	tate.
AUXC	24:22	ro	Aux Current These three bits report the maximum 3.3 Vaux curren AN985B/BX. If bit 31 of PMR0 is '1', the default value AN985B/BX need 100 mA to support remote wake-u state.	e is 0101 _B , means
DSI	21	ro	Device Specific InitializationThe Device Specific Initialization bit indicates whetherinitialization of this function is required before the gerdriver is able to use it.00, indicates that the function does not require ainitialization sequence following transition to thestate	neric class device device specific
Res	20	ro	Reserved	
PMEC	19	ro	PME Clock When "1" indicates that the AN985B/BX relies on the CARDBUS clock for PME#/CSTSCHG operation. Wh no CARDBUS clock is required for the AN985B/BX to PME#/CSTSCHG.	ile "0" indicates the
VER	18:16	ro	Version The value of 010 _B indicates that the AN985B/BX com 1.0a of the CARDBUS Power Management Interface	
NIP	15:8	ro	Next Item Pointer This value is always $0_{\rm H}$, indicates that there is no add Capabilities List.	ditional items in the



Field	Bits	Туре	Description	
CAPID	7:0	ro	Capability Identifier This value is always 01 _H , indicates the link list item as being CARDBUS Power Management Registers.	



Power Management Register 1

PMR1_CR49 Power Management Register 1	Offset C4 _H			et Value)0 0000 _H
31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 Res	PM DSCA ES L	12 11 10 9 8 DSEL PM EE	7 6 5 4 3 2 Res	2 1 0 PWRS
ro	rw* ro	rw rw	ro	rw

Field	Bits	Туре	Description
Res	31:16	ro	Reserved
PMES	15	rw*	PME Status This bit is set when the AN985B/BX would normally assert the PME#/CSTSCHG signal for wake-up event, this bit is independent of the state of the PME-En bit. Writing a "1" to this bit will clear it and cause the AN985B/BX to stop asserting a PME#/CSTSCHG (if enabled). Writing a "0" has no effect. Note: rw*: Read and Write Clear
DSCAL	14:13	ro	Data Scale Indicates the scaling factor to be used when interpreting the value of the Data register.
DSEL	12:9	rw	Data SelectThis four-bit field is used to select which data is to be reported through theData register and Data_Scale field.
PMEE	8	rw	PME En "1" enables the AN985B/BX to assert PME#/CSTSCHG. When "0" disables the PME#/CSTSCHG assertion. Magic packet default enable: Csr18 <18> and csr18 <19> are set ->csr13 <9> is set, then #pme asserts without impact of PME_En.
Res	7:2	ro	Reserved
PWRS	1:0	rw	Power StateThis two-bit field is used both to determine the current power state of the AN985B/BX and to set the AN985B/BX into a new power state. The definition of this field is given below.Note: This field is auto cleared to D0 when power resumed. 00_B D0, 01_B 01_B D1, 10_B 10_B D2, 11_B 11_B D3hot,



8.2 PCI /CARDBUS Control/Status Registers

Table 11 Registers Address Space

Module	Base Address	End Address	Note
PCI/CARDBUS	0000 0000 _H	0000 010C _H	

Table 12Registers Overview

Register Short Name	Register Long Name	Offset Address	Page Number
PAR_CSR0	CARDBUS Access Register	00 _H	49
TDR_CSR1	Transmit Demand Register	08 _H	50
RDR_CSR2	Receive Demand Register	10 _H	52
RDB_CSR3	Receive Descriptor Base Address	18 _H	52
TDB_CSR4	Transmit Descriptor Base Address	20 _H	53
SR_CSR5	Status Register	28 _H	53
NAR_CSR6	Network Access Register	30 _н	57
IER_CSR7	Interrupt Enable Register	38 _H	58
LPC_CSR8	Lost Packet Counter	40 _H	61
SPR_CSR9	Serial Port Register	48 _H	61
TMR_CSR11	General-Purpose Timer	58 _H	62
WCSR_CSR13	Wake-up Control/Status Register	68 _H	62
WTMR_CSR15	Watchdog Timer	78 _H	65
ACSR5_CSR16	Assistant CSR5 (Status Register 2)	80 _H	66
ACSR7_CSR17	Assistant CSR7 (Interrupt Enable Register 2)	84 _H	67
CR_CSR18	Command Register	88 _H	67
CARDBUSC_CSR19	CARDBUS Bus Performance Counter	8C _H	70
PMCSR_CSR20	Power Management Command and Status	90 _H	70
WTDP_CSR21	Current Working Transmit Descriptor Pointer	94 _H	72
WRDP_CSR22	Current Working Receive Descriptor Pointer	98 _H	72
TXBR_CSR23	Transmit Burst Count/Time-out	9C _H	73
FROM_CSR24	Flash ROM (also the boot ROM) Port	A0 _H	73
PAR0_CSR25	Physical Address Register 0	A4 _H	74
PAR1_CSR26	Physical Address Register 1	A8 _H	74
MAR0_CSR27	Multicast Address Register 0	AC _H	75
MAR1_CSR28	Multicast Address Register 1	B0 _H	76
UAR0_CSR_29	Unicast Address Register 0	B4 _H	77
UAR1_CSR_30	Unicast Address Register 1	B8 _H	77
OMR	Operation Mode Register	FC _H	77
FER	Function Event Register	100 _H	78
FEMR	Function Event Mask Register	104 _H	79
FPSR	Function Present State Register	108 _H	80
FFER	Function Force Event Register	10C _H	80



The register is addressed wordwise.

Standard abbreviations:

Table 10 Registers Access Types	Table 13	Registers Access Types
---------------------------------	----------	------------------------

Mode	Symbol	Description Hardware (HW)	Description Software (SW)
read/write	rw	Register is used as input for the HW	Register is read and writable by SW
read	r	Register is written by HW (register between input and output -> one cycle delay)	Value written by software is ignored by hardware; that is, software may write any value to this field without affecting hardware behavior (= Target for development.)
write	w		Register is writable by SW
read/write hardware affected	rwh	Register can be modified by HW	Register can be modified by HW, but the priority SW versus HW has to be specified
	rwv		
Read only	ro	Register is set by HW (register between input and output -> one cycle delay)	SW can only read this register
Read virtual	rv	Physically, there is no new register, the input of the signal is connected directly to the address multiplexer.	SW can only read this register
Latch high, self clearing	lhsc	Latch high signal at high level, clear on read	SW can read the register
Latch low, self clearing	llsc	Latch high signal at low-level, clear on read	SW can read the register
Latch high, mask clearing	lhmk	Latch high signal at high level, register cleared with written mask	SW can read the register, with write mask the register can be cleared (1 clears)
Latch low, mask clearing	llmk	Latch high signal at low-level, register cleared on read	SW can read the register, with write mask the register can be cleared (1 clears)
Interrupt high, self clearing	ihsc	Differentiate the input signal (low- >high) register cleared on read	SW can read the register
Interrupt low, self clearing	ilsc	Differentiate the input signal (high- >low) register cleared on read	SW can read the register
Interrupt high, mask clearing	ihmk	Differentiate the input signal (high- >low) register cleared with written mask	SW can read the register, with write mask the register can be cleared
Interrupt low, mask clearing	ilmk	Differentiate the input signal (low- >high) register cleared with written mask	SW can read the register, with write mask the register can be cleared
Interrupt enable register	ien	Enables the interrupt source for interrupt generation	SW can read and write this register
latch_on_reset	lor	rw register, value is latched after first clock cycle after reset	Register is read and writable by SW
Read/write self clearing	rwsc	Register is used as input for the hw, the register will be cleared due to a HW mechanism.	Writing to the register generates a strobe signal for the HW (1 pdi clock cycle) Register is read and writable by SW.



8.2.1 PCI/CARDBUS Control/Status Registers Description

CARDBUS Access Register

PAR_CSR0	Offset	Reset Value
CARDBUS Access Register	00 _H	0000 1000 _H

3	1 30 29 28 27 26 2	25 24 23 22 21	20 19 18	17 16 15 ⁻	4 13 12 11 10 9	870	6543	2 1 0
	Res	MWMR Re MI IE LE s MI		AP Re CA	- PBL	BL E	DSL	BASW R R
	ro	rw*rw* ro rw	* ro rw	/* ro rw [:]	rw*	rw*	rw*	rw*rw*

Field	Bits	Туре	Description
Res	31:25	ro	Reserved
MWIE	24	rw*	Memory Write and Invalidate Enable
			Note: rw*: Before writing the trasmitting and receiving operations should be stopped.
			 0_B , disable AN985B/BX to generate memory write invalidate command and use memory write commands instead 1_B , enable AN985B/BX to generate memory write invalidate command. AN985B/BX will generate this command while writing full cache lines
MRLE	23	rw*	Memory Read Line Enable
			Note: rw*: Before writing the trasmitting and receiving operations should be stopped.
			1 _B , enable AN985B/BX to generate memory read line command while read access instruction reach the cache line boundary. If the read access instruction doesn't reach the cache line boundary then AN985B/BX uses the memory read command instead.
Res	22	ro	Reserved
MRME	21	rw*	Memory Read Multiple Enable
			Note: rw*: Before writing the trasmitting and receiving operations should be stopped.
			1 _B , enable AN985B/BX to generate memory read multiple commands while reading full cache line. If the memory is not cache aligned the AN985B/BX uses memory read command instead.
Res	20:19	ro	Reserved



Field	Bits	Туре	Description
TAP	18:17	rw*	Transmit Auto-polling in Transmit Suspended State
			Note: rw*: Before writing the trasmitting and receiving operations should be stopped.
			00 _B , disable auto-polling (default)
			01 _B , polling own-bit every 200 μ s
			10 _B , polling own-bit every 800 μ s
			11 _B , polling own-bit every 1600 μ s
Res	16	ro	Reserved
CAL	15:14	rw*	Cache Alignment, Address Boundary for Data Burst, Set after Reset
			Note: rw*: Before writing the trasmitting and receiving operations should be stopped.
			00 _B , reserved (default)
			01 _B , 8 DW boundary alignment
			10 _B , 16 DW boundary alignment
_			11 _B , 32 DW boundary alignment
PBL	13:8	rw*	Programmable Burst Length
			This value defines the maximum number of DW to be transferred in one DMA transaction. Value: 0 (unlimited), 1, 2, 4, 8, 16 (default), 32
			Note: rw*: Before writing the trasmitting and receiving operations should
			be stopped.
BLE	7	rw*	Big or Little Endian Selection
			Note: rw*: Before writing the trasmitting and receiving operations should be stopped.
			0 _B , little endian (e.g. INTEL)
			$1_{\rm B}$, big endian (only for data buffer)
DSL	6:2	rw*	Descriptor Skip Length
			Defines the gap between two descriptions in the units of DW.
			Note: rw*: Before writing the trasmitting and receiving operations should be stopped.
BAR	1	rw*	Bus Arbitration
			Note: rw*: Before writing the trasmitting and receiving operations should be stopped.
			0 _B , receive higher priority
			0 _B , receive higher priority 1 _B , transmit higher priority
SWR	0	rw*	Software Reset
own			Note: rw*: Before writing the trasmitting and receiving operations should be stopped.
			 1_B , reset all internal hardware except configuration registers. This signal will be cleared by AN985B/BX itself after it completed the reset process.

Transmit Demand Register



TDR_CSR1 Transmit Demand Register	Offset 08 _H	Reset Value FFFF FFFF _H
31 30 29 28 27 26 25 24 23	21 20 19 18 17 16 15 14 13 12 11 10 9 TPDM	8 7 6 5 4 3 2 1 0
	rw*	

Field	Bits	Туре	Description
TPDM	31:0	rw*	Transmit Poll Demand When written any value in suspended state, trigger read-tx-descriptor process and check the own-bit, if own-bit = 1, then start transmit process.
			Note: rw*: Before writing the trasmitting process should be in the suspended state.



Receive Demand Register

RDR_CSR2 Receive Demand Register	Offset 10 _H	Reset Value FFFF FFFF _H
31 30 29 28 27 26 25 24 23 22 2	1 20 19 18 17 16 15 14 13 12 11 10	9 8 7 6 5 4 3 2 1 0
	RPDM	

Field	Bits	Туре	Description
RPDM	31:0	rw*	Receive Poll Demand When written any value in suspended state, trigger the read-rx-descriptor process and check own-bit, if own- bit = 1, then start move data to buffer from FIFO.
			Note: rw*: Before writing the receiving process should be in the suspended state.

