

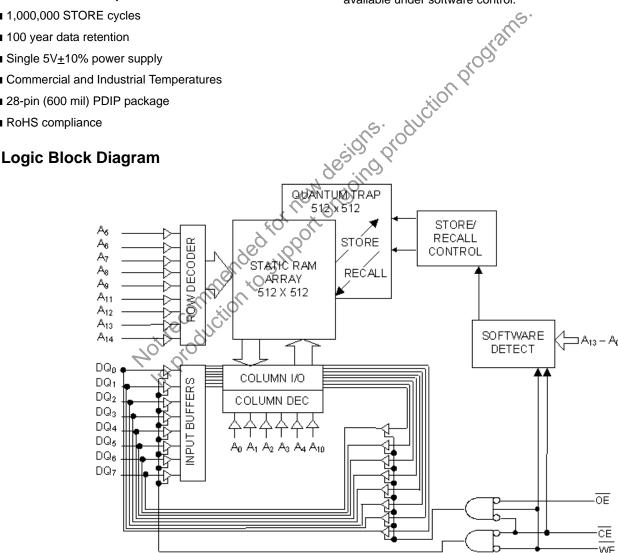
# 256 Kbit (32K x 8) AutoStore+ nvSRAM

#### **Features**

- 25 ns and 45 ns access times
- Directly replaces battery-backed SRAM modules such as Dallas/Maxim DS1230 AB
- Automatic nonvolatile STORE on power loss
- Nonvolatile STORE under Software control
- Automatic RECALL to SRAM on power up
- Unlimited Read/Write endurance
- Unlimited RECALL cycles
- 1,000,000 STORE cycles
- 100 year data retention
- Single 5V±10% power supply
- Commercial and Industrial Temperatures
- 28-pin (600 mil) PDIP package
- RoHS compliance

# **Functional Description**

The Cypress STK16C88 is a 256 Kb fast static RAM with a nonvolatile element in each memory cell. The embedded nonvolatile elements incorporate QuantumTrap technology producing the world's most reliable nonvolatile memory. The SRAM provides unlimited read and write cycles, while independent, nonvolatile data resides in the highly reliable QuantumTrap cell. Data transfers from the SRAM to the nonvolatile elements (the STORE operation) takes place automatically at power down. On power up, data is restored to the SRAM (the RECALL operation) from the nonvolatile memory. Both the STORE and RECALL operations are also available under software control.





#### Contents

Features 1	DC Electrical Characterist
Functional Description 1	Data Retention and Endu
Logic Block Diagram 1	Capacitance
Contents 2	Thermal Resistance
Pin Configurations 3	AC Test Conditions
Device Operation 4	AC Switching Characteris
SRAM Read 4	Switching Waveforms
SRAM Write 4	AutoStore or Power Up R
AutoStore+ Operation 4	Software Controlled STOR
Hardware RECALL (Power Up) 4	Part Numbering Nomencle
Software STORE 4	(Commercial and Industri
Software RECALL 4	Ordering Information
Hardware Protect 5	Package Diagrams
Noise Considerations 5	Sales, Solutions and Lega
Low Average Active Power 5	Worldwide Sales and D
Best Practices 5	Products
Maximum Ratings 7	ijo.
Software STORE	designs proc

DC Electrical Characteristics	. 7
Data Retention and Endurance	. 7
Capacitance	. 8
Thermal Resistance	. 8
AC Test Conditions	. 8
AC Switching Characteristics	. 9
Switching Waveforms	. (
AutoStore or Power Up RECALL	11
Software Controlled STORE/RECALL Cycle	12
Part Numbering Nomenclature	
(Commercial and Industrial)	
Ordering Information	13
Package Diagrams	14
Sales, Solutions and Legal Information	
Worldwide Sales and Design Support	
Products	15



