

# 8314/19H DC Axial Fan

80mm axial fan with high air flow. The DC drive employs an electronically commutated external rotor motor with high efficiency. Drive electronics is completely integrated into the fan hub. The air flow and noise level can be controlled by varying the supply voltage range.



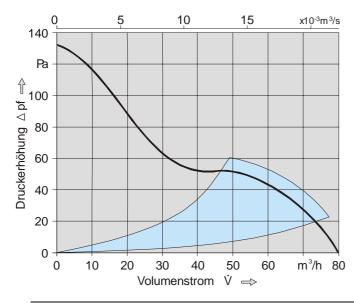
#### **Features**

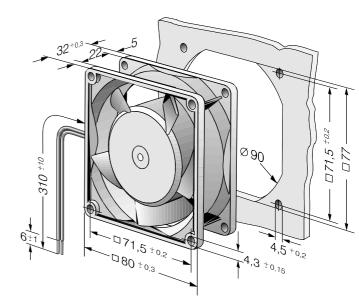
- Electronic protection against locking or overload.
- Electronic reverse polarity protection. Fan starts only with correct polarity.
- Alarm output signal type /19; high on fail; for details please refer to alarm specification attached.
- Electrical connection via 3 leads AWG 22, TR64, 310mm long, stripped and tinned ends (red = +24V; black = GND; yellow = alarm)

Patents granted or applied for.

### **General Data**

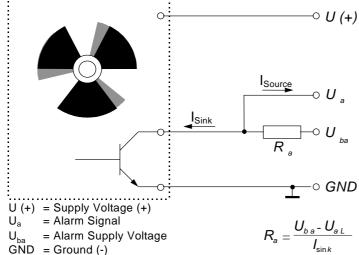
Nominal voltage	V DC	24
Voltage range	V DC	12 26.5
Nominal speed	rpm	5000 (+/- 7,5 %)
Max. flow rate	m³/h	80
Max. flow rate	CFM	47
Noise free air	dB(A)	48
Noise in optimum operating range	bels	6.2
Current consumption	mA	270
Power consumtion	W	6.4
Permanent ambient temperature	°C	-20 +65
at max. voltage		
Service life (65 °C)	h	37.500
Service life (40 °C)	h	70.000
Approvals		UL, VDE, CSA
Fan housing / impeller		PBTP / PA 6.6
Bearing system		Ball bearings
Mass	kg	0,170
All data are mean values at nominal conditions.		Subject to change without notice



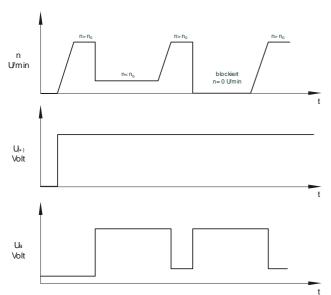




## **Alarm Signal Output:**



Ra = External Pull up-Resistor



### **Alarm Circuit**

latched.

This fan is equipped with an integrated alarm circuit producing a continuous output signal  $U_a$  for monitoring fan speed. At proper operation in the nominal voltage range the alarm output is a "low" level.

When speed decreases below limit speed  $n_G = 1500 \mathrm{rpm}$  (+/-100 rpm), e.g. by high friction torque, locked rotor condition, or low operating voltage, a "high" level output will occur. When speed recovers, the alarm signal goes back to "low", i.e. alarm is non-

### **Technical Data**

Designation	Test condition	Symbol	Value
Alarm output voltage		U <sub>ba</sub> max	60 V DC
Max. sink current		I <sub>sink</sub> max	20 mA
Output voltage "Low" n <n<sub>G</n<sub>	I <sub>sink</sub> = 20 mA	U <sub>a</sub> L	≤ 0,3 V
Output voltage "High" n>n <sub>G</sub>		U <sub>a</sub> H	≤ 60 V
Leakage current	U <sub>a</sub> = 60 V	I <sub>sink</sub>	max. 15µA
n>n <sub>G</sub>			
Alarm delay time	at start up only	t <sub>2</sub>	< 15 s +/- 1s
Signal rise and fall time U <sub>a</sub>		t <sub>r</sub> , t <sub>f</sub>	min.0,5V/µs (Stand TTL)
Alarm trip speed		$n_G$	1500pm
			+/- 100rpm
$t_r \rightarrow \text{Low-High}$ $t_f \rightarrow \text{High-Low}$		Alarm Signa	al suppressed at start-up