Receive Descriptor Base Address

RDB_CSR3 Receive Descriptor Base Address		t Value x xxxx _H
31 30 29 28 27 26 25 24 23 22 21 20 19 18	17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0
	SAR	RBND
	rw*	ro

Field	Bits	Туре	Description
SAR	31:2	rw*	Start Address of Receive Descriptor
			Note: rw*: Before writing the receiving process should be stopped.
RBND	1:0	ro	Must be 00, DW Boundary



Transmit Descriptor Base Address

TDB_CSR4 Transmit Descriptor Base Address	Offset 20 _H		eset Value xxxx xxxx _H
31 30 29 28 27 26 25 24 23 22 21	20 19 18 17 16 15 14 13 12	2 11 10 9 8 7 6 5 4 3	2 1 0
	SAT		TBND
	rw*		ro

Field	Bits	Туре	Description
SAT	31:2	rw*	Start Address of Transmit Descriptor
			Note: rw*: Before writing the trasmitting process should be stopped.
TBND	1:0	ro	Must be 00, DW Boundary

Status Register

	SR_CSR5 Status Register			Offset 28 _H										Reset Value 0000 0000 _H						
	31 30 29 28 27 26	25 24 23	22 21 20	19 18 17	' 16 1	15 14	13 12	2 11	10	98	7	6	5	4	3	2	1	0		
	Res	BET	TS	RS		AI Re SS s	FB Re E s	e GP TT		RWRP T S			TU F	Re s	тJ Т	TD U	TP S	TC I		
ro ro		ro	ro	ro/Inc	/lh ro	ro/lh ro	ro/lh	roro	o/lhro/lh	io/lh	io/Ih	io/lh	ror	o/Ih	10/lh	io/lh	io/lŀ			

Field	Bits	Туре	Description
Res	31:26	ro	Reserved
BET	25:23	ro	$\begin{array}{c} \textbf{Bus Error Type} \\ This field is valid only when bit 13 of CSR5 (fatal bus error) is set. There is no interrupt generated by this field. \\ 000_{B} \ , parity error \\ 001_{B} \ , master abort \\ 010_{B} \ , target abort \\ 011_{B} \ , reserved \\ 1xx_{B} \ , reserved \end{array}$



Field	Bits	Туре	Description
TS	22:20	ro	$\label{eq:transmit_state} \begin{array}{ c c c } \hline \textbf{Transmit State} \\ Report the current transmission state only, no interrupt will be generated. \\ 000_{B} , stop \\ 001_{B} , read descriptor \\ 010_{B} , read descriptor \\ 011_{B} , FIFO fill read the data from memory and put into FIFO \\ 100_{B} , reserved \\ 101_{B} , reserved \\ 110_{B} , suspended, unavailable transmit descriptor or FIFO overflow \\ 111_{B} , write descriptor \\ \end{array}$
RS	19:17	ro	$\begin{tabular}{ c c c c c } \hline Receive State \\ Report current receive state only, no interrupt will be generated. \\ \hline 000_B , stop \\ \hline 001_B , read descriptor \\ \hline 010_B , read descriptor \\ \hline 010_B , check this packet and pre-fetch next descriptor \\ \hline 011_B , wait for receiving data \\ \hline 100_B , suspended \\ \hline 101_B , write descriptor \\ \hline 110_B , flush the current FIFO \\ \hline 111_B , FIFO drain. move data from receiving FIFO into memory \\ \hline \end{tabular}$
NISS	16	ro/lh	Normal Interrupt Status SummaryIt's set if any of below bits of CSR5 asserted. (Combines with bit 16 of ACSR5)bit0, transmit completed interruptbit2, transmit descriptor unavailablebit6, receive descriptor interruptNote: LH = High Latching and cleared by writing 1
AISS	15	ro/lh	Abnormal Interrupt Status Summary It's set if any of below bits of CSR5 asserted. (Combines with bit 15 of ACSR5) bit1, transmit process stopped bit3, transmit jabber timer time-out bit5, transmit under-flow bit7, receive descriptor unavailable bit8, receive processor stopped bit9, receive watchdog time-out bit11, general purpose timer time-out bit13, fatal bus error Note: LH = High Latching and cleared by writing 1
Res	14	ro	Reserved
FBE	13	ro/lh	Fatal Bus ErrorNote: LH = High Latching and cleared by writing 1111, while any of parity error master abort, or target abort is occurred (see bits 25~23 of CSR5). AN985B/BX will disable all bus access. The way to recover parity error is by setting software reset.
Res	12	ro	Reserved



Field	Bits	Туре	Description
GPTT	11	ro/lh	General Purpose Timer Time-out
			Base on CSR11 timer register.
			Note: LH = High Latching and cleared by writing 1
Res	10	ro	Reserved
RWT	9	ro/lh	Receive Watchdog Time-out
			Based on CSR15 watchdog timer register.
			Note: LH = High Latching and cleared by writing 1
RPS	8	ro/lh	Receive Process Stopped Receive state = stop
			Note: LH = High Latching and cleared by writing 1
RDU	7	ro/lh	Receive Descriptor Unavailable
			Note: LH = High Latching and cleared by writing 1
			1 _B , while the next receive descriptor can't be applied by AN985B/BX. The receive process is suspended in this situation. To restart the receive process the ownership bit of next receive descriptor should be set to AN985B/BX and a receive poll demand command should be issued (or a new recognized frame is received, if the receive poll demand is not issued).
RCI	6	ro/lh	Receive Completed Interrupt
			Note: LH = High Latching and cleared by writing 1
			$1_{\rm B}$, while a frame reception is completed
TUF	5	ro/lh	Transmit Under-Flow
			Note: LH = High Latching and cleared by writing 1
			1 _B , while the transmit FIFO had an under-flow condition happened during transmitting. The transmit process will enter the suspended state and report the under-flow error on bit1 of TDES0
Res	4	ro	Reserved
TJT	3	ro/lh	Transmit Jabber Timer Time-out
			Note: LH = High Latching and cleared by writing 1
			 1_B , while the transmit jabber timer expired. The transmit processor will enter the stop state and the transmit jabber time-out flag of bit 14 of TDES0 will be asserted
TDU	2	ro/lh	Transmit Descriptor Unavailable
			Note: LH = High Latching and cleared by writing 1
			1 _B , while the next transmit descriptor can't be applied by AN985B/BX. The transmission process is suspended in this situation. To restart the transmission process the ownership bit of next transmit descriptor should be set to AN985B/BX and if the transmit automatic polling is not enabled then a transmit poll demand command should be issued.
TPS	1	ro/lh	Transmit Process Stopped
			Note: LH = High Latching and cleared by writing 1
		1	



AN985B/BX

Field	Bits	Туре	Description
TCI	0	ro/lh	Transmit Completed Interrupt
			Note: LH = High Latching and cleared by writing 1
_			1 _B , means a frame transmission is completed while bit 31 of TDES1 is asserted in the first transmit descriptor of the frame



Network Access Register

NAR_CSR6 Network Acce		Offset 30 _H														set 008				
31 30 29 28	23 22 2	1 20 -	19 1	18 17	16	15 14	13	12	11 1	0	9	87	6	5	4	3	2	1	0	
	Res	s	F s Re S	SQ E		1	TR	sт	FC	ОМ		Re	s M	MPF	SB C	Re s	ΡВ	PU	SR	Re s
	rv	/* ro r	w*	ro		rw*	rw	rw*	* rw*'	ł	ro	rw'	'Ťŵ*	* ř w*	* ror	w*†	₩**	*rw	ro	
Field	Description																			
Res	Res	erv	ved																	

Res	31:22	ro	Reserved
SF	21	rw*	Store and Forward for Transmit
			Note: w* = only write when the transmit processor stopped.
			0 _B , disable
			1_{B} , enable ignore the transmit threshold setting
Res	20	ro	Reserved
SQE	19	rw*	SQE Disable
			<i>Note: w</i> [*] = only write when the transmit processor stopped.
			0 _B , enable SQE function for 10BASE-T operation. The AN985B/BX provides SQE test function for 10BASE-T half duplex operation 1 _B , disable SQE function
Res	18:16	ro	Reserved
TR	15:14	rw*	Transmit Threshold Control
			Note: w* = only write when the transmit processor stopped.
			00 _B , 128-byte (100 Mbit/s) 72-byte (10 Mbit/s)
			01 _B , 256-byte (100 Mbit/s) 96-byte (10 Mbit/s)
			10 _B , 512-byte (100 Mbit/s) 128-byte (10 Mbit/s)
			00 _B , 1024-byte (100 Mbit/s) 160 -byte (10 Mbit/s)
ST	13	rw	Stop Transmit
			0 _B , stop (default)
			1 _B , start
FC	12	rw**	Force Collision Mode
			Note: w** = only write when the transmit and receive processor both
			stopped.
			0 _B , disable
			1_{B}^{J} , generate collision when transmit (for test in loop-back mode)



Field	Bits	Туре	Description
ОМ	11:10	rw**	Operating Mode
			Note: w** = only write when the transmit and receive processor both stopped.
			00 _B , normal
			01 _B , MAC loop-back
			10 _B , reserved
			11 _B , reserved
Res	9:8	ro	Reserved
MM	7	rw***	Multicast Mode
			<i>Note: w</i> *** = only write when the receive processor stopped.
			1 _B , receive all multicast packets
PR	6	rw***	Promiscuous Mode
			Note: w*** = only write when the receive processor stopped.
			0 _B , receive only the right destination address packets
			$1_{\rm B}$, receive any good packet
SBC	5	rw**	Stop Back-off Counter
			Note: w** = only write when the transmit and receive processor both
			stopped.
			0 _B , back-off counter is not effected by carrier
			$1_{\rm B}$, back-off counter stop when carrier is active and resume when
			carrier drop.
Res	4	ro	Reserved
PB	3	rw***	Pass Bad Packet
			Note: w*** = only write when the receive processor stopped.
			0 _B , filters all bad packets
			$1_{\rm B}$, receives any packets if pass address filter, including runt packets,
			CRC error, truncated packets For receiving all bad packets, the
			bit 6 of CSR6 should be set to 1.
PU	2	rw***	Pass Unicast Mode
			<i>Note: w</i> *** = only write when the receive processor stopped.
			$1_{\rm B}$, back-off counter stop when carrier is active and resume when
			carrier drop.
SR	1	rw	Start/Stop Receive
			$0_{\rm B}$, receive processor will enter stop state after the current reception
			frame completed. This value is effective only when the receive
			processor is in the running or suspending state. Notice: In "Stop
			Receive" state the PAUSE packet and Remote Wake Up packet won't be affected and can be received if the corresponding function
			is enabled.
			1 _B , receive processor will enter running state

Interrupt Enable Register



IER_CSR7 Interrupt Enable Register	Offset 38 _H										Reset Value 0000 0000 _H			
31 30 29 28 27 26 25 24 23 22 21 20 19 18 17	16 15	5 14	13 1	12 11	10	9	8 7	6	5	4	3	2	1	0
Res	NI AI E E			Re GF s T*			RS RI					TD U*		
ro	rw rw	/ ro	rw r	o rw	ro	rw	w rv	/ rw	rw	ro	rw	rw	rw	rw

Field	Bits	Туре	Description
Res	31:17	ro	Reserved
NIE	16	rw	Normal Interrupt Enable 1_B , enable all the normal interrupt bits (see bit16 of CSR5)
AIE	15	rw	Abnormal Interrupt Enable 1_B , enable all the abnormal interrupt bits (see bit15 of CSR5)
Res	14	ro	Reserved
FBEIE	13	rw	Fatal Bus Error Interrupt Enable 1 _B , combine this bit and bit 15 of CSR7 to enable fatal bus error interrupt
Res	12	ro	Reserved
GPTIE	11	rw	General Purpose Timer Interrupt Enable11optimizer101010111
Res	10	ro	Reserved
RWTIE	9	rw	Receive Watchdog Time-out Interrupt Enable1, combine this bit and bit 15 of CSR7 to enable receive watchdog time-out interrupt
RSIE	8	rw	Receive Stopped Interrupt Enable 1 _B , combine this bit and bit 15 of CSR7 to enable receive stopped interrupt
RUIE	7	rw	Receive Descriptor Unavailable Interrupt Enable11, combine this bit and bit 15 of CSR7 to enable receive descriptor unavailable interrupt
RCIE	6	rw	Receive Completed Interrupt Enable 1 _B , combine this bit and bit 16 of CSR7 to enable receive completed interrupt
TUIE	5	rw	Transmit Under-flow Interrupt Enable11optimize this bit and bit 15 of CSR7 to enable transmit under-flowinterrupt
Res	4	ro	Reserved
TJTTIE	3	rw	Transmit Jabber Timer Time-out Interrupt Enable11. combine this bit and bit 15 of CSR7 to enable transmit jabber timer time-out interrupt
TDUIE	2	rw	Transmit Descriptor Unavailable Interrupt Enable11, combine this bit and bit 16 of CSR7 to enable transmit descriptor unavailable interrupt



AN985B/BX

Field	Bits	Туре	Description
TPSIE	1	rw	Transmit Processor Stopped Interrupt Enable 1 _B , combine this bit and bit 15 of CSR7 to enable transmit processor stopped interrupt
TCIE	0	rw	Transmit Completed Interrupt Enable11, combine this bit and bit 16 of CSR7 to enable transmit completedinterrupt.