# **Pin Configurations**

Figure 1. Pin Diagram - 28-Pin PDIP

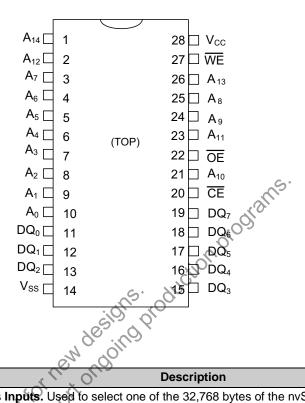


Table 1. Pin Definitions - 28-Pin PDIP

Pin Name	Alt	I/O Type	Description
A <sub>0</sub> -A <sub>14</sub>		Input	Address Inputs. Used to select one of the 32,768 bytes of the nvSRAM.
DQ <sub>0</sub> -DQ <sub>7</sub>		Input or Output	Bidirectional Data I/O lines. Used as input or output lines depending on operation.
WE	W	Input	Write Enable Input, Active LOW. When the chip is enabled and WE is LOW, data on the I/O pins is written to the specific address location.
CE	Ē	Input	Chip Enable Input, Active LOW. When LOW, selects the chip. When HIGH, deselects the chip.
ŌĒ	G	Input	Output Enable, Active LOW. The active LOW OE input enables the data output buffers during read cycles. Deasserting OE HIGH causes the I/O pins to tristate.
V <sub>SS</sub>		Ground	Ground for the Device. The device is connected to ground of the system.
V <sub>CC</sub>		Power Supply	Power Supply Inputs to the Device.



### **Device Operation**

The AutoStore+ STK16C88 is a fast 32K x 8 SRAM that does not lose its data on power down. The data is preserved in integral QuantumTrap nonvolatile storage elements when power is lost. Automatic STORE on power down and automatic RECALL on power up guarantee data integrity without the use of batteries.

#### **SRAM Read**

The STK16C88 performs a READ cycle whenever  $\overline{\text{CE}}$  and  $\overline{\text{OE}}$  are LOW while  $\overline{\text{WE}}$  is HIGH. The address specified on pins  $A_{0-14}$  determines the 32,768 data bytes accessed. When the READ is initiated by an address transition, the outputs are valid after  $\underline{\text{a}}$  delay of  $t_{AA}$  (READ cycle 1). If the READ is initiated by  $\overline{\text{CE}}$  or  $\overline{\text{OE}}$ , the outputs are valid at  $t_{ACE}$  or at  $t_{DOE}$ , whichever is later (READ cycle 2). The data outputs repeatedly respond to address changes within the  $t_{AA}$  access time without the need for transitions on any control input pins, and remains valid until another address change or until  $\overline{\text{CE}}$  or  $\overline{\text{OE}}$  is brought HIGH.

#### **SRAM Write**

A WRITE cycle is performed whenever  $\overline{\text{CE}}$  and  $\overline{\text{WE}}$  are LOW. The address inputs must be stable prior to entering the WRITE cycle and must remain stable until either  $\overline{\text{CE}}$  or  $\overline{\text{WE}}$  goes HIGH at the end of the cycle. The data on the common I/O pins DQ<sub>0-7</sub> are written into the memory if it has valid t<sub>SD</sub>, before the end of a  $\overline{\text{WE}}$  controlled WRITE or before the end of an  $\overline{\text{CE}}$  controlled WRITE. Keep  $\overline{\text{OE}}$  HIGH during the entire WRITE cycle to avoid data bus contention on common I/O lines, If  $\overline{\text{OE}}$  is left  $\underline{\text{LOW}}$ , internal circuitry turns off the output buffers the latter  $\overline{\text{WE}}$  goes LOW.

# **AutoStore+ Operation**

The STK16C88's automatic STORE on power down is completely transparent to the system. The STORE initiation takes less than 500 ns when power is lost ( $V_{\rm CC}$  <  $V_{\rm SWITCH}$ ) at which point the part depends only on its internal capacitor for STORE completion.

If the power supply drops faster than 20  $\mu$ s/volt before Vcc reaches Vswitch, then a 2.2 ohm resistor should be inserted between Vcc and the system supply to avoid a momentary excess of current between Vcc and internal capacitor.

In order to prevent unneeded STORE operations, automatic STOREs are ignored unless at least one WRITE operation has taken place since the most recent STORE or RECALL cycle. Software initiated STORE cycles are performed regardless of whether or not a WRITE operation has taken place.

# Hardware RECALL (Power Up)

During power up or after any low power condition ( $V_{CC}$ < $V_{RESET}$ ), an internal RECALL request is latched. When  $V_{CC}$  once again exceeds the sense voltage of  $V_{SWITCH}$ , a RECALL cycle is automatically initiated and takes  $t_{HRECALL}$  to complete.

If the STK16C88 is in a WRITE state at the end of power up RECALL, the SRAM data is corrupted. To help avoid this situation, a 10 Kohm resistor is connected either between WE and system  $V_{CC}$  or between  $\overline{CE}$  and system  $V_{CC}$ .

#### Software STORE

Data is transferred from the SRAM to the nonvolatile memory by a software address sequence. The STK16<u>C88</u> software STORE cycle is initiated by executing sequential <u>CE</u> controlled READ cycles from six specific address locations in exact order. During the STORE cycle, an erase of the previous nonvolatile data is first performed followed by a program of the nonvolatile elements. When a STORE cycle is initiated, input and output are disabled until the cycle is completed.

Because a sequence of READs from specific addresses is used for STORE initiation, it is important that no other READ or WRITE accesses intervene in the sequence. If they intervene, the sequence is aborted and no STORE or RECALL takes place.

To initiate the software STORE cycle, the following READ sequence is performed:

- 1. Read address 0x0E38, Valid READ
- 2. Read address 0x31C7, Valid READ
- 3. Read address 0x03E0, Valid READ
- Read address 0x3C1F, Valid READ
- Read address 0x303F, Valid READ
- 6. Read address 0x0FC0, Initiate STORE cycle

The software sequence is clocked with  $\overline{\text{CE}}$  controlled READs. When the sixth address in the sequence is entered, the STORE cycle commences and the chip is disabled. It is important that READ cycles and not WRITE cycles are used in the sequence. It is not necessary that  $\overline{\text{OE}}$  is LOW for a valid sequence. After the  $t_{\text{STORE}}$  cycle time is fulfilled, the SRAM is again activated for READ and WRITE operation.

#### Software RECALL

Data is transferred from the nonvolatile memory to the SRAM by a software address sequence. A software RECALL cycle is initiated with a sequence of READ operations in a manner similar to the software STORE initiation. To initiate the RECALL cycle, the following sequence of CE controlled READ operations is performed:

- 1. Read address 0x0E38, Valid READ
- 2. Read address 0x31C7, Valid READ
- 3. Read address 0x03E0, Valid READ
- 4. Read address 0x3C1F, Valid READ
- 5. Read address 0x303F, Valid READ
- 6. Read address 0x0C63, Initiate RECALL cycle

Internally, RECALL is a two step procedure. First, the SRAM data is cleared, and then the nonvolatile information is transferred into the SRAM cells. After the t<sub>RECALL</sub> cycle time, the SRAM is once again ready for READ and WRITE operations. The RECALL operation does not alter the data in the nonvolatile elements. The nonvolatile data can be recalled an unlimited number of times.



#### Hardware Protect

The STK16C88 offers hardware protection against inadvertent STORE operation and SRAM WRITEs during low voltage conditions. When  $V_{CAP} < V_{SWITCH}$ , all externally initiated STORE operations and SRAM WRITEs are inhibited.

#### Noise Considerations

The STK16C88 is a high speed memory. It must have a high frequency bypass capacitor of approximately 0.1 µF connected between V<sub>CC</sub> and V<sub>SS</sub>, using leads and traces that are as short as possible. As with all high speed CMOS ICs, careful routing of power, ground, and signals reduce circuit noise.

# Low Average Active Power

CMOS technology provides the STK16C88 the benefit of drawing significantly less current when it is cycled at times longer than 50 ns. Figure 2 and Figure 3 shows the relationship between I<sub>CC</sub> and READ or WRITE cycle time. Worst case current consumption is shown for both CMOS and TTL input levels (commercial temperature range, VCC = 5.5V, 100% duty cycle on chip enable). Only standby current is drawn when the chip is disabled. The overall average current drawn by the STK16C88 depends on the following items:

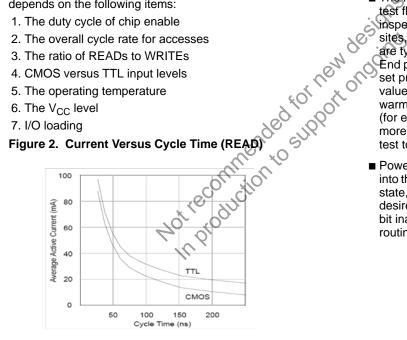
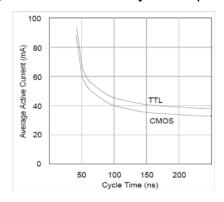


Figure 3. Current Versus Cycle Time (WRITE)



# **Best Practices**

nvSRAM products have been used effectively for over 15 years. While ease-of-use is one of the product's main system values, experience gained working with hundreds of applications has resulted in the following suggestions as best practices:

- The nonvolatile cells in an nvSRAM are programmed on the test floor during final test and quality assurance. Incoming inspection routines at customer or contract manufacturer's sites, sometimes, reprogram these values. Final NV patterns are typically repeating patterns of AA, 55, 00, FF, A5, or 5A. End product's firmware should not assume an NV array is in a set programmed state. Routines that check memory content values to determine first time system configuration and cold or warm boot status should always program a unique NV pattern (for example, complex 4-byte pattern of 46 E6 49 53 hex or more random bytes) as part of the final system manufacturing test to ensure these system routines work consistently.
- Power up boot firmware routines should rewrite the nvSRAM into the desired state. While the nvSRAM is shipped in a preset state, best practice is to again rewrite the nvSRAM into the desired state as a safeguard against events that might flip the bit inadvertently (program bugs or incoming inspection routines).