Lost Packet Counter

LPC_CSR8 Lost Packet Counter				Offset 40 _H										Reset V 0000 0								
31 30 29 28 27 26 25 24 23 22 21 Res ro				<u>19 1</u>		16 LP CO		14	13	12	11	<u>10</u>	9	8 LF ro/	с	6	5	4	3	2	1	0

Field	Bits	Туре	Description
Res	31:17	ro	Reserved
LPCO	16	ro/lh	Lost Packet Counter Overflow
			Note: LH = High Latching and cleared by writing 1
			$1_{\rm B}$, while lost packet counter overflowed. Cleared after read
LPC	15:0	ro/lh	Lost Packet Counter Increment the counter while packet discarded since there was no host receives descriptors available. Cleared after read.
			Note: LH = High Latching and cleared by writing 1

Serial Port Register

SPR_CSR9	Offset	Reset Value		
Serial Port Register	48 _H	0004 000E _H		
31 30 29 28 27 26 25 24 23	22 21 20 19 18 17 16 15 14 13 12 11 10 9	876543210		

	JI JU ZJ ZU ZI ZU ZJ Z4 ZJ ZZ ZI	20 19 10 17	1 10 15	14 13 12 11	10 3 0 7 0 3 4	5 2 1 0
ſ						
		MOMMM		SRSWRe SR		
	Res				Res	30 30 30 30
	ILES		D C s I	CCSSS	nes	
	ro	rw rw rw	wrwroi	rw rw ro rw	ro	ro rw rw rw

Field	Bits	Туре	Description		
Res	31:20	ro	Reserved		
MDI	19	rw	MII Management Data Input Specified read data from the external PHY	•	
MMC	18	rw	MII Management Control 0_B , Write operation to the external PHY 1_B , Read operation from the external PHY		
MDO	17	rw	MII Management Data Output Specified Write Data to the external PHY		



AN985B/BX

Registers and Descriptors Description

Field	Bits	Туре	Description	
MDC	16	rw	MII Management Clock 1 _B , MII Management Clock is a output reference clock to the external PHY	
Res	15	ro	Reserved	
SRC	14	rw	Serial EEPROM Read Control	
SWC	13	rw	Serial EEPROM Write Control	
Res	12	ro	Reserved	
SRS	11	rw	Serial EEPROM Select	
Res	10:4	ro	Reserved	
SDO	3	ro	Serial EEPROM Data Out This bit serially shifts data from the EEPROM to the AN985B/BX.	
SDI	2	rw	Serial EEPROM Data In This bit serially shifts data from the AN985B/BX to the EEPROM.	
SCLK	1	rw	Serial EEPROM Clock High/Low this bit to provide the clock signal for EEPROM.	
SCS	0	rw	Serial EEPROM Chip Select 1 _B , selects the serial EEPROM chip	

General-Purpose Timer

TMR_CSR11 General-Purpose Timer	Offset 58 _H		Reset Value 0000 0000 _H
31 30 29 28 27 26 25 24 23 22 21 20 Res	19 18 17 16 15 14 13 CO M	12 11 10 9 8 7 6 5 GTV	4 3 2 1 0
ro	rw	rw	

Field	Bits	Туре	Description
Res	31:17	ro	Reserved
СОМ	16	rw	$\begin{array}{l} \textbf{Continuous Operation Mode} \\ \textbf{1}_B & , \text{ sets the general-purpose timer in continuous operating mode} \end{array}$
GTV	15:0	rw	General-Purpose Timer Value Sets the counter value. This is a countdown counter with the cycle time of 204 μ s.

Wake-up Control/Status Register

WCSR_CSR13	Offset	Reset Value
Wake-up Control/Status Register	68 _H	0000 00?? _Н



AN985B/BX

	/PWPWPWP E 3E 4E 5E	Re	es Li Li Res WFMPLS RERECE Res RFMPLS
ro rw rw r	w rw rw rw	ro	rwrw ro rwrwrw ro rw1ow1ow1
Field	Bits	Туре	Description
Res	31	ro	Reserved
CRCT	30	rw	CRC-16 Type 0_B , Initial contents = 0000h 1_B , Initial contents = FFFFh
WP1E	29	rw	Wake-up Pattern n Matched Enable
WP2E	28	rw	n = 1 to 5
WP3E	27	rw	
WP4E	26	rw	
WP5E	25	rw	
Res	24:18	ro	Reserved
LinkOFF	17	rw	Link Off Detect Enable The AN985B/BX will set the LSC bit of CSR13 after it has detected that link status is from ON to OFF.
LinkON	16	rw	Link On Detect Enable The AN985B/BX will set the LSC bit of CSR13 after it has detected that link status is from OFF to ON.
Res	15:11	ro	Reserved
WFRE	10	rw	Wake-up Frame Received Enable The AN985B/BX will include the "Wake-up Frame Received" event into wake-up events. If this bit is set, AN985B/BX will assert PMES bit of PMR1 after AN985B/BX has received a matched wake-up frame.
MPRE	9	rw	Magic Packet Received Enable The AN985B/BX will include the "Magic Packet Received" event into wake-up events. If this bit is set, AN985B/BX will assert PMES bit of PMR1 after AN985B/BX has received a Magic packet.
LSCE	8	rw	Link Status Changed Enable The AN985B/BX will include the "Link Status Changed" event into wake- up events. If this bit is set, AN985B/BX will assert PMES bit of PMR1 after AN985B/BX has detected a link status changed event.
Res	7:3	ro	Reserved
WFR	2	rw1c	Wake-up Frame Received
			Note: rw1c: Read only and Write one cleared.
			 1_B , Indicates AN985B/BX has received a wake-up frame. It is cleared by write 1 or upon power-up reset. It is not affected by a hardware or software reset



Field	Bits	Туре	Description
MPR	1	rw1c	Magic Packet Received
			Note: rw1c: Read only and Write one cleared.
			1 _B , Indicates AN985B/BX has received a magic packet. It is cleared by write 1 or upon power-up reset. It is not affected by a hardware or software reset
LSC	0	rw1c	Link Status Changed
			Note: rw1c: Read only and Write one cleared.
			1 _B , Indicates AN985B/BX has detected a link status change event. It is cleared by write 1 or upon power-up reset. It is not affected by a hardware or software reset

CSR14, WPDR – Wake-up Pattern Data Register

All six wake-up patterns filtering information are programmed through WPDR register. The filtering information is as follows:

Offset	31-24	23-16	15-8	7-0					
0000h	Wake-up pattern 1 mask bits 31:0								
0004h	Wake-up pattern 1 mask bits 63:32								
0008h	Wake-up pattern 1 mask bits 95:64								
000ch	Wake-up patte	rn 1 mask bits 127:96							
0010h	CRC16 of patte	ern 1	Reserved	Wake-up pattern 1 offset					
0014h	Wake-up patte	rn 2 mask bits 31:0							
0018h	Wake-up patte	rn 2 mask bits 63:32							
001ch	Wake-up patte	rn 2 mask bits 95:64							
0020h	Wake-up patte	rn 2 mask bits 127:96							
0024h	CRC16 of patte	ern 2	Reserved	Wake-up pattern 2 offset					
0028h	Wake-up patte	rn 3 mask bits 31:0							
002ch	Wake-up patte	rn 3 mask bits 63:32							
0030h	Wake-up patte	rn 3 mask bits 95:64							
0034h	Wake-up patte	rn 3 mask bits 127:96							
0038h	CRC16 of patte	ern 3	Reserved	Wake-up pattern 3 offset					
003ch	Wake-up patte	rn 4 mask bits 31:0							
0040h	Wake-up patte	rn 4 mask bits 63:32							
0044h	Wake-up patte	rn 4 mask bits 95:64							
0048h	Wake-up patte	rn 4 mask bits 127:96							
004ch	CRC16 of patte	ern 4	Reserved	Wake-up pattern 4 offset					
0050h	Wake-up patte	rn 5 mask bits 31:0							
0054h	Wake-up pattern 5 mask bits 63:32								
0058h	Wake-up patte	rn 5 mask bits 95:64							
005ch	Wake-up pattern 5 mask bits 127:96								
0060h	CRC16 of patte	ern 5	Reserved	Wake-up pattern 5 offset					

1. CRC-16 polynomial: still pending



- 2. Offset value is from 0-255 (8-bit width).
- 3. To load the whole wake-up frame-filtering information, consecutive 25 long words write operation to CSR14 should be done.

Watchdog Timer

WTMR_CSR15	Offset	Reset Value
Watchdog Timer	78 _H	0000 0000 _H
31 30 29 28 27 26 25 24 23 22	21 20 19 18 17 16 15 14 13 12 11 10	9876543210

0		50	20	20	21	20	20	27	20	~~~	Z I	20	13	10	17	10	10	1-	10	12	 10	3	0	'	0	0	-	5	~		0
C	s	CB S	Rx S	Rx Re		1	1	1	1	1	1			1	R	es				T					1	RW R	RW D	Re s	JC LK	NJ	JB D
ଞୀ	6	b[ð	je [2]e1 6]h[0]									r	0										rw	rw	ro	rw	rw	rw

Field	Bits	Туре	Description
CS	31	ro/ee16	Clock Save Mode
		h[3]	0 _B , clock stuck at 0 when clock save mode enable
			1 _B , clock stuck at 1 when clock save mode enable
CBS	30	ro/ee16	CARDBUS Save Mode
		h[2]	1 _B , CARDBUS clock save mode enable
RxS	29	ro/ee16	Rx Save Mode
		h[1]	1 _B , RX save mode enable
RxRe	28	ro/ee16	Rx Clock Reverse Mode
		h[0]	1 _B , reverse (for NS HomePHY mode)
Res	27:6	ro	Reserved
RWR	5	rw	Receive Watchdog Release
			The time of release watchdog timer from last carrier deserted.
			0 _B , 24 bit-time
			1 _B , 48 bit-time
RWD	4	rw	Receive Watchdog Disable
			$0_{\rm B}$, If the receiving packet's length is longer than 2560 bytes the
			watchdog timer will be expired
			1 _B , disable the receive watchdog
Res	3	ro	Reserved
JCLK	2	rw	Jabber Clock
			0_B , cut off transmission after 2.6 ms (100 Mbit/s) or 26 ms (10 Mbit/s)
			1_B , cut off transmission after 2560 byte-time
NJ	1	rw	Non-Jabber
			0_B , if jabber expired re-enable transmit function after 42 ms
			(100 Mbit/s) or 420 ms (10 Mbit/s)
			1_{B} , immediately re-enable the transmit function after jabber expired
JBD	0	rw	Jabber Disable
			1 _B , disable transmit jabber function



Assistant CSR5 (Status Register 2)

ACSR5_CSR16		Offset	Reset Value
Assistant CSR5 (Status Registe		80 _H	0000 0000 _H
31 30 29 28 27 26 25 24 23 2 TE RE LC TD Re PF IS IS S IS S R ro/lmo/lmo/lmo/lh ro ro/lh	Res	16 15 14 13 12 11 10 9 AN AA I* I*	8 7 6 5 4 3 2 1 0 CSR5 ro

Field	Bits	Туре	Description
TEIS	31	ro/lh	Transmit Early Interrupt Status Transmit early interrupt status is set to 1 when Transmit early interrupt function is enabled (set bit 31 of CSR17 = 1) and the transmitted packet is moved completed from descriptors to TX-FIFO buffer. This bit is cleared by written with 1.
			Note: LH = High Latching and cleared by writing 1
REIS	30	ro/lh	Receive Early Interrupt Status Receive early interrupt status is set to 1 when Receive early interrupt function is enabled (set bit 30 of CSR17 = 1) and the received packet is fill up its first receive descriptor. This bit is cleared by written with 1.
			Note: LH = High Latching and cleared by writing 1
LCS	29	ro/lh	Status of Link Status Change
			Note: LH = High Latching and cleared by writing 1
TDIS	28	ro/lh	Transmit Deferred Interrupt Status
			Note: LH = High Latching and cleared by writing 1
Res	27	ro	Reserved
PFR	26	ro/lh	PAUSE Frame Received Interrupt Status
			Note: LH = High Latching and cleared by writing 1
			1 _B , indicates a PAUSE frame received when the PAUSE function is enabled
Res	25:17	ro	Reserved
ANISS	16	ro/lh	Added Normal Interrupt Status Summary
			Note: LH = High Latching and cleared by writing 1
			1 _B , any of the added normal interrupts happened
AAISS	15	ro/lh	Added Abnormal Interrupt Status Summary
			Note: LH = High Latching and cleared by writing 1
			1 _B , any of added abnormal interrupt happened
CSR5	14:0	ro	This bits are the same as CSR5
			You can access those status bits through either CSR5 or CSR16