Table 2. Software STORE/RECALL Mode Selection

CE	WE	A <sub>13</sub> – A <sub>0</sub>	Mode	I/O	Notes
L	Н	0x0E38 0x31C7 0x03E0 0x3C1F 0x303F 0x0FC0	Read SRAM Read SRAM Read SRAM Read SRAM Read SRAM Nonvolatile STORE	Output Data	[1, 2]
L	Н	0x0E38 0x31C7 0x03E0 0x3C1F 0x303F 0x0C63	Read SRAM Read SRAM Read SRAM Read SRAM Read SRAM Nonvolatile RECALL	Output Data	[1, 2]

Jut, Out.

Not. recommended for new designs production programs.

Not. recommended for new designs production production production to support ongoing production production to support ongoing production production to support ongoing production productio

#### Notes

<sup>1.</sup> The six consecutive addresses must be in the order listed. WE must be high during all six consecutive CE controlled cycles to enable a nonvolatile cycle.

2. While there are 15 addresses on the STK16C88, only the lower 14 are used to control software modes.



# **Maximum Ratings**

Exceeding maximum ratings may shorten the useful life of the device. These user guidelines are not tested.

Storage Temperature ......-65°C to +150°C Temperature under bias......-55°C to +125°C Supply Voltage on  $V_{CC}$  Relative to GND .....-0.5V to 7.0V Voltage on Input Relative to Vss.....-0.6V to  $V_{CC}$  + 0.5V

Voltage on DQ <sub>0-7</sub> 0.5	V to Vcc + 0.5V
Power Dissipation	1.0W
DC output Current (1 output at a time, 1s du	ration) 15 mA
Operating Range	

Range	ge Ambient Temperature	
Commercial	0°C to +70°C	4.5V to 5.5V
Industrial	-40°C to +85°C	4.5V to 5.5V

#### **DC Electrical Characteristics**

Over the operating range ( $V_{CC} = 4.5V$  to 5.5V)

Parameter	Description	Test Conditions		Min	Max	Unit
I <sub>CC1</sub>	Average V <sub>CC</sub> Current	t <sub>RC</sub> = 45 ns Dependent on output loading and cycle rate. Values obtained without output loads.	Commercial Industrial	)*	97 70 100 70	mA mA mA
I <sub>CC2</sub>	Average V <sub>CC</sub> Current during STORE	I <sub>OUT</sub> = 0 mA.  All Inputs Do Not Care, V <sub>CC</sub> = Max  Average current for duration t <sub>STORE</sub>	on pros		3	mA
I <sub>CC3</sub>	Average V <sub>CC</sub> Current at t <sub>RC</sub> = 200 ns, 5V, 25°C Typical	$\overline{\text{WE}} \ge (\text{V}_{\text{CC}} - 0.2\text{V})$ . All other inputs cycling. Dependent on output loading and cycle rate. Val without output loads.	ues obtained		10	mA
I <sub>SB1</sub> <sup>[3]</sup>	Average V <sub>CC</sub> Current (Standby, Cycling	$t_{RC}$ =25ns, $\overline{CE} \ge V_{IH}$ $t_{RC}$ =45ns, $\overline{CE} \ge V_{IH}$	Commercial		30 22	mA
	[3] Average $V_{CC}$ Current (Standby, Cycling TTL Input Levels) $t_{RC}=25 \text{ns}, \overline{CE} \ge V_{IH}$ [3] $V_{CC} = 25 \text{ns}, \overline{CE} \ge V_{IH}$ [4] $V_{CC} = 25 \text{ns}, \overline{CE} \ge V_{IH}$	Industrial		31 23	mA	
I <sub>SB2</sub> <sup>[3]</sup>	V <sub>CC</sub> Standby Current (Standby, Stable CMOS Input Levels)	OL 2 (VCC - 0.20). All dires VIN < 0.20 01 2 (VI	<sub>CC</sub> – 0.2V).		1.5	mA
I <sub>IX</sub>	Input Leakage Current	$V_{CC} = Max$ , $V_{SS} \le V_{IN} \le V_{CC}$		-1	+1	μА
I <sub>OZ</sub>	Off State Output Leakage Current	$V_{CC} = Max$ , $V_{SS} \le V_{IN} \le V_{CC}$ , $\overline{CE}$ or $\overline{OE} \ge V_{IH}$ or	WE ≤ V <sub>IL</sub>	-5	+5	μΑ
V <sub>IH</sub>	Input HIGH Voltage	Olive		2.2	V <sub>CC</sub> + 0.5	V
V <sub>IL</sub>	Input LOW Voltage	\$		V <sub>SS</sub> – 0.5	0.8	V
V <sub>OH</sub>	Output HIGH Voltage	I <sub>OUT</sub> = -4 mA		2.4		V
V <sub>OL</sub>	Output LOW Voltage	I <sub>OUT</sub> = 8 mA			0.4	V

#### **Data Retention and Endurance**

Parameter Description		Min	Unit
DATA <sub>R</sub>	Data Retention	100	Years
$NV_C$	Nonvolatile STORE Operations	1,000	К

Document Number: 001-50595 Rev. \*B Page 7 of 15



### Capacitance

In the following table, the capacitance parameters are listed.<sup>[4]</sup>

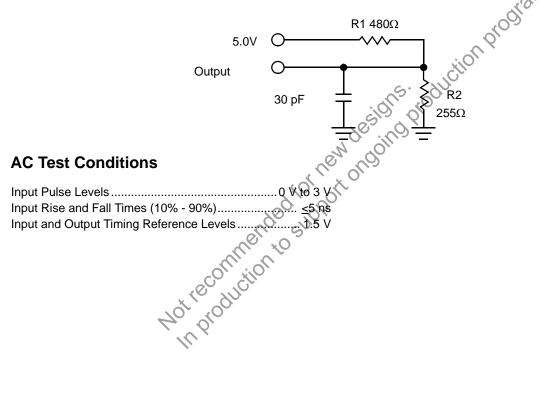
Parameter	Description	Test Conditions	Max	Unit
C <sub>IN</sub>	Input Capacitance	$T_A = 25$ °C, $f = 1$ MHz,	5	pF
C <sub>OUT</sub>	Output Capacitance	$V_{CC} = 0 \text{ to } 3.0 \text{ V}$	7	pF

# **Thermal Resistance**

In the following table, the thermal resistance parameters are listed.<sup>[4]</sup>

Parameter	Description	Test Conditions	28-PDIP	Unit
$\Theta_{JA}$	Thermal Resistance (Junction to Ambient)	Test conditions follow standard test methods and procedures for measuring thermal impedance, per EIA /	TBD	°C/W
$\Theta_{\sf JC}$	Thermal Resistance (Junction to Case)	JESD51.	TBD	°C/W





### Note

<sup>4.</sup> These parameters are guaranteed by design and are not tested.