Assistant CSR7 (Interrupt Enable Register 2)

ACSR7_CSR17	errupt Enable Register 2)	Offset	Reset Value
Assistant CSR7 (Int		84 _H	0000 0000 _H
31 30 29 28 27 26 TE RE LC TD Re PF IE IE IE IE s R* TW TW TW TW TO TW		17 16 15 14 13 12 ANAA I* IE	11 10 9 8 7 6 5 4 3 2 1 0 CSR7

Field	Bits	Туре	Description
TEIE	31	rw	Transmit Early Interrupt Enable
REIE	30	rw	Receive Early Interrupt Enable
LCIE	29	rw	Link Status Change Interrupt Enable
TDIE	28	rw	Transmit Deferred Interrupt Enable
Res	27	ro	Reserved
PFRIE	26	rw	PAUSE Frame Received Interrupt Enable
Res	25:17	ro	Reserved
ANISE	16	rw	Added Normal Interrupt Summary Enable11adds the interrupts of bit 30 and 31 of ACSR7 to the normalinterrupt summary (bit 16 of CSR5)
AAIE	15	rw	Added Abnormal Interrupt Summary Enable11adds the interrupt of bit 26, 28 and 29 of ACSR7 to the abnormal interrupt summary
CSR7	14:0	ro	This bits are the same as CSR7 You can access those status bits through either CSR7 or CSR16

Command Register

Bit 31 to Bit 16 Automatically recall from EEPROM

_	CSR18 nmand R	egi	ster										-	iset 8 _H												-		: Val 000	
	<u>30 29 28</u>	1	26 PM E*				<u>г</u>		20 CR			LW		15	14	T	T	11	10	9	8 PL	7 D3	6 RW	5 PA	4 RT	3	2	1 SI	0 AT
D3 CS	AUXCL	E*	E *	I	PS	3Ē	RF	·S	D	РМ	Μ	S		I	1	R	es	1			S	Α	Ρ	U*		DF	۲ ۲	NT	UR
rw	ro	rw	rw	rw	rw	rw	rv	v	rw	ro	rw	rw				r	o				rw	rw	rw	rw	rw	r١	N	rw	rw

Field	Bits	Туре	Description
D3CS	31	rw	D3cold Support, Mapped to CR48<31>



Field	Bits	Туре	Description
AUXCL	30:28	ro	Aux Current Should be 0.
PMEPS	27	rw	PMEP Select 0 _B , positive pulse 1 _B , negative pulse
PMEPE	26	rw	PMEP Pin Enable 0 _B , disable(for old board) 1 _B , enable
PCI	25	rw	PCI Pad 0 _B , apply CARDBUS Pad in CARDBUS Mode. No effect in PCI Mode 1 _B , apply PCI Pad in CARDBUS Mode(for twinhead notebook)
PS	24	rw	 PMES Sticky 0_B , pmez auto de-asserted: pmez will be disasserted by power up after wakeup event trigger. 1_B , pmez sticky: Vcc_detect has no impact to pmez disasserts
4_3L	23	rw	4_3LED 0 _B , 3 LED scheme 1 _B , 4 LED scheme
RFS	22:21	rw	Receive FIFO Size Control 00_B , reserved 01_B , reserved 10_B , 2K 11_B , 1K
CRD	20	rw	Clock Run (clk-run pin) Disable 1 _B , disables the function of clock run supports to CARDBUS
PM	19	ro	Power Management Enables the AN985B/BX whether to activate the Power Management abilities. When this bit is set into "0" the AN985B/BX will set the Cap_Ptr register to zero, indicating no CARDBUS compliant power management capabilities.The value of this bit will be mapped to NC-bit 20 of CR1.In CARDBUS Power Management mode, the Wake-up events include "Wake-up Frame Received", "Magic Packet Received" and "Link Status Changed" depends on the CSR13 settings.
APM	18	rw	APM Mode This bit is effective when PM (csr18 [19]) = 1.
LWS	17	rw	Should be 0
Res	16:9	ro	Reserved
PLS	8	rw	PMEP Pulse Length Select 0 _B , long pulse 50ms 1 _B , short pulse 100us for test purpose
D3A	7	rw	D3_cold APM Mode Enable PMEZ can be asserted without the impact of PME_EN
RWP	6	rw	Reset Wake-up Pattern Data Register Pointer0, Normal1, Reset



Field	Bits	Туре	Description
PAUSE	5	rw	$\begin{array}{c c} \textbf{PAUSE Function Control} \\ To disable or enable the PAUSE function for flow control. The default value of PAUSE is decided by the result of Auto-Negotiation. Driver can force to enable or disable it after the Auto-Negotiation completed. \\ 0_{B} , PAUSE function is disabled \\ 1_{B} , PAUSE function is enabled \end{array}$
RTE	4	rw	 Receive Threshold Enable 0_B , disable the receive FIFO threshold selection in bit 3~2 of this register, the receive threshold is set to 64-byte. 1_B , the receive FIFO threshold is enabled
DRT	3:2	rw	Drain Receive Threshold 00_B , 32 bytes (8 DW) 01_B , 64 bytes (16 DW) 10_B , store-and -forward 11_B , reserved
SINT	1	rw	Software Interrupt
ATUR	0	rw	Automatically Transmit-Underrun Recovery11. enable automatically transmit-underrun recovery



CARDBUS Bus Performance Counter

CARDBUSC_CSR19 CARDBUS Bus Performance Counter	Offset 8C _H	Reset Value 0000 0000 _H					
31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 CLKCNT	16 15 14 13 12 11 10 9 8 7 6 5 4 Res DWC						
ro*	ro ro	*					

Field	Bits	Туре	Description
CLKCNT	31:16	ro*	Clock Count The number of CARDBUS clock from read request asserted to access completed. This CARDBUS clock number is accumulated all the read command cycles from last CSR19 read to current CSR19 read.
Res	15:8	ro	Note: ro*: Read only and cleared by reading Reserved
DWCNT	7:0	ro ro*	Double Word Count
DWCNT	7.0	10	The number of double word accessed by the last bus master. This double word number is accumulated all the bus master data transactions from last CSR19 read to current CSR19 read.
			Note: ro*: Read only and cleared by reading

ro = Read only and cleared by reading

Power Management Command and Status

(The same register value mapping to CR49-PMR1)

PMCSR_CSR20	Offset	Reset Value
Power Management Command and Status	90 _H	0000 0000 _H

	Re	es		PM ES	DSCA L	DSEL	PM E*	Res	PWRS
					1				
	rc)		ro	ro	ro	ro	ro	ro
Field	Bits	Туре	Description						

Field	Bits	Туре	Description
Res	31:16	ro	Reserved



Field	Bits	Туре	Description
PMES	15	ro	PME_Status This bit is set when the AN985B/BX would normally assert the PME# signal for wake-up event, this bit is independent of the state of the PME-En bit. Writing a "1" to this bit will clear it and cause the AN985B/BX to stop asserting a PME# (if enabled). Writing a "0" has no effect. Since the AN985B/BX doesn't supports PME# from D3cold, this bit is defaulted to "0".
DSCAL	14:13	ro	Data_Scale Indicates the scaling factor to be used when interpreting the value of the Data register. This field is required for any function that implements the Data register. Otherwise, it's optional.The AN985B/BX doesn't support Data register and Data_Scale.
DSEL	12:9	ro	Data_SelectThis four bit field is used to select which data is to be reported through theData register and Data_Scale field. This field is required for any functionthat implements the Data register. The AN985B/BX doesn't supportData_Select.
PME_En	8	ro	PME_En "1" enables the AN985B/BX to assert PME#. When "0" disables the PME# assertion.This bit defaults to "0" if the function does not support PME# generation from D3cold.
Res	7:2	ro	Reserved
PWRS	1:0	ro	PowerStateThis two bit field is used both to determine the current power state of theAN985B/BX and to set the AN985B/BX into a new power state. Thedefinition of this field is given below. $00_B - D0$ $01_B - D1$ $10_B - D2$ $11_B - D3hot$ If software attempts to write an unsupported, optional state to this field, the write operation must complete normally on the bus, however the data is discarded a no state change occurs.



Current Working Transmit Descriptor Pointer

WTDP_CSR21 Current Working Transmit Descriptor Pointer	Offset 94 _H									set xxx		
31 30 29 28 27 26 25 24 23 22 21 20 19 18	17 16 15 14	4 13 12	11 10	9	8	7 (6 5	4	3	2	1	0
	WTDP											
			<u> </u>					1	I	L 1		
	ro											

Field	Bits	Туре	Description
WTDP	31:0	ro	Working Transmit Descriptor Pointer
			The current working transmit descriptor pointer for driver's double- checking or other special purpose.

Current Working Receive Descriptor Pointer

WRDP_CSR22 Current Working Receive Descriptor Pointer	Offset 98 _H	Reset Value xxxx xxxx _H
31 30 29 28 27 26 25 24 23 22 21 20 19 18 13	7 16 15 14 13 12 11 10 9 8 7 6 5 4	3 2 1 0
	WRDP	
	ro	

Field	Bits	Туре	Description
WRDP	31:0	ro	Working Receive Descriptor Pointer
			The current working receive descriptor pointer for driver's double-
			checking or other special purpose.



Transmit Burst Count/Time-out

TXBR_CSR23 Transmit Burst Count/Time-out	-	fset C _H	Reset Value 0000 0000 _H					
31 30 29 28 27 26 25 24 23 22 21	20 19 18 17 16	15 14 13 12	11 10 9 8 7 6 5 4	3 2 1 0				
Res	TBCNT	Res	тто					
ro	rw		rw					

Field	Bits	Туре	Description
Res	31:21	ro	Reserved
TBCNT	20:16	rw	Transmit Burst Count After this number of consecutive successful transmit, transmit completed interrupt will be generated. Continuously do this function if no reset.
ТТО	11:0	rw	Transmit Time-Out = (deferred time + back-off time) When the TDIE (bit28 of ACSR7) is set, the timer is decreased in unit of 2.56 μ s (100M) or 25.6 μ s (10M). If the timer expires before another packet transmit begin, then the TDIE interrupt will be generated.

Flash ROM (also the boot ROM) Port

FROM_CSR24	Offset	Reset Value
Flash ROM (also the boot ROM) Port	A0 _H	8000 0000 _H

31 3	30 29 28	3 27 2	6 25	24	23	22 2	21 20) 19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
BO N	Res	REW N N	E I	1		1	1	1	I	AD	DR					I	1 1	1			I	I	DA	TA	I		
					L 1			1	1			L				1	I I					I	1	L	I		
rw	ro	rw rv	v							r	w												r	W			

Field	Bits	Туре	Description
BON	31	rw	Bra16_on
			This bit is no effective when 3_LED scheme applied.
			Driver needs to program this bit when 4_LED applied especially when
			boot rom read.
			0 _B , bra[16]=fd/col LED path
			1 _B , no effect to bar[16]
Res	30:28	ro	Reserved
REN	27	rw	Read Enable
			Clear if read data is ready in DATA, bit7-0 of FROM.
WEN	26	rw	Write Enable
			Cleared if write completed.



Field	Bits	Туре	Description
ADDR	25:8	rw	Flash ROM Address
DATA	7:0	rw	Read/Write Data of Flash ROM

Physical Address Register 0

Automatically recall from EEPROM

PAR0_CSR25	Offset	Reset Value
Physical Address Register 0	A4 _H	xxxx xxxx _H

31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

PAB3	PAB2	PAB1	PAB0					
rw	rw	rw	rw					

Field	Bits	Туре	Description
PAB3	31:24	rw	Physical Address Byte n
PAB2	23:16	rw	n = 0 to 3
PAB1	15:8	rw	
PAB0	7:0	rw	

Physical Address Register 1

Automatically recall from EEPROM

PAR1_CSR26	Offset	Reset Value
Physical Address Register 1	A8 _H	xxxx xxxx _H

|--|

Res	Res	PAB5	PAB4	
ro	ro	rw	rw	

Field	Bits	Туре	Description
Res	31:24	ro	Reserved
Res	23:16	ro	Reserved
PAB5	15:8	rw	Physical Address Byte 5
PAB4	7:0	rw	Physical Address Byte 4

For example, physical address = 00-00-e8-11-22-33

PAR0 = 11 e8 00 00

PAR1 = xx xx 33 22

PAR0 and PAR1 are readable, but can be written only if the receive state is in stopped (CSR5 bit19-17 = 000).