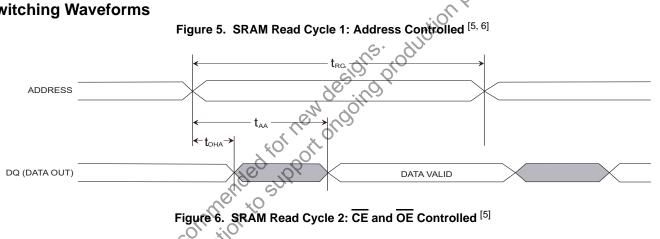


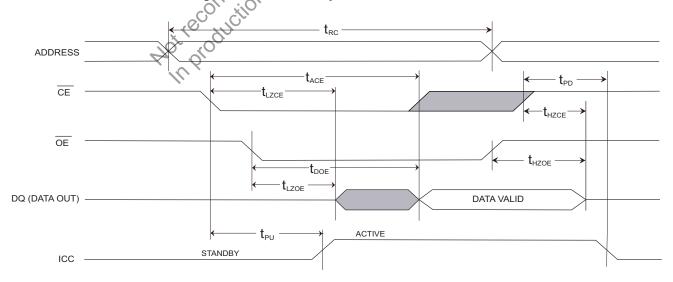
# **AC Switching Characteristics**

Table 3. SRAM Read Cycle

Pa	rameter		25	ns	45 ns		
Cypress Parameter	Alt	Description	Min	Max	Min	Max	Unit
t <sub>ACE</sub>	t <sub>ELQV</sub>	Chip Enable Access Time		25		45	ns
t <sub>RC</sub> [5]	t <sub>AVAV</sub> , t <sub>ELEH</sub>	Read Cycle Time	25		45		ns
t <sub>AA</sub> <sup>[6]</sup>	t <sub>AVQV</sub>	Address Access Time		25		45	ns
t <sub>DOE</sub>	t <sub>GLQV</sub>	Output Enable to Data Valid		10		20	ns
t <sub>OHA</sub> <sup>[6]</sup>	t <sub>AXQX</sub>	Output Hold After Address Change	5		5		ns
t <sub>LZCE</sub> [7]	t <sub>ELQX</sub>	Chip Enable to Output Active	5		5		ns
t <sub>HZCE</sub> [7]	t <sub>EHQZ</sub>	Chip Disable to Output Inactive		10		15	ns
t <sub>LZOE</sub> [7]	t <sub>GLQX</sub>	Output Enable to Output Active	0	G.	0		ns
t <sub>HZOE</sub> [7]	t <sub>GHQZ</sub>	Output Disable to Output Inactive		10		15	ns
t <sub>PU</sub> [4]	t <sub>ELICCH</sub>	Chip Enable to Power Active	0	1.0.	0		ns
t <sub>PD</sub> [4]	t <sub>EHICCL</sub>	Chip Disable to Power Standby	-40	25		45	ns

# **Switching Waveforms**





#### Note<u>s</u>

- 5. WE must be HIGH during SRAM Read Cycles and LOW during SRAM WRITE cycles.
  6. I/O state assumes CE and OE ≤ V<sub>IL</sub> and WE ≥ V<sub>IH</sub>; device is continuously selected.
  7. Measured ±200 mV from steady state output voltage.

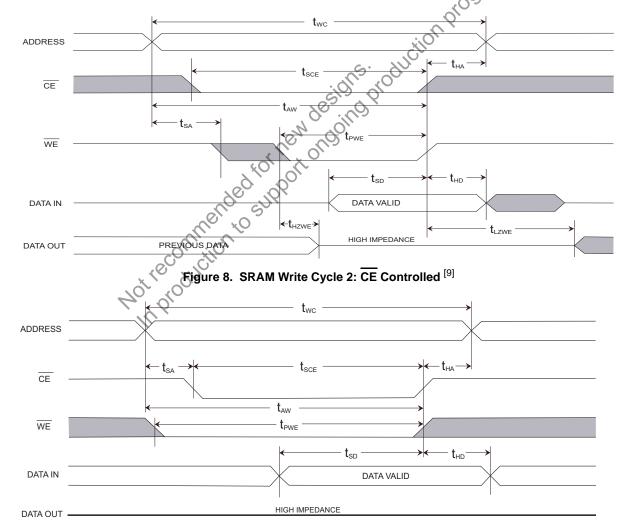


Table 4. SRAM Write Cycle

F	Parameter		25	ns	45 ns		
Cypress Parameter	Alt	Description	Min	Max	Min	Max	Unit
t <sub>WC</sub>	t <sub>AVAV</sub>	Write Cycle Time	25		45		ns
t <sub>PWE</sub>	t <sub>WLWH</sub> , t <sub>WLEH</sub>	Write Pulse Width	20		30		ns
t <sub>SCE</sub>	t <sub>ELWH</sub> , t <sub>ELEH</sub>	Chip Enable To End of Write	20		30		ns
t <sub>SD</sub>	t <sub>DVWH</sub> , t <sub>DVEH</sub>	Data Setup to End of Write	10		15		ns
t <sub>HD</sub>	t <sub>WHDX</sub> , t <sub>EHDX</sub>	Data Hold After End of Write	0		0		ns
t <sub>AW</sub>	t <sub>AVWH</sub> , t <sub>AVEH</sub>	Address Setup to End of Write	20		30		ns
t <sub>SA</sub>	t <sub>AVWL</sub> , t <sub>AVEL</sub>	Address Setup to Start of Write	0		0		ns
t <sub>HA</sub>	t <sub>WHAX</sub> , t <sub>EHAX</sub>	Address Hold After End of Write	0		0		ns
t <sub>HZWE</sub> [7,8]	t <sub>WLQZ</sub>	Write Enable to Output Disable		10		15	ns
t <sub>LZWE</sub> [7]	t <sub>WHQX</sub>	Output Active After End of Write	5	·0.	5		ns

**Switching Waveforms** 

Figure 7. SRAM Write Cycle 1:  $\overline{\text{WE}}$  Controlled [9]



Notes
8. If WE is Low when CE goes Low, the outputs remain in the high impedance state.

<sup>9.</sup>  $\overline{\text{CE}}$  or  $\overline{\text{WE}}$  must be greater than  $V_{\text{IH}}$  during address transitions.