Data Sheet



Multicast Address Register 0

MAR0_CS Multicast	Offset AC _H													Reset Value 0000 0000 _H											
31 30 29	28 27 2	26 25	23 22	3 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5											4	3	2	1	0						
	MAB3				MAB2									M	4 B1						MA	AB0			
	rw		<u> </u>			I	I		1	w				I		r	w	1							
Field	В	Туре																							
MAB3	rw		Multicast Address Byte n																						

IVIADO	31.24	IW	Multicast Address Byte n
MAB2	23:16	rw	n = 0 to 3
MAB1	15:8	rw	_
MAB0	7:0	rw	



MAB5

MAB4

Registers and Descriptors Description

Multicast Address Register 1

15:8

7:0

rw

rw

MAR1_CSR28 Multicast Address Register 1									Offset B0 _H																		Va 000	
31 30 29 2	23	22	21	20	19	18	17	16	15	14	13	12	2 11	10	9	8	7	6	5	4	3	2	1	0				
MAB7						I	I	MA	\B6	1				1		M	AB5		I	I			1	MA	B 4	I	I	
	rw	1	1	1			1	r	w		1		1	1	1	1	rw	1		1	1	1	1	ŗ	w	1	1	
Field		Bits			T	Type Description																						
MAB7 31:24 rv					V		Multicast Address Byte 7 (hash table 63:56)												-									
MAB6 23:16 rw					V		Multicast Address Byte 6 (hash table 55:48)																					

Multicast Address Byte 5 (hash table 47:40)

Multicast Address Byte 4 (hash table 39:32)

MAR0 and MAR1 are readable, but can be written only if the receive state is in stopped (CSR5 bit19-17 = 000)



Unicast Address Register 0

UAR0_CSR_29	Off		Reset Value
Unicast Address Register	0 B4		0000 0000 _H
31 30 29 28 27 26 25 24 UAB3	23 22 21 20 19 18 17 16 UAB2 rw	15 14 13 12 11 10 9 3 UAB1 rw	3 7 6 5 4 3 2 1 0 UAB0

Field	Bits	Туре	Description
UAB3	31:24	rw	Unicast Address Byte 3 (hash table 31:24)
UAB2	23:16	rw	Unicast Address Byte 2 (hash table 23:16)
UAB1	15:8	rw	Unicast Address Byte 1 (hash table 15:8)
UAB0	7:0	rw	Unicast Address Byte 0 (hash table 7:0)

Unicast Address Register 1

UAR1_CSR_30	Offset	Reset Value
Unicast Address Register 1	B8 _H	0000 0000 _H
31 30 29 28 27 26 25 24 23 22 21	20 19 18 17 16 15 14 13 12 11 10	9876543210

UAB7	UAB6	UAB5	UAB4							
rw		rw								

Field	Bits	Туре	Description
UAB7	31:24	rw	Unicast Address Byte 7 (hash table 63:56)
UAB6	23:16	rw	Unicast Address Byte 6 (hash table 55:48)
UAB5	15:8	rw	Unicast Address Byte 5 (hash table 47:40)
UAB4	7:0	rw	Unicast Address Byte 4 (hash table 39:32)

Unicast64 Algorithm

The algorithm is the same with multicast64.

Operation Mode Register

OMR	Offset	Reset Value
Operation Mode Register	FC _H	0000 0007 _H



31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
SP E*	FD	LI NK	Re s	ET	E2 SL		Res												CMode		de										
								1	I	L	1		I		I	I	1	I	I	I	I I			I	I	I		I			
ro	ro	ro	ro	rw	rw												ro													rw	

Field	Bits	Туре	Description	
SPEED	31	ro	Network Speed Status	
			0 _B , 10M	
			1 _B , 100M	
FD	30	ro	Full/Half Duplex Status	
			0 _B , Half duplex	
			1 _B , Full duplex	
LINK	29	ro	Network Link Status	
			0 _B , Link off	
			1 _B , Link OK	
Res	28	ro	Reserved	
ET	27	rw	ET	
			0 _B , 9346	
			1 _B , 9366	
E2SL	26	rw	E2prom_Soft_Load	
			Write 1 to reload e2prom	
Res	25:3	ro	Reserved	
CMode	2:0	rw	Chip Mode	
			These three bits are used to configure AN985B/BX's chip mode:	
			111 _B , normal mode	
			110 _B , monitor mode	
			100 _B , HOME PNA mode	
			001 _B , phy only mode	
			$101_{\rm B}$, HP94000tester mode(vaux, vcc_detect will be internal forced to	
			1 _B , and muxed with poweron_reset input and ssram_rdy)	

Function Event Register

FER Function Event Register	Offset 100 _H	Reset Value 0000 0000 _H
<u>31 30 29 28 27 26 25 24 23 22 21 20 19 18 17</u>	7 16 15 14 13 12 11 10 9 8 7 6 5	GW
Res	Ev Res	
ro	rlh/w1c ro	rw1c ro

Field	Bits	Туре	Description
Res	31:16	ro	Bits[31:16] are reserved in the CARDBUS Specification



Field	Bits	Туре	Description
InEv	15	rlh/w1c	Interrupt Event This bit is used for as the interrupt bit. It is set when the Ethernet interrupt source is set,regardless of the mask value. It is cleared when the OS writes 1_B to the field and the interrupt source has been serviced. Writing 0_B to the field has no effect.
Res	14:5	ro	Bits[14:5] are reserved in the CARDBUS Specification
GWUE	4	rw1c	General Wake-up Event This bit is used for general wake-up. It is set when the Ethernet wake-up source is set, regardless of the mask value. Writing 1_B to the field clears this bit and the PME status bit in the PMCSR. Writing 0_B to the field has no effect. Note that writing 1_B to the PME status bit in the PMCSR has the same effect.
			Note: rw1c: Read only and Write one cleared.
Res	3:0	ro	Bits[3:0] are reserved in the CARDBUS Specification

Function Event Mask Register

FEMR	Offset	Reset Value
Function Event Mask Register	104 _H	0000 8000 _H

31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

Res	In WU Ev M		GW UE Res
ro	rw rw	ro	ro ro

Field	Bits	Туре	Description
Res	31:16	ro	Bits[31:16] are reserved in the CARDBUS Specification
InEv	15	rw	Interrupt Event This bit is the interrupt mask. When the bit equals 0_{B} , it masks the Ethernet function CSTSCHG signal bit has no effect on the Function Event Register. This bit is dependent on bit 4 of this register.
WUM	14	rw	Wake-Up MaskWhen the bit equals 0_B , it masks the Ethernet function INTA# line bus hasno effect on the Function Event Register. The interrupt mask
Res	13:5	ro	Bits[14:5] are reserved in the CARDBUS Specification
GWUE	4	ro	General Wake-up Event This bit is the general wake-up mask. When the bit equals 0 _B , it masks Ethernet function wake-up events towards the CSTSCHG signal. It has no effect on the Function Event register. The AN985B/BX can assert the CSTSCHG signal in the following configuration of masked bits:wake-up bit AND general wake-up bit, or PME Enable bit in the PMCSR register only.
Res	3:0	ro	Bits[3:0] are reserved in the CARDBUS Specification



Function Present State Register

FPSR Function Present State Register			Reset Value 0000 0000 _H
31 30 29 28 27 26 25 24 23 22 2 Res	ln Ev	Res	GW UE Res
ro	ro	ro	ro ro

Field	Bits	Туре	Description
Res	31:16	ro	Bits[31:16] are reserved in the CARDBUS Specification
InEv	15	ro	Interrupt Event This bit is used for interrupts. It reflects the current state of the Ethernet source of the interrupt regardless of the mask value. It is set when the Ethernet function has pending interrupt and cleared when the software driver acknowledges all active interrups through the SCB Command Word.
Res	14:5	ro	Bits[14:5] are reserved in the CARDBUS Specification
GWUE	4	ro	General Wake-up Event This bit is used for general wake-up. It reflects the current state of the Ethernet source of CSTSCHG. It is a logical OR reseult of the gated three most significant bits in the PMDR: Link Status change bit is gated by the Link Status Change Wake Enable bit in the Configuration command. The Magic Packet bit is gated by the Magic Packet Wake-up disable bit in the Configuration command. The Interesting Packet bit is gated by the programmable filter command.
Res	3:0	ro	Bits[3:0] are reserved in the CARDBUS Specification

Function Force Event Register

FFER Function Force Event Register	Offset 10С _н	Reset Value 0000 0000 _H
31 30 29 28 27 26 25 24 23 22 21 20 19 18 17	<u>16 15 14 13 12 11 10 9 8 7 6 5</u>	4 3 2 1 0
Res	In F* Res	GW UF ^{Res}
ro	w ro	w ro

Field	Bits	Туре	Description
Res	31:16	ro	Bits[31:16] are reserved in the CARDBUS Specification



Field	Bits	Туре	Description
InFor	15	w	Interrupt Force This bit is used for interrupts. Writing 1_B in the field will set the interrupt bit in the Function Event register. If the INTA# pin is not masked, then it will also be actived. Writing 0_B to the field has no effect.
Res	14:5	ro	Bits[14:5] are reserved in the CARDBUS Specification
GWUF	4	w	General Wake-up Force This bit is used for general wake-up. Writing 1_B in the field will set the CSTSCHG bit in the Function Event register. If the CSTSCHG pin is not masked, then it will also be actived. Writing 0_B to the field has no effect
Res	3:0	ro	Bits[3:0] are reserved in the CARDBUS Specification



8.3 PHY Registers

Table 14 Registers Address Space

Module	Base Address	End Address	Note
PHY	0000 0000 _H	0000 0006 _H	

Table 15Registers Overview

Register Short Name	Register Long Name	Offset Address	Page Number	
R0	Register 0(MII Control)	0 _H	83	
R1	Register 1(Status)	1 _H	85	
R2	Register 2	2 _H	87	
R3	Register 3	3 _H	87	
R4	Register 4	4 _H	88	
R5	Register 5	5 _H	89	
R6	Register 6	6 _H	90	

The register is addressed wordwise.

Standard abbreviations:

Table 16 Registers Access Types

Mode	Symbol	Description Hardware (HW)	Description Software (SW)
read/write	rw	Register is used as input for the HW	Register is read and writable by SW
read	r	Register is written by HW (register between input and output -> one cycle delay)	Value written by software is ignored by hardware; that is, software may write any value to this field without affecting hardware behavior (= Target for development.)
write	w		Register is writable by SW
read/write hardware affected	rwh	Register can be modified by HW	Register can be modified by HW, but the priority SW versus HW has to be specified
	rwv		
Read only	ro	Register is set by HW (register between input and output -> one cycle delay)	SW can only read this register
Read virtual	rv	Physically, there is no new register, the input of the signal is connected directly to the address multiplexer.	SW can only read this register
Latch high, self clearing	lhsc	Latch high signal at high level, clear on read	SW can read the register
Latch low, self clearing	llsc	Latch high signal at low-level, clear on read	SW can read the register
Latch high, mask clearing	lhmk	Latch high signal at high level, register cleared with written mask	SW can read the register, with write mask the register can be cleared (1 clears)



Mode	Symbol	Description Hardware (HW)	Description Software (SW)
Latch low, mask clearing	llmk	Latch high signal at low-level, register cleared on read	SW can read the register, with write mask the register can be cleared (1 clears)
Interrupt high, self clearing	ihsc	Differentiate the input signal (low- >high) register cleared on read	SW can read the register
Interrupt low, self clearing	ilsc	Differentiate the input signal (high- >low) register cleared on read	SW can read the register
Interrupt high, mask clearing	ihmk	Differentiate the input signal (high- >low) register cleared with written mask	SW can read the register, with write mask the register can be cleared
Interrupt low, mask clearing	ilmk	Differentiate the input signal (low- >high) register cleared with written mask	SW can read the register, with write mask the register can be cleared
Interrupt enable register	ien	Enables the interrupt source for interrupt generation	SW can read and write this register
latch_on_reset	lor	rw register, value is latched after first clock cycle after reset	Register is read and writable by SW
Read/write self clearing	rwsc	Register is used as input for the hw, the register will be cleared due to a HW mechanism.	Writing to the register generates a strobe signal for the HW (1 pdi clock cycle) Register is read and writable by SW.

Table 16Registers Access Types (cont'd)

8.3.1 PHY Transceiver Registers Descriptions

Register 0

MII Control

R0 Regist	er 0(M	(MII Control) 0 _H									Reset	: Value 1000 _H			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
RESE T	LOOP	SPEE D	ANE	PD	IS	RAN	DM	СТ		1	1	Res	1	1	
rwsc	rw	rw	rw	rw	rw	rwsc	rw	ro				ro			<u> </u>

Field	Bits	Туре	Description
RESET	15	rwsc	Reset 0 _B , normal operation 1 _B , PHY Reset
LOOP	14	rw	Loopback 0 _B , disable loopback 1 _B , enable loopback



Registers and Descriptors Description

Field	Bits	Туре	Description
SPEED	13	rw	Speed Selection0B, 10 Mbit/s1B, 100 Mbit/s
ANE	12	rw	Autonegotiation Enable 0 _B , disable autoneg 1 _B , enable autoneg
PD	11	rw	Power Down 0 _B , normal operation 1 _B , Power Down
IS	10	rw	Isolate 0 _B , normal operation 1 _B , isolate PHY from MII
RAN	9	rwsc	Restart Autonegotiation 1 _B , Restart Autoneg
DM	8	rw	Duplex Mode 0 _B , half duplex 1 _B , full duplex
СТ	7	ro	Collision Test Not implemented
Res	6:0	ro	Reserved

SC: Self Clearing

Reset: Reset this port only. This will cause the following:

- 1. Restart the autonegotiation process.
- 2. Reset the registers to their default values. Note that this does not affect registers 20, 22, 30 or 31. These registers are not reset by this bit to allow test configurations to be written and then not affected by resetting the port.
- Note: No reset is performed to analogue sections of the port. There is also no physical reset to any internal clock synthesizers or the local clock recovery oscillator which will continue to run throughout the reset period. However since the port is restarted and autoneg re-run the process of locking the frequency of the local oscillator (slave) to the reference oscillator (master) will be repeated as it is at the start of any link initialization process.