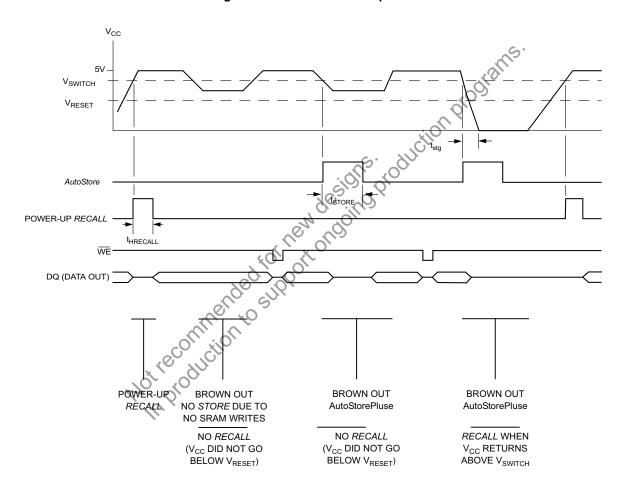


**AutoStore or Power Up RECALL** 

Parameter	Alt	Description	STK1	Unit	
		Description	Min	Max	Offic
t <sub>HRECALL</sub> [10]	t <sub>RESTORE</sub>	Power up RECALL Duration		550	μS
t <sub>STORE</sub>	t <sub>HLHZ</sub>	STORE Cycle Duration		10	ms
t <sub>stg</sub> <sup>[4, 6]</sup>		Power-down AutoStore Slew Time to Ground	500		ns
V <sub>RESET</sub>		Low Voltage Reset Level		3.6	V
V <sub>SWITCH</sub>		Low Voltage Trigger Level	4.0	4.5	V

# **Switching Waveforms**

Figure 9. AutoStore/Power Up RECALL



Note

<sup>10.</sup>  $t_{\mbox{\scriptsize HRECALL}}$  starts from the time  $V_{\mbox{\scriptsize CC}}$  rises above  $V_{\mbox{\scriptsize SWITCH}}.$ 



# **Software Controlled STORE/RECALL Cycle**

The software controlled STORE/RECALL cycle follows. [11, 12]

Parameter	Alt	Description	25 ns		45 ns		Unit
			Min	Max	Min	Max	Unit
t <sub>RC</sub>	t <sub>AVAV</sub>	STORE/RECALL Initiation Cycle Time	25		45		ns
t <sub>SA</sub> <sup>[11]</sup>	t <sub>AVEL</sub>	Address Setup Time	0		0		ns
t <sub>CW</sub> <sup>[11]</sup>	t <sub>ELEH</sub>	Clock Pulse Width	20		30		ns
t <sub>HACE</sub> <sup>[7, 11]</sup>	t <sub>ELAX</sub>	Address Hold Time	20		20		ns
t <sub>RECALL</sub>		RECALL Duration		20		20	μS

# **Switching Waveforms**

Figure 10.  $\overline{\text{CE}}$  Controlled Software STORE/RECALL Cycle [12]  $t_{RC}$ DATA VALID THE CONTROL OF THE CONTRO ADDRESS CE OE t<sub>STORE</sub> / t<sub>RECALL</sub> HIGH IMPEDANCE DATA VALID DQ (DATA)

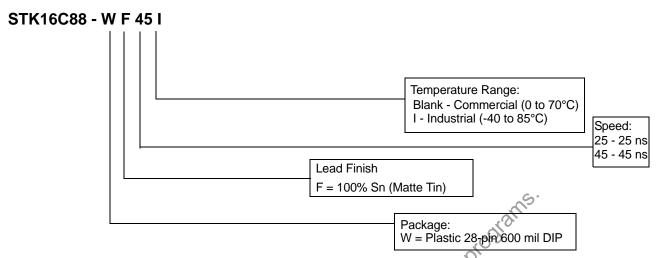
#### Notes

<sup>11.</sup> The software sequence is clocked on the falling edge of  $\overline{\text{CE}}$  without involving  $\overline{\text{OE}}$  (double clocking aborts the sequence).

12. The six consecutive addresses must be read in the order listed in the Mode Selection table.  $\overline{\text{WE}}$  must be HIGH during all six consecutive cycles.