Loopback: Loop back of transmit data to receive via a path as close to the wire as possible. When set inhibits actual transmission on the wire.

Speed selection: Forces speed of Phy only when autonegotiation is disabled. The default state of this bit will be determined by a power-up configuration pin in this case. Otherwise it defaults to 1.

Auto-neg enable Defaults to pin programmed value. When cleared allows forcing of speed and duplex settings. When set (after being cleared) causes re-start of autoneg process. Pin programming at power-up allows it to come up disabled and for software to write the desired capability before allowing the first negotiation to commence.

Restart Negotiation: only has effect when autonegotiating. Restarts state machine.

Power down: Has no effect in this device. Test mode power down modes may be implemented in other specific modules.

Isolate: Puts RMII receive signals into high impedance state and ignores transmit signals.

Duplex mode: When bit12 is cleared (i.e. autoneg disabled), this bit forces full duplex (bit = 1) or half duplex (bit = 0).



Collision test: Always 0 because collision signal is not implemented.

Register 1

Status

R1 Regist	er 1(St	atus)					Off 1	set н						Reset	Value 7849 _H
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
100B T4	100B FD	100B HD	10FD	10HD	100B T2FD	100B T2HD	Re	es	MFPS	AC	RF	AA	LS	JD	EC
ro	ro	ro	ro	ro	ro	ro	r	0	ro	ro	ro, lh	ro	ro, ll	ro, lh	ro

Field	Bits	Туре	Description
100BT4	15	ro	100 BASE T4
			Not supported
100BFD	14	ro	100 BASE-X Full Duplex
			0 _B , PHY is not 100BASE-X full duplex capable
			1_B , PHY is 100BASE-X full duplex capable
100BHD	13	ro	100BASE-X Half Duplex
			0 _B , PHY is not 100BASE-X half duplex capable
			1 _B , PHY is 100BASE-X half duplex capable
10FD	12	ro	10 Mbit/s Full Duplex
			0 _B , PHY is not 10 Mbit/s/s Full duplex capable
			1 _B , PHY is 10 Mbit/s/s Full duplex capable
10HD	11	ro	10 Mbit/s Half Duplex
			0 _B , PHY is not 10 Mbit/s/s Half duplex capable
			1 _B , PHY is 10 Mbit/s/s Half duplex capable
100BT2FD	10	ro	100BASE-T2 Full Duplex
			Not supported
100BT2HD	9	ro	100BASE-T2 Half Duplex
			Not supported
Res	8:7	ro	Reserved
MFPS	6	ro	MF Preamble Suppression
			$0_{ m B}$, PHY cannot accept management frames with preamble
			suppression
			$1_{\rm B}$, PHY can accept management frames with preamble suppression
AC	5	ro	Autoneg Complete
			0 _B , autoneg incomplete
			1 _B , autoneg completed
RF	4	ro, lh	Remote Fault
			Note: Ih: Latch High
			0 _B , no remote fault detected
			1 _B , remote fault detected



Field	Bits	Туре	Description
AA	3	ro	Autoneg Ability
			0 _B , PHY cannot auto-negotiate
			1 _B , PHY can auto-negotiate
LS	2	ro, ll	Link Status
			Note: Ih: Latch Low
			0 _B , link is down
			1 _B , link is up
JD	1	ro, lh	Jabber Detect
			Only used in 10Base-T mode. Reads as 0 in 100Base-TX mode.
			Note: Ih: Latch High
			1 _B , jabber condition detected
EC	0	ro	Extended Capability
			0 _B , basic register set capabilities only
			1 _B , extended register capabilities

Register 2 and 3

Each PHY has an unique identifier, which is assigned to the device.

The identifier contains a total of 32 bits, which consists of the following: 22 bits of a 24bit organizationally unique identifier (OUI) for the manufacturer; a 6-bit manufacturer's model number; a 4-bit manufacturer's revision number. For an explanation of how the OUI maps to the register, please refer to IEEE 802-1990 clause 5.1.

There is physically only one of each of these registers for all six network(MDI) ports. When reading this register the port number is ignored.



Register 2

	R2 Offset Register 2 2 _H											Value 001D _H				
Г	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		1	I	T	1	1	1	PH	Y_ID	I	I	1	1	1	1	1
-		•				•		r	o							

Field	Bits	Туре	Description
PHY_ID	15:0	ro	PHY_ID[31-16] 3Com OUI (bits 3-18)

Register 3

R3 Regist	er 3					Offset 3 _H					Reset Value 2411 _H					
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
	PHY_ID0						PHY_ID1						PHY_ID2			
ro					1	1	r	0	1	1		r	o			

Field	Bits	Туре	Description
PHY_ID0	15:10	ro	PHY_ID[15-10]
			3Com OUI (bits 19-24)
PHY_ID1	9:4	ro	PHY_ID[9-4]
			Manufacturer's Model Number (bits 5-0)
PHY_ID2	3:0	ro	PHY_ID[3-0]
			Revision Number (bits 3-0); Register 3, bit 0 is LS bit of PHY Identifier

This uses the OUI of Infineon-ADMtek, device type of 1 and rev 0



Register 4

R4 Regist	ter 4							fset I _H						Reset	t Value 0001 _H
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
NP	Res	RF	N	1	PAUS E	NI2	100B FD	100B HD	10BF D	10BH D		1	SF	1	
rw	ro	rw	ro	C	rw	ro	rw	rw	rw	rw			ro		
Field		Bits		Туре	e De	script	ion								
NP		15		rw	Nе 0 _в 1 _в					ext Pag Page	e				
Res		14		ro	Re	serve	d								
RF		13		rw	Re 0 _в 1 _в		fault d			to link p	partner				
NI1		12:1	12:11 ro Not Implemented Technology ability bits A7-A6												
PAUS	E	10		rw		i use chnolo	gy abili	ty bit A	5						
NI2		9		ro		-	emente gy abili		4						
100BF	D	8		rw		chnolo , Ur	E-TX Fu gy abili nit is no nit is ca	ty bit A t capab	3 ole of Fi	ull Dupl	ex				
100BH	ID	7		rw		chnolo , Ur	E-TX H a gy abili nit is no nit is ca	ty bit A t capab	2 ole of H	alf Dupl Duplex	ex 100)BASE	-TX		
10BFD)	6		rw		chnolo , Ur		ty bit A t capat	1 ble of Fi	ull Dupl)uplex 1			-		
10BHE)	5		rw	10	BASE- chnolo , Ur	-T Half gy abili nit is no	Duple ty bit A t capab	(0 ble of H	i alf Dupl Duplex 2	ex 10E	BASE-1	г		
SF		4:0		ro	Se Ide	lector	Field	·		ng sent.			ly one \	alue is	,



Register 5

The register is used to view the advertised capabilities of the link partner once autonegotiation is complete. The contents of this register should not be relied upon unless register 1 bit 5 is set (autoneg complete). After negotiation this register should contain a copy of the link partner's register 4. All bits are therefore defined in the same way as for register 4.

All bits are read only.

This register is used for Base Page code word only.

Base Page Register Format

	R5 Offset Register 5 5 _H													Value 0000 _H		
_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	NP	АСК	RF				٦	ΓA	'					SF		
L	ro	ro	ro	I	1	II		ro		1			1	ro	I	

Field	Bits	Туре	Description
NP	15	ro	Next Page 0_B , Base Page is requested 1_B , Link Partner is requesting Next Page function
ACK	14	ro	Acknowledge Link Partner acknowledgement bit
RF	13	ro	Remote Fault Link Partner is indicating a fault
TA	12:5	ro	Technology Ability Link Partner technology ability field.
SF	4:0	ro	Selector Field Link Partner selector field



Register 6

R6OffsetRegister 66 _H												Reset	Value 0004 _H		
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
					Res			1		1	PDF	LPNP	NP	PR	LPAA
	_	1	1		ro	1	1	L	1	1	ro, lh	ro	ro	ro, lh	ro

Field	Bits	Туре	Description
Res	15:5	ro	Reserved
PDF	4	ro, lh	Parallel Detection Fault
			Note: Ih: Latch Hight
			0 _B , No fault detected
			1 _B , Local Device Parallel Detection Fault
LPNP	3	ro	Link Partner Next Page Able
			0 _B , Link Partner is not Next Page Able
			1 _B , Link Partner is Next Page Able
NP	2	ro	Next Page Able
			0 _B , Local device is not Next Page Able
			1 _B , Local device is Next Page Able
PR	1	ro, lh	Page Received
			Note: Ih: Latch Hight
			0 _B , A New Page has not been received
			1 _B , A New Page has been received
LPAA	0	ro	Link Partner Autonegotiation Able
			$0_{\rm B}$, Link Partner is not Autonegotiation able
			1 _B , Link Partner is Autonegotiation able



LH: Latch High

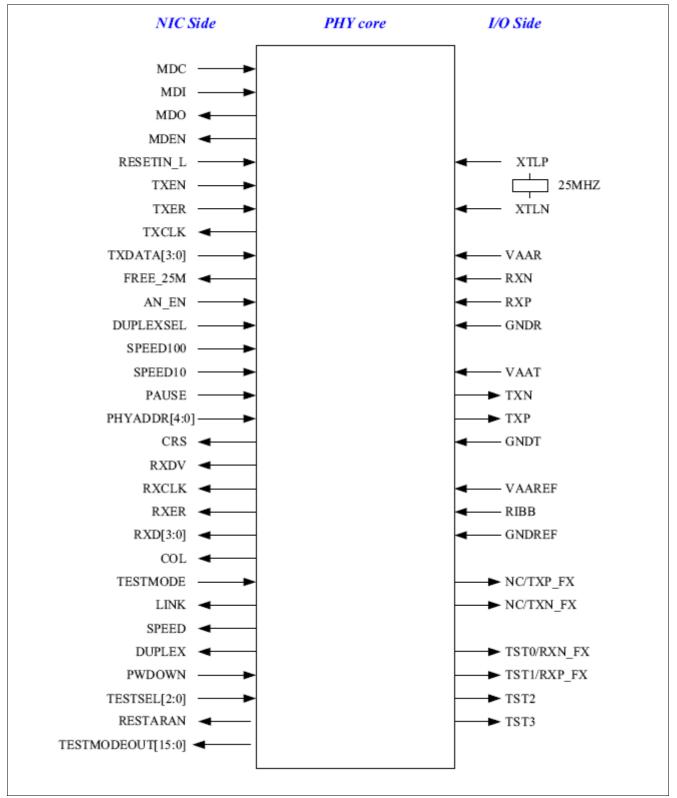


Figure 15 NIC, PHY, and I/O interconnection



Registers and Descriptors Description

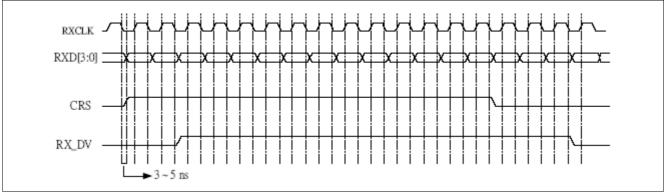


Figure 16 Timing



8.4 Descriptors and Buffer Management

Table 17 Registers Overview

Register Short Name	Register Long Name	Offset Address	Page Number
RDES0	RDES0	00 _H	94
RDES1	RDES1	04 _H	97
RDES2	RDES2	08 _H	97
RDES3	RDES3	0Ch _H	97
TDES0	TDES0	00 _H	98
TDES1	TDES1	04 _H	99
TDES2	TDES2	08 _H	100
TDES3	TDES3	0Ch _H	100

The register is addressed wordwise.

Standard abbreviations:

Mode	Symbol	Description Hardware (HW)	Description Software (SW)
read/write	rw	Register is used as input for the HW	Register is read and writable by SW
read	r	Register is written by HW (register between input and output -> one cycle delay)	Value written by software is ignored by hardware; that is, software may write any value to this field without affecting hardware behavior (= Target for development.)
write	w		Register is writable by SW
read/write hardware affected	rwh	Register can be modified by HW	Register can be modified by HW, but the priority SW versus HW has to be specified
	rwv		
Read only	ro	Register is set by HW (register between input and output -> one cycle delay)	SW can only read this register
Read virtual	rv	Physically, there is no new register, the input of the signal is connected directly to the address multiplexer.	SW can only read this register
Latch high, self clearing	lhsc	Latch high signal at high level, clear on read	SW can read the register
Latch low, self clearing	llsc	Latch high signal at low-level, clear on read	SW can read the register
Latch high, mask clearing	lhmk	Latch high signal at high level, register cleared with written mask	SW can read the register, with write mask the register can be cleared (1 clears)
Latch low, mask clearing	llmk	Latch high signal at low-level, register cleared on read	SW can read the register, with write mask the register can be cleared (1 clears)

Table 18 Registers Access Types



Mode	Symbol	Description Hardware (HW)	Description Software (SW)
Interrupt high, self clearing	ihsc	Differentiate the input signal (low- >high) register cleared on read	SW can read the register
Interrupt low, self clearing	ilsc	Differentiate the input signal (high- >low) register cleared on read	SW can read the register
Interrupt high, mask clearing	ihmk	Differentiate the input signal (high- >low) register cleared with written mask	SW can read the register, with write mask the register can be cleared
Interrupt low, mask clearing	ilmk	Differentiate the input signal (low- >high) register cleared with written mask	SW can read the register, with write mask the register can be cleared
Interrupt enable register	ien	Enables the interrupt source for interrupt generation	SW can read and write this register
latch_on_reset	lor	rw register, value is latched after first clock cycle after reset	Register is read and writable by SW
Read/write self clearing	rwsc	Register is used as input for the hw, the register will be cleared due to a HW mechanism.	Writing to the register generates a strobe signal for the HW (1 pdi clock cycle) Register is read and writable by SW.

Table 18Registers Access Types (cont'd)

8.4.1 Receive Descriptor Descriptions

The AN985B/BX provides receive and transmit descriptors for packet buffering and management.

Descriptors and receive buffers addresses must be longword alignment

Table 19 Receive Descriptor Table

	31				0						
RDES0	Own	Status									
RDES1			Control	Buffer2 byte-count	Buffer1 byte-count						
RDES2	Buffer1 ad	dress (DW	boundary)								
RDES3	Buffer2 ad	Buffer2 address (DW boundary)									

RDES0

RDES0 RDES0		Offset 00 _H				Reset Value xxxx xxxx _H
31 30 29 28 27 26 25 2 OW N	24 23 22 21 20 19 18 17 FL	<u>16 15</u>			7 6 5 4	
rw	rw	rw i	rw rw	rw rw rw rw	rw rw rw rw	ro rw rw rw



Field	Bits	Туре	Description
OWN	31	rw	Own Bit
			 0_B , Host does not move the receiving data out yet 1_B , indicate the new receiving data can be put into this descriptor
FL	30:16	rw	Frame Length, Including CRC This field is valid only in last descriptor
ES	15	rw	Error Summary, OR of the Following Bit This field is valid only in last descriptor. 0: overflow 1: CRC error 6: late collision 7: frame too long 11: runt packet 14: descriptor error
DE	14	rw	Descriptor Error This bit is valid only in last descriptor 1 _B , the current receiving packet is not able to put into the current valid descriptor. This packet is truncated
DT	13:12	rw	Data Type These bits are valid only in last descriptor 00 _B , normal 01 _B , MAC loop-back 10 _B , Transceiver loop-back 11 _B , remote loop-back
RF	11	rw	Runt Frame (packet length < 64 bytes) This bit is valid only in last descriptor.
MF	10	rw	Multicast Frame This bit is valid only in last descriptor.
FS	9	rw	First Descriptor
LS	8	rw	Last Descriptor
TL	7	rw	Too Long Packet (packet length > 1518 bytes) This bit is valid only in last descriptor.
CS	6	rw	Late Collision Set when collision is active after 64 bytes. This bit is valid only in last descriptor.
FT	5	rw	Frame TypeThis bit is valid only in last descriptor. 0_B , 802.3 type 1_B , Ethernet type
RW	4	rw	Receive Watchdog (refer to CSR15, bit 4) This bit is valid only in last descriptor.
Res	3	ro	Reserved
DB	2	rw	Dribble Bit This bit is valid only in last descriptor. ECPacket length is not integer multiple of 8-bit.
CE	1	rw	CRC Error This bit is valid only in last descriptor.



Field	Bits	Туре	Description
OF	0	rw	Overflow
			This bit is valid only in last descriptor.



RDES1

RDES1 RDES1				Offset 04 _H	Reset Value xxxx xxxx _H
31 30 29 28 2 Res	F	25 24 RE RC R H		21 20 19 18 17 16 15 14 13 12 11 10 9 8 RBS2	7 6 5 4 3 2 1 0 RBS1
ro	r	w rw	ro	rw	rw
Field	Bits		Туре	Description	
Res	31:26		ro	Reserved	

1.00	01.20		
RER	25	rw	Receive End of Ring Indicates this descriptor is last, return to base address of descriptor.
RCH	24	rw	Second Address Chain Use for chain structure. Indicates the buffer2 address is the next descriptor address.Ring mode takes precedence over chained mode
Res	23:22	ro	Reserved
RBS2	21:11	rw	Buffer 2 Size DW boundary
RBS1	10:0	rw	Buffer 1 Size DW boundary

RDES2

RDES2	Offset	Reset Value
RDES2	08 _H	xxxx xxxx _H

 		 	 	 -	-	-	-	-	-	-	_	-	0							
								1												

	RBA1																																						
1		1				I	1		1					1			I	rw		I			1		1			1			I		1						L

Field	Bits	Туре	Description
RBA1	31:0	rw	Receive Buffer Address 1
			This buffer address should be double word aligned.

RDES3



RDES3 RDES3	Offset 0Ch _H	Reset Value xxxx xxxx _H
31 30 29 28 27 26 25 24 23 22 21 20 19 18		3 2 1 0
	RBA2	
	rw	· · · · · · · · · · · · · · · · · · ·

Field	Bits	Туре	Description
RBA2	31:0	rw	Receive Buffer Address 2
			This buffer address should be double word aligned.

8.4.2 Transmit Descriptor Descriptions

The AN985B/BX provides receive and transmit descriptors for packet buffering and management.

Descriptor addresses must be longword alignment

Table 20Transmit Descriptor Table

	31			0
TDES0	Own	Status		
TDES1	Control		Buffer2 byte-count	Buffer1 byte-count
TDES2	Buffer1 ad	dress		
TDES3	Buffer2 ad	dress		

TDES0

TDES0	Offset	Reset Value
TDES0	00 _H	xxxx xxxx _H
21 20 20 29 27 26 25 24		7 6 5 4 2 2 1 0

51	30 29 20	21 20	20 24	23 ZZ	21 20	19 10	17 1	0 15	14	13 14	2 11	10	9	0 1	0	5	4	3	2	1	0
OW N		Res		UR		Res		ES	то	Res	LO	NC	LCE	сн	=	C	C	1	Re s	UF	DE
rw		ro		rw		ro		rw	rw	ro	rw	rw	rw r	w rw	1	r	W		ro	rw	rw

Field	Bits	Туре	Description
OWN	31	rw	Own Bit
			$0_{\rm B}$, No transmit data in this descriptor for transmission
			$1_{\rm B}$, Indicate this descriptor is ready to transmit
Res	30:24	ro	Reserved
UR	23:22	rw	Under-run Count
Res	21:16	ro	Reserved





Field	Bits	Туре	Description
ES	15	rw	Error Summary, OR of the Following Bit
			1: under-run error
			8: excessive collision
			9: late collision
			10: no carrier
			11: loss carrier
			14: jabber time-out
ТО	14	rw	Transmit Jabber Time-out
Res	13:12	ro	Reserved
LO	11	rw	Loss Carrier
NC	10	rw	No Carrier
LC	9	rw	Late Collision
EC	8	rw	Excessive Collision
HF	7	rw	Heartbeat Fail
CC	6:3	rw	Collision Count
Res	2	ro	Reserved
UF	1	rw	Under-run Error
DE	0	rw	Deferred

TDES1

TD TD														fset 4 _H	t											-	eset xxx	-	
		29 FS	28 27 Res	26 AC	TE	тс		22 Re s	20	19	18	I	16 BS	T	14	13	12	11	10	9	8	7	T	_5 	1	3	2	1	0
rw	rw	rw	ro	rw	rw	rw	rw	ro	I	I	I	1	rw	I	1	1	I	I			I		1	rw		1	1	I	

Field	Bits	Туре	Description
IC	31	rw	Interrupt Completed
LS	30	rw	Last Descriptor
FS	29	rw	First Descriptor
Res	28:27	ro	Reserved
AC	26	rw	Disable add CRC Function
TER	25	rw	End of Ring
ТСН	24	rw	2nd Address Chain Indicate the buffer2 address is the next descriptor address
DPD	23	rw	Disable Padding Function
Res	22	ro	Reserved
TBS2	21:11	rw	Buffer 2 Size
TBS1	10:0	rw	Buffer 1 Size



TDES2

TDES2 TDES2	Offset 08 _H	Reset Value xxxx xxxx _H
31 30 29 28 27 26 25 24 23 22 21 20 19 18 17	7 16 15 14 13 12 11 10 9 8 7 6 5 4	3 2 1 0
	BA1	
	rw	

Field	Bits	Туре	Description
BA1	31:0	rw	Buffer Address 1
			Without any limitation on the transmission buffer address.

TDES3

TDES3 TDES3	Offset 0Ch _H	Reset Value xxxx xxxx _H
31 30 29 28 27 26 25 24 23 22 21 20 19 18 17	<u>16 15 14 13 12 11 10 9 8 7 6 5 4</u>	3 2 1 0
	BA2	
	rw	

Field	Bits	Туре	Description
BA2	31:0	rw	Buffer Address 2
			Without any limitation on the transmission buffer address.



Electrical Specifications and Timings

9 Electrical Specifications and Timings

9.1 Absolute Maximum Ratings

Table 21 Min-Max Ratings

Parameter	Symbol		Values	S	Unit	Note / Test Condition	
		Min.	Тур.	Max.			
Supply Voltage	V _{cc}	-0.5	-	3.6	V	-	
Input Voltage	V _{CC}	-0.5	-	V _{CC} + 0.5	V		
Output Voltage	V _{CC}	-0.5	-	V _{CC} + 0.5	V		
Storage Temperature	°C	- 65		150	°C		
Ambient Temperature	°C	0		70	°C		
ESD Protection				2000	V		

9.2 DC Specifications

Table 22 General DC Specifications

Parameter	Symbol		Values	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Supply Voltage	V _{CC}	3.0	-	3.6	V	-
Power Supply	I _{CC}	-	_	1	А	-

Table 23 PCI Interface DC Specifications

Parameter	Symbol		Value	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input LOW Voltage	V _{ilp}	-0.5	-	0.325 V _{CC}	V	-
Input HIGH Voltage	V _{ihp}	0.475 V _{CC}	-	V _{CC} + 0.5	V	-
Input Leakage Current	I _{ilp}	-10	-	10	μA	$0 < V_{in} < V_{CC}$
Output LOW Voltage	V _{olp}	-	-	0.1 V _{CC}	V	I _{out} = 700 μA
Output HIGH Voltage	V _{ohp}	0.9 V _{CC}	-	-	V	I _{out} = -150 μA
Input Pin Capacitance	C _{inp}	5	-	17	pF	-
CLK Pin Capacitance	C _{clkp}	10	-	22	pF	-

Table 24 Flash/EEPROM Interface DC Specifications

Parameter	Symbol		Unit	Note / Test Condition		
		Min.	Тур.	Max.		
Input LOW Voltage	V_{ilf}	0	-	0.3 V _{CC}	V	-
Input HIGH Voltage	V_{ihf}	0.7 V _{CC}	-	V _{CC} + 1	V	-
Input Leakage Current	I _{if}	?	-	?	μA	-
Output LOW Voltage	$V_{\sf olf}$	-	-	0.2	V	-



Electrical Specifications and Timings

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Output HIGH Voltage	V _{ohf}	V _{CC} - 0.2	-	-	V	-
Input Pin Capacitance	$C_{\rm inf}$?	-	?	pF	-

Table 24 Flash/EEPROM Interface DC Specifications (cont'd)

9.3 AC Specifications

Table 25 PCI Signaling AC Specifications for 3.3 V

Parameter	Symbol Values			S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Switching Current High	$I_{\rm oh}$ (AC)	_	4	-	mA	-
Switching Current Low	$I_{\rm ol}$ (AC)	_	6	-	mA	-
Slew Rate	-	0.25	-	1	V/ns	-
Unloaded Output Rise Time	T _r	1	-	4	V/ns	0.2 V _{CC} ~ 0.6 V _{CC}
Unloaded Output Fall Time	T _f	1	-	4	V/ns	0.6 V _{CC} ~ 0.2 V _{CC}