# Part Numbering Nomenclature (Commercial and Industrial)



# **Ordering Information**

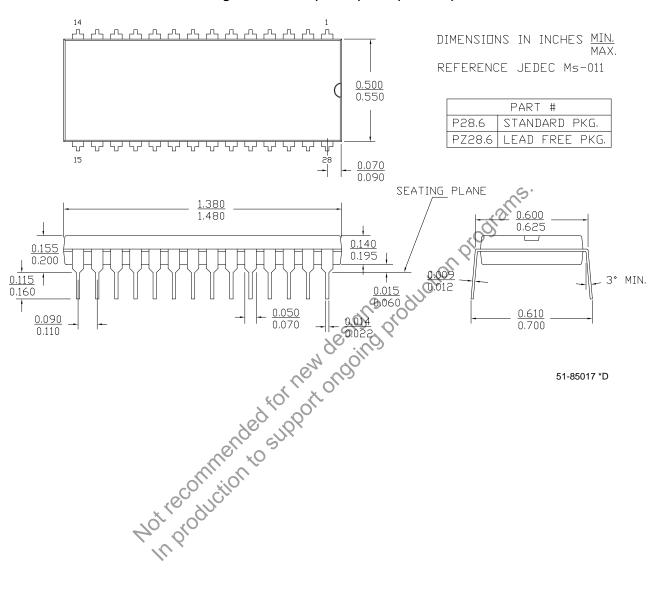
These parts are not recommended for new designs. They are in production to support ongoing production programs only.

Speed (ns)	Ordering Code	Package Diagram	Package Type	Operating Range
25	STK16C88-WF25I	51-85017	28-pin PDIP	Industrial
45	STK16C88-WF45	51-85017	28-pin PDIP	Commercial
	Not recomb	nendeo suppe ction to suppe		



# **Package Diagram**

Figure 11. 28-Pin (600 Mil) PDIP (51-85017)





### **Document History Page**

Documer Documer	t Title: STK10 t Number: 00	6C88 256 Kbit (3 11-50595	32K x 8) AutoSt	core+ nvSRAM	
Rev.	ECN No.	Orig. of Change	Submission Date	Description of Change	
**	2625096	GVCH/PYRS	12/19/08	New data sheet	
*A	2826441	GVCH	12/11/2009	Added following text in the Ordering Information section: "These are not recommended for new designs. In production to support on production programs only."  Added watermark in PDF stating "Not recommended for new des In production to support ongoing production programs only."  Added Contents on page 2.	
*B	3052511	GVCH	10/08/10	Removed the following inactive parts: STK16C88-WF25, STK16C88-WF45I Updated package diagram	
Sales, S	olutions a	nd Legal In	formation	waln's	
Worldwide	Sales and	Design Suppo	ort	<sup>₹</sup> 00).	
	intains a world	lwide network of	offices solution	centers, manufacturer's representatives, and distributors. To find the office	
	ou, visit us at o	cypress.com/sale	es.	solitore, managada o reproductivos, and distributors. To find the office	
Products				S. 100	
PSoC			psoc.cypress.co	om idis idis	
Clocks & Bu	ffers	С	locks.cypress.co	om Service Control of the Control of	
Wireless		wire	eless.cypress.co	om 40° cilles	
Memories		me	mory.cypress.co		
lmage Sens	ors	ir	nage.cypress.co	m X	
USB		pso	c.cypress.com/u	s <sub>O</sub>	
		Hotrecon	mender sur	centers, manufacturer's representatives, and distributors. To find the office of the control of	

© Cypress Semiconductor Corporation, 2008-2010. The information contained herein is subject to change without notice. Cypress Semiconductor Corporation assumes no responsibility for the use of any circuitry other than circuitry embodied in a Cypress product. Nor does it convey or imply any license under patent or other rights. Cypress products are not warranted nor intended to be used for médical, lifé support, life saving, critical control or safety applications, unless pursuant to an express written agreement with Cypress. Furthermore, Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress products in life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

Any Source Code (software and/or firmware) is owned by Cypress Semiconductor Corporation (Cypress) and is protected by and subject to worldwide patent protection (United States and foreign), United States copyright laws and international treaty provisions. Cypress hereby grants to licensee a personal, non-exclusive, non-transferable license to copy, use, modify, create derivative works of, and compile the Cypress Source Code and derivative works for the sole purpose of creating custom software and or firmware in support of licensee product to be used only in conjunction with a Cypress integrated circuit as specified in the applicable agreement. Any reproduction, modification, translation, compilation, or representation of this Source Code except as specified above is prohibited without the express written permission of Cypress.

Disclaimer: CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. Cypress reserves the right to make changes without further notice to the materials described herein. Cypress does not assume any liability arising out of the application or use of any product or circuit described herein. Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress' product in a life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

Use may be limited by and subject to the applicable Cypress software license agreement.

Document Number: 001-50595 Rev. \*B Revised October 8, 2010 Page 15 of 15

All products and company names mentioned in this document may be the trademarks of their respective holders