9.4 Timing Specifications

Table 26 PCI Clock Specifications

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Clock Cycle Time	T _{cyc}	30	-	-	ns	-
Clock High Time	T _{high}	12	-	-	ns	-
Clock Low Time	T _{low}	12	-	-	ns	-
Clock Slew Rate	-	1	-	4	V/ns	-



Electrical Specifications and Timings

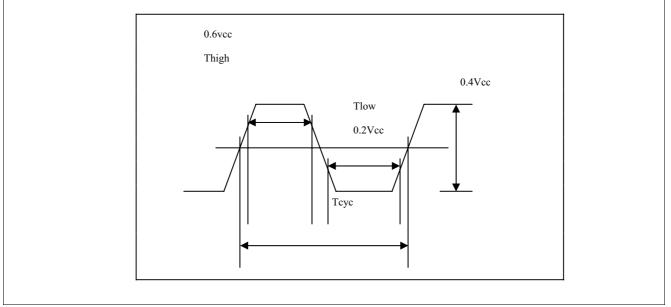


Figure 17 PCI Clock Waveform

Table 27 PCI Timings

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Access time – bused signals	T _{val}	2	-	11	ns	-
Access time – point to point	T _{val} (ptp)	2	-	12	ns	-
Float to Active Delay	T _{on}	2	-	-	ns	-
Active to Float Delay	T _{off}	_	_	28	ns	-
Input Set up Time to Clock – bused signals	T _{su}	7	-	-	ns	-
Input Set up Time to Clock – point to point	T _{su} (ptp)	10, 12	-	-	ns	-
Input Hold Time from Clock	T _h	0	-	-	ns	-
Reset Active Time after Power Stable	T _{rst}	1	-	-	ms	-
Reset Active Time after CLK Stable	T _{rst-clk}	100	-	-	μS	-
Reset Active to Output Float delay	T _{rst-off}	-	-	40	ns	-



Electrical Specifications and Timings

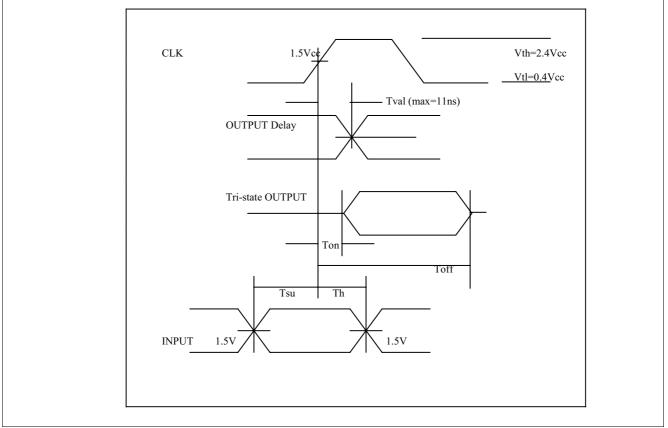


Figure 18 PCI Timings

Table 28 Flash Interface Timings

Parameter	Symbol		Values	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Read cycle time	T _{rc}	90	-	-	ns	-
Chip enable access time	T _{ce}	-	-	90	ns	-
Address access time	T _{aa}	-	-	90	ns	-
Output enable access time	T _{oe}	-	-	45	ns	-
CE low to active output	T _{clz}	0	-	-	ns	-
OE low to active output	T _{olz}	0	-	-	ns	-
CE high to active output	T _{chz}	-	-	45	ns	-
OE high to active output	T _{ohz}	-	-	45	ns	-
Output hold from address change	T _{oh}	0	_	-	ns	-
Write cycle time	T _{wc}	_	-	10	ms	-
Address setup time	T _{as}	0	-	-	ns	-
Address hold time	T _{ah}	50	-	-	ns	-
WE and CE setup time	T _{cs}	0	-	-	ns	-
$\overline{\text{WE}}$ and $\overline{\text{CE}}$ hold time	T _{ch}	0	-	-	ns	-
OE high setup time	T _{oes}	10	-	-	ns	-
OE high hold time	T _{oeh}	10	-	-	ns	-



Electrical Specifications and Timings

Parameter	Symbol		Value	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
CE pulse width	T _{cp}	70	-	-	ns	-
WE pulse width	T _{wp}	70	-	-	ns	-
WE high width	T _{wph}	150	-	-	ns	-
Data setup time	T _{ds}	50	-	-	ns	-
Data hold time	T _{dh}	10	-	_	ns	-
Byte load cycle time	T _{blc}	0.22	-	200	μs	-
Byte load cycle time out	T _{blco}	300	-	-	μs	-



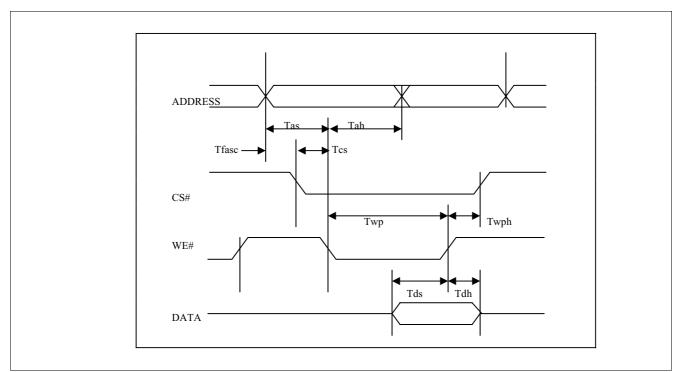


Figure 19 Flash Write Timings



Electrical Specifications and Timings

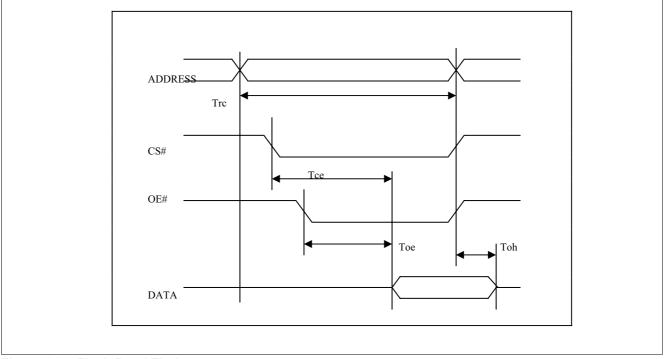


Figure 20 Flash Read Timings

Table 29 EEPROM Interface Timings (AC/AD)

Parameter	Symbol		Values			Note / Test Condition
		Min.	Тур.	Max.		
Serial Clock Frequency	T _{scf}	-	-	0.4M/ 0.1M	Hz	2.7 V < V _{CC} < 5.5 V
Delay from CS High to SK High	T _{ecss}	160/640	-	-	ns	2.7 V < V _{CC} < 5.5 V
Delay from SK Low to CS Low	T _{ecsh}	1120/ 4480	-	-	ns	2.7 V < V _{CC} < 5.5 V
Setup Time of DI to SK	T _{edts}	160/640	-	-	ns	$2.7 \text{ V} < V_{\text{CC}} < 5.5 \text{ V}$
Hold Time of DI after SK	T _{edth}	2320/ 9280	-	-	ns	2.7 V < V _{CC} < 5.5 V
CS Low Time	T _{ecsl}	7400/ 29600	-	-	ns	2.7 V < V _{CC} < 5.5 V



Electrical Specifications and Timings

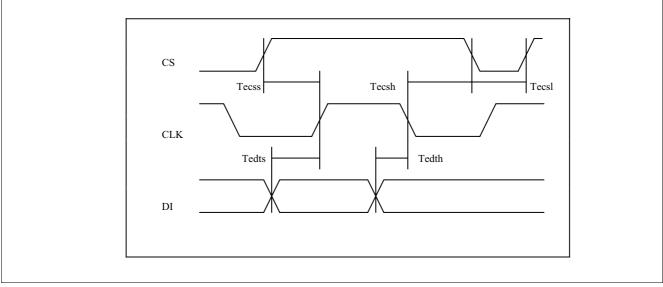


Figure 21 Serial EEPROM Timing



Package Outlines

10 Package Outlines

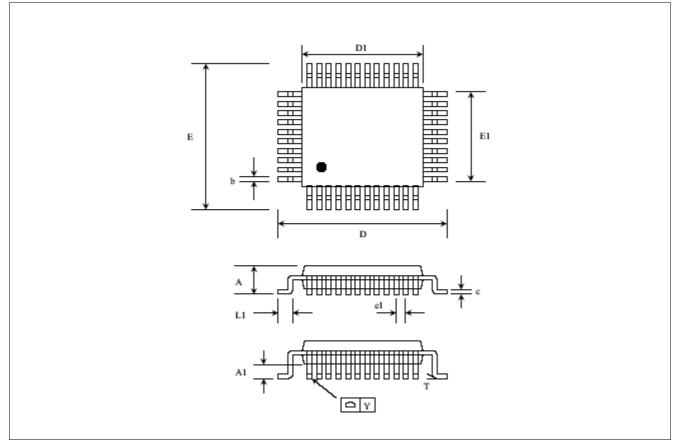


Figure 22 Package Outline for the AN985B/BX

Table 30 Dimensions for 128 -pin LQFP Package (AN985B/BX)

Symbol	Description	Minimum	Maximum
A	Overall Height	-	1.6 mm
A1	Stand Off	0.05 mm	0.15 mm
b	Lead Width	0.17 mm	0.27 mm
С	Lead Thickness	0.13 mm	0.23 mm
D	Terminal Dimension 1	21.9.0 mm	22.1 mm
D1	Package Body 1	19.9 mm	20.1 mm
E	Terminal Dimension 2	15.9 mm	16.1 mm
E1	Package Body 2	13.9 mm	14.1 mm
e1	Lead Pitch	0.50 mm	-
L1	Foot Length	0.45 mm	0.75 mm
Т	Lead Angle	0°	7°
Y	Coplanarity		0.076 mm



Appendix

11 Appendix

11.1 MII Management Access Procedure

Read Management Data From Phyter

- 1. Write CSR9[18]=1 to let Mdio become input mode.
- 2. Write CSR9[16] according to the IEEE802.3u spec to generate the MII management clock.
- 3. Read CSR9[19] with reference the MII management clock.

Write Management Data From Phyter

- 1. Write CSR9[18]=1 to let Mdio become output mode.
- 2. Write CSR9[16] according to the IEEE802.3u spec to generate the MII management clock.
- 3. Write CSR9[19] with reference the MII management clock.

11.2 Debugging Purpose Registers: Offset FCH

MAC(HOME/PNA), MODE/SET FCH[2:0]=100_B

MDC:bra11 TXEN:bra10 TXD[3:0]:bra[9:6] TXER:bra5 MDIO:bra3 RXDV:brd4 CRS:bra2 RXD[2:0]:brd[3:0] COL:bra1 RXER:bra0 RXCLK:brwe_ RXCLK:broe_

PHY MINITOR MODE/SET FCH[2:0]=110_B

bra[16:0]=rxd[3:0], crs, col, rx_clk, rx_dv, rx_er, rx_clk,txd[3:0], tx_er, tx_en, mdi brd[7:6]=mdo, mdc

PHY ONLY MODE/SET FCH[2:0]=001_B

bra[16:9]=rxd[3:0], csr, col,rx_er, rx_dv brd[7:0]=mdc, mdio, tx_er, tx_en, txd[3:0] broez=rx_clk brwez=tx_clk

11.3 EEPROM DATA TABLE



Appendix

Table 31	EEPROM DATA TABLE							
Offset	b15b8	b7b0						
08 _H	PHY ADDR 00							
0A _H	PH	PHY ADDR 01						
0C _H	PH	Y ADDR 10						
16 _H		C_control(offset f8 _H [15:4])						
	[b3~b0]	=CSR15[31:28]						
20 _H	[Device ID						
22 _H	V	Vendor ID						
24 _H	Subsystem ID							
26 _H	Subsystem Vendor ID							
28 _H	MaxLat	MinGnt						
2A _H	L	LAN CISL						
2C _H	L	LAN CISH						
2E _H	CS	CSR18_REG						
30 _H ~3F _H								
40 _H	PWRDATA1HB(LAN D0)	PWRDATA1LB(LAN D321)						
42 _H ~51 _H								
52 _H	CARDBUS CIS word count(<128)							
54 _H ~7F _H								
80 _H ~13F _H								
140 _H ~1FF _H	CARDBUS C	IS DATA(192 Words)						

Table 31 EEPROM DATA TABLE



References

References

- [1]
- [2]
- [3]
- [4]
- [5]
- [6]

www.infineon